Modern Information Retrieval

Chapter 5 Text Classification

Introduction

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Feature Selection or Dimensionality Reduction

Evaluation Metrics

Trends and research issues

Introduction

- Since ancient times, librarians had to deal with the issue of storing documents for later retrieval and reading
- As time passed, the size of the collection grew and the problem hardened
- To minorate the problem, librarians started labeling the documents
- A very first approach for labeling documents is to assign a single identifier to each document

Introduction

- However, this not solve the more generic problem of finding documents on a specific subject or topic
- In this case, the natural solution is to
 - group documents by common topics, and
 - name these groups with meaningful labels
- Each labeled group is call a class, that is a set of documents that can be described by the group label
- The process of inserting the documents into the classes is commonly referred to as text classification

The Need to Organize Information

- Every day we receive documents through postal mail that we feel compelled to store for later reference
 - These are utility bills, bank account reports, tax filings
- As the volume of itens increases, there is a natural need to organize them somehow
- For this, we usually separate the itens into files, label them in a meaningful way, and store them in a cabinet
- The process of separating documents into files is a text classification procedure

The Need to Organize Information

- Text classification provides a means to organize information which allows better understanding and interpretation of the data
- To illustrate, consider a large company that produce thousands of documents related to its business
- These documents constitute a valuable asset to support the business decision making process
- To organize the corporate information we need a knowledge organization system
- Such systems allow defining
 - a set of classes, organizing them hierarchically
 - classifying the documents of the collection into these classes automatically



A Characterization of Algorithms

- A classification algorithm can be fundamentally of two types, as we now discuss:
 - unsupervised
 - supervised

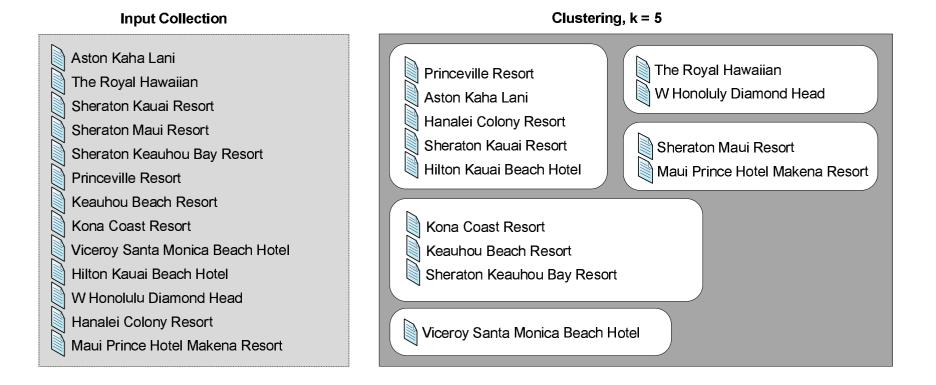
A Characterization of Algorithms Unsupervised Algorithms

- Unsupervised algorithm: no examples of documents that belong to each class is given as input
- Consider, for instance, that the only input data are the documents in the collection
- In this case, the task of the classifier is to separate the documents in groups in fully automatic fashion
- This procedure is frequently referred to as clustering

- A second form of algorithm is to specify the classes without any information on training examples
- The classifier matches the text of the documents to the class labels to guide the classification process
- The classifier can use a ranking function to define rewards and penalties on the classification of a doc
- However, matching of text documents to the few terms in a class label might yield poor results

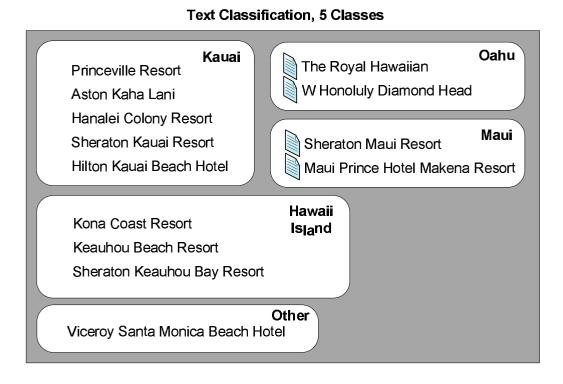
- Unsupervised classification is useful, for instance, to gain initial insight into the data
- It might also be used to gain insight on the number of classes of a set of docs
- In its most general form, the unsupervised text classification problem can be defined as follows
 - lacksquare Given a collection of N documents, separate them automatically into clusters
 - Following, generate labels for each cluster in fully automatic fashion

Unsupervised text classification applied to Web pages of hotels in Hawaii: clustering



- Unsupervised text classification applied to Web pages of hotels in Hawaii: assignment of classes to hotels
- Each class is composed of hotels located in a same island

Aston Kaha Lani The Royal Hawaiian Sheraton Kauai Resort Sheraton Maui Resort Sheraton Keauhou Bay Resort Princeville Resort Keauhou Beach Resort Kona Coast Resort Viceroy Santa Monica Beach Hotel Hilton Kauai Beach Hotel W Honolulu Diamond Head Hanalei Colony Resort Maui Prince Hotel Makena Resort



- While this clustering is naturally appealing to humans, it is difficult to be generated by an automatic procedure
- The reason is that the hotel Web pages contain many terms in common
- Without human understanding, it is very hard to establish that terms describe the hotel locations
- Thus, most likely, an automatic clustering algorithm will not generate the clusters shown

- Even if the right clusters had been produced, we would still have to label these clusters
- Labels generated automatically tend to be very distinct from labels specified by humans
- Thus, solving the whole classification problem with no provision of any form of human knowledge is hard
- This continues to be an excessively complex task, particularly because of the labelling of the clusters
- Unsupervised classification is more effective when class labels have been provided

A Characterization of Algorithms Supervised Algorithms

- An algorithm is said to be supervised when it uses human provided information as input data
- In the standard case, a set of classes and examples of documents for each class are provided
- The examples are determined by human specialists and constitute what we call the training set
- This training set is used to learn a classification function
- Once this function has been learnt, it is used to classify new unseen documents

Training Examples

- For instance, one can specify 4 classes with an average number of 100 documents in each of them
- These documents are known to belong to the classes, as determined by human experts
- The classifier can then determine, for instance, the terms that occur most frequently in each class
- These terms can be used to produce an initial description of that class
- An analogous process can be repeated in the case the examples are provided for clusters

Training Examples

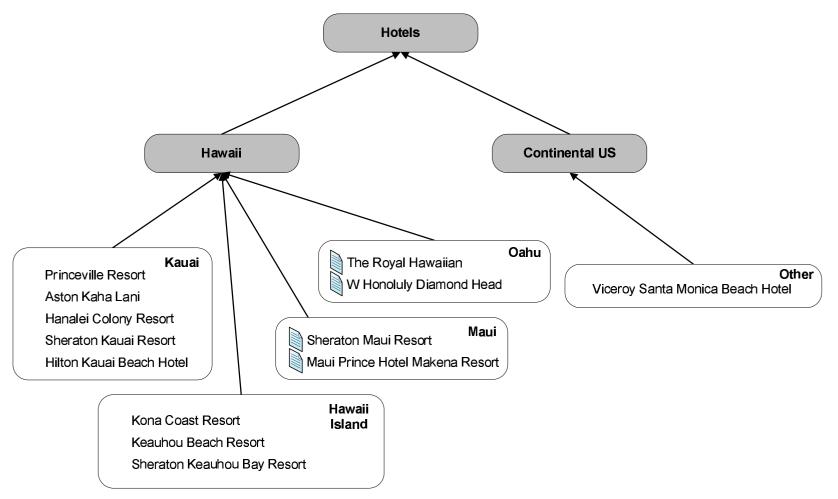
- Larger the number of training examples, usually better is the fine tunning of the classifier
- Once the fine tunning is completed, the classifier can be applied to an unseen set of objects
- This set objects is usually referred to as the test set

A Characterization of Algorithms Organizing the Classes – Taxonomies

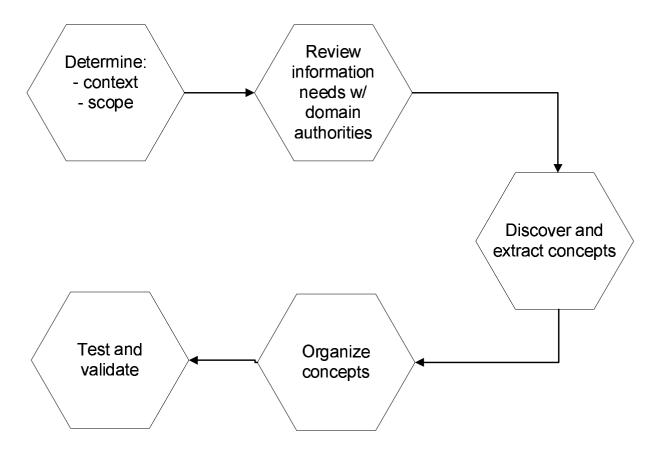
- Labeling provides information on the semantics of each class
- However, no organization of the classes is provided
- Lack of organization of the classes imposes restrictions to comprehension and reasoning
- Among all sorts of organization, the most appealing one is the hierarchical organization
- Hierarchies allow us to reason in terms of more generic concepts
- They also provide for specialization which allows breaking up a larger set of entities into subsets

- We can organize the classes hierarchically using specialization, generalization, and sibling relations
- Classes organized hierarchically in this fashion compose a taxonomy
- In this case, the relations among the classes can be used to further fine tune the classifier
- Taxonomies make more sense when built for a specific domain of knowledge

Organization of Web pages of hotels in Hawaii in a geo-referenced taxonomy



- Usually, taxonomies are built manually or semi-automatically using complex procedures
- The process of building a taxonomy:



- Manual taxonomies tend to be of superior quality, and better reflect the information needs of the users
- The automatic construction of taxonomies is one area of technology that needs more research and development
- Once a taxonomy has been built, the documents of the collection can be classified according to its concepts
- This can be accomplished manually or automatically
- Automatic classification algorithms are advanced enough to work well in practice

- The text classification problem, in its more general form, can be stated as follows
 - Given (i) a collection \mathcal{D} of documents, and (ii) a set \mathcal{C} of classes with their respective labels,
 - Determine a classification method to automatically assign documents to one or more classes
- The method itself is frequently referred to as the classifier

- Fundamental intuition: the words in a document should be matched against the labels of each class
- This matching function can take many different forms, but always guides the classification procedure
- The problem can be made more sophisticated by adding two extra components to the input
 - First, the classes might be organized hierarchically composing a taxonomy
 - Second, for each class we might have a number of example documents pre-classified by humans (training set)

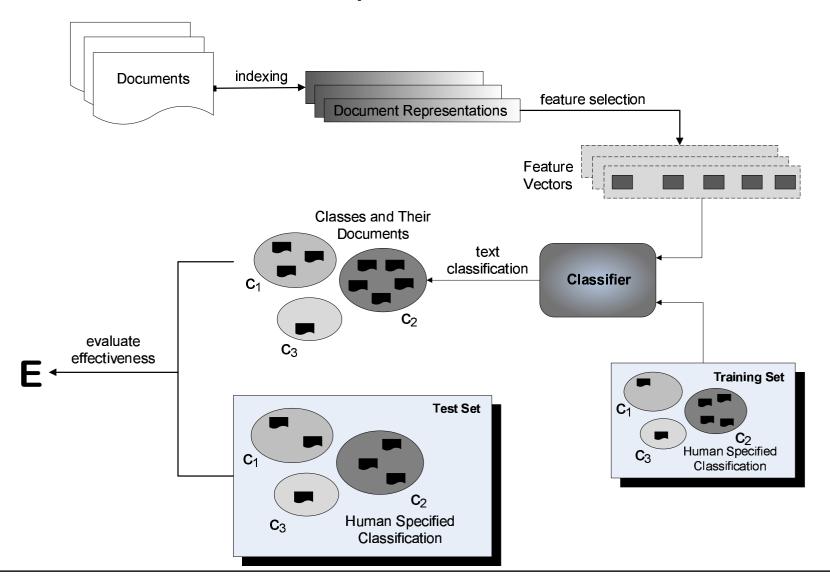
- In a more restrict sense, the problem can be defined as follows
 - Given (i) a collection \mathcal{D} of documents, and (ii) a set $\mathcal{C} = \{c_1, c_2, \dots, c_L\}$ of L classes with their respective labels,
 - A text classifier is a binary function $\mathcal{F}: \mathcal{D} \times \mathcal{C} \rightarrow \{0,1\}$
- That is, \mathcal{F} is a function that assigns a value of 0 or 1 to each pair $[d_j, c_p]$, such that $d_j \in \mathcal{D}$ and $c_p \in \mathcal{C}$
- If the value assigned is 1, we say that the document d_j is a member of class c_p
- If the value assigned is 0, we say that the document d_j is not a member of class c_p

- If no restrictions are posed to the classifier, two or more classes might be assigned to a single document
- In this case, we say that the classifier is of type multi-label
- A different problem results if we restrict the classifier to assigning a single class to each document
- In this case, we say that the classifier is of type single-label

- The above definition of our classification function \mathcal{F} is binary
- However, the function \mathcal{F} might be built to compute a degree of membership of document d_j in the class c_p
- Then, we say that there are a number of documents that are candidates to be members of class c_p
- Further, we can present them to a user ordered by the decreasing values of $\mathcal{F}(d_j, c_p)$
- We also can use this rank to enforce a decision on whether a document belongs to a class or not

- To improve its effectiveness, our classifier might take advantage of a **training set**, as follows
 - Given a sub-collection $\mathcal{D}_t \subset \mathcal{D}$ of training documents,
 - A training set function $\mathcal{T}:\mathcal{D}_t\times\mathcal{C}\to\{0,1\}$ assigns a value of 0 or 1 to each pair $[d_j,c_p],\,d_j\in\mathcal{D}_t$ and $c_p\in\mathcal{C}$, according to the judgement of human specialists
- The training set function \mathcal{T} is used to fine tune the classifier
- Any evaluation of the classifier must be done considering only documents outside the training set

The text classification process



- Given a collection of documents, we first index them producing document representations
- In the full text logical view, a representation of a document d_j is the set of all its terms (or words)
- Each term of the document representation is considered as a separate variable or feature
- We can select a subset of the terms to represent the documents
- This is done through a process of **feature selection**, which reduces the document representations

- To improve its effectiveness, the classifier might also go through a process of fine tunning its internal parameters
- This is accomplished using a training set
- Once its parameters have been fine tunned, the classifier is used to classify the documents in a test set
- The final phase of the process is to evaluate the effectiveness of the classification
- The evaluation of a classifier is done by comparing results with a classification produced by humans

Classification Algorithms

Classification Algorithms

- In here, we discuss distinct approaches for performing document classification
- We do cover state-of-the art approaches that deliver top performance
- For each algorithm, we present first the basic technique used as its foundation

Classification Algorithms Decision Trees

Decision Trees

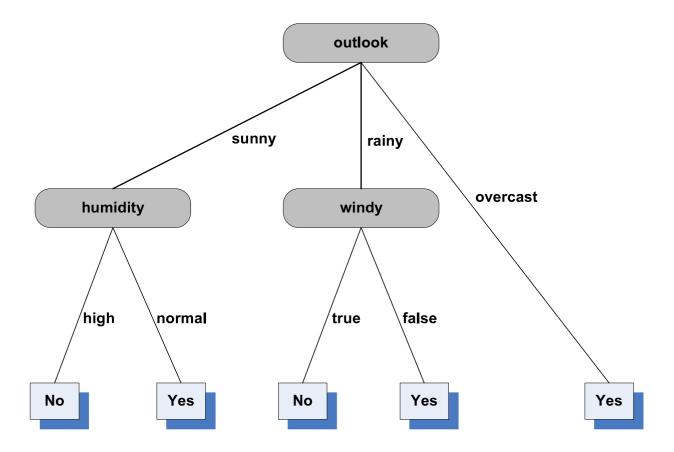
- A decision tree (DT) is a supervised classification method
- It uses a training set to build classification rules organized as paths in a tree
- These tree paths can then be used to classify documents outside the training set
- One of the advantages of the approach is that the rules in the tree are amenable to human interpretation
- This data structure facilitates the interpretation of the results of the classification process

Consider the small relational database in Table below

	Id	Play	Outlook	Temperature	Humidity	Windy
Training set	1	yes	rainy	cool	normal	false
	2	no	rainy	cool	normal	true
	3	yes	overcast	hot	high	false
	4	no	sunny	mild	high	false
	5	yes	rainy	cool	normal	false
	6	yes	sunny	cool	normal	false
	7	yes	rainy	cool	normal	false
	8	yes	sunny	hot	normal	false
	9	yes	overcast	mild	high	true
	10	no	sunny	mild	high	true
Test Instance	11	?	sunny	cool	high	false

A decision tree for this database is a data structure that allows predicting the values of a given attribute

To illustrate, the DT below allows predicting the values of the attribute Play, given that we know the values for attributes like Outlook, Humidity, and Windy



- The internal nodes are associated with attribute names and the edges are associated with attribute values
- A recursive traversal of the DT allows deciding the most appropriate value for the attribute "Play".
- In the case of tuple 11, the decision would be "not to play" based on the rule induced by the path

$$(Outlook = sunny) \land (Humidity = high)$$

	ld	Play	Outlook	Temperature	Humidity	Windy
Test Instance	11	?	sunny	cool	high	false

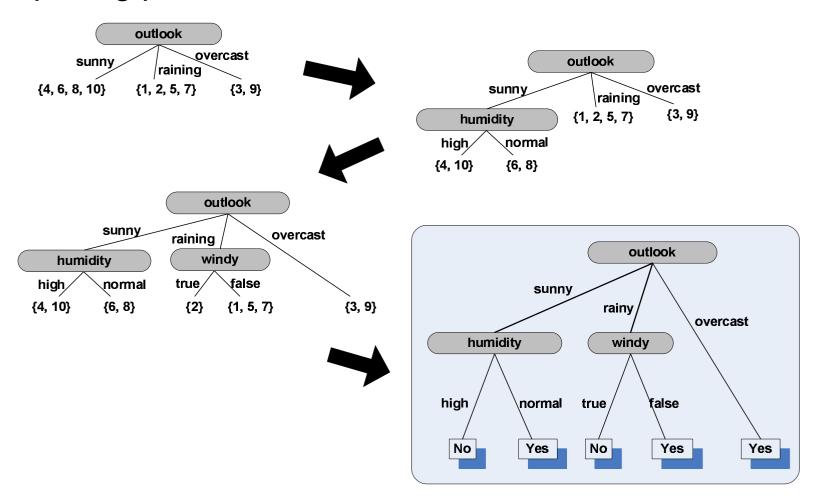
- Notice that our predictions are based on the instances that we have seen in the example database
- A new instance that violates these predictions will lead to an erroneous prediction
- We say that the example database works as a training set for building the decision tree

The Splitting Process

- Given a training set, a DT model for the database can be built using a recursive splitting strategy
- Consider that the objective is to build a decision tree for predicting the values of attribute Play
- The first step is to select one of the attributes, other than Play, to be the root of the decision tree
- The corresponding attribute values are then used to split the tuples in the database into subsets
- For each subset of tuples, a second splitting attribute is selected and the process is repeated

The Splitting Process

Figure below shows an step by step example of this splitting process



The Splitting Process

- Notice that the splitting process is strongly affected by the order with which the split attributes are selected
- Depending of this ordering, the tree might become unbalanced
- This is one of the key challenges while devising a splitting strategy
- Usually, balanced or near-balanced trees work better and more efficient for predicting attribute values
- Thus, a common rule of thumb is to select attributes that reduce the average path length of the leaves

- For document classification, with each internal node in the tree we associate an index term
- With each leave in the tree we associate a document class
- Further, with the edges we associate binary predicates that indicate the presence/absence of an index term
- One alternative is to verify the weight of the term in the document to decide which path to take in the tree
- This recursive traversal is conducted for each document to be classified
- Once a leaf is reached the class node associated with it becomes the document class

- Let V be a set of nodes
- A tree T = (V, E, r) is an acyclic graph on V where
 - \blacksquare $E \subseteq V \times V$ is the set of edges and
 - $r \in V$ is called the root of T
- Given an edge (v_i, v_j) , v_i is considered the father node and v_j is the child node
- We designate by I the set of all internal nodes and by \overline{I} the set of all leaf nodes

- \blacksquare Given a tree T, we can associate information on documents and their classes with the tree
- By doing so, we create a decision tree for document classification, as follows
- Let
 - $K = \{k_1, k_2, \dots, k_t\}$ be the set of index terms of a doc collection
 - C be the set of all classes, as before
 - \blacksquare P be a set of logical predicates on the index terms

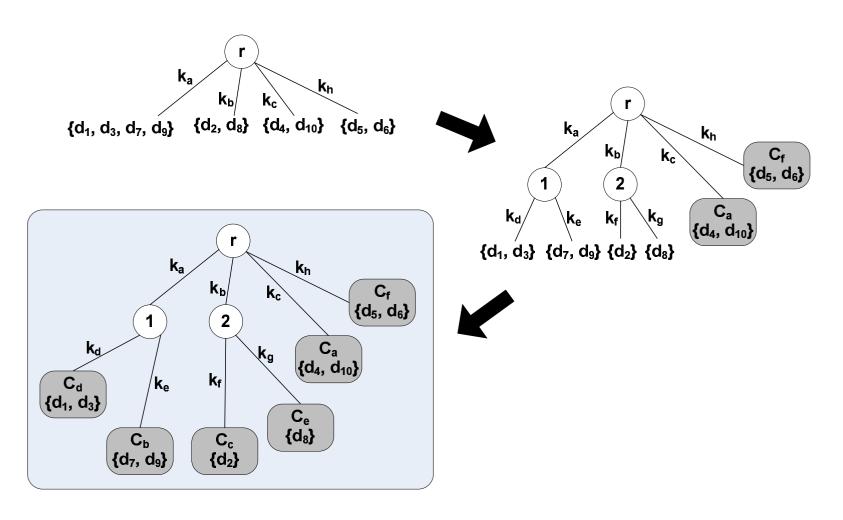
Further, let

- A decision tree $DT = (V, E; r; l_I, l_L, l_E)$ is a six-tuple where (V; E; r) is a tree whose root is r
- $lackbox{\limits} l_I:I o K$ is a function that associates with each internal node of the tree one or more index terms
- $lackbox{l} l_L: \overline{I}
 ightarrow C$ is a function that associates with each non-internal (leaf) node a class $c_p \in C$
- $l_E: E \to P$ is a function that associates with each edge of the tree a logical predicate from P

- Given a training set, a decision tree model for a class c_p can be built using a recursive splitting strategy
- The first step is to associate all documents to the root
- The **second step** is to select a number of index terms that provide a good separation of the documents
- To illustrate, consider that terms k_a , k_b , k_c , and k_h have been selected for this first split
- Then, the documents in the root are separated into 4 subsets

- The edge connecting a subset to the root is labelled with the respective index term
- Notice that a same document might appear in more than one subset
- Following, new splitting terms are selected for each doc subset and the process is repeated recursively
- At each branch, the recursion is stopped whenever all documents of a subset belong to a same class

Splitting process for inducing a decision tree for a collection of documents



- The crucial point of this process is the procedure for selecting splitting terms
- While distinct procedures can be used, information gain and entropy are the most commonly used ones
- Selection of terms with high information gain tends
 - to increase the number of branches at a given level, and
 - to reduce the number of documents in each resultant subset
- This tends to yield smaller and less complex decision trees

- Decision trees have some inherent problems such as missing or unknown values
- These appear when the document to be classified does not contain some terms used to build the DT
- In this case, it is not clear which branch of the tree should be traversed
- One approach to deal with the problem is to delay the construction of the tree until a new document is presented for classification
- The tree is then built based on the features presented in the document, therefore avoiding the problem

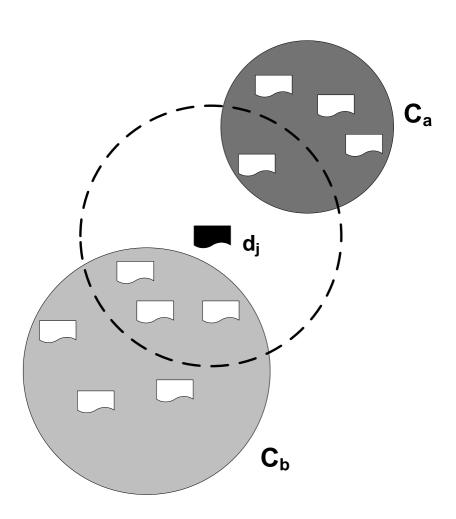
Classification Algorithms The kNN Classifier

The kNN Classifier

- The kNN (k-nearest neighbor) classifier is a type of on-demand (or lazy) classifier
- Lazy classifiers do not build a classification model a priori
- The classification is performed at the moment a new document d_i is given to the classifier
- It is based on the classes of the k nearest neighbors of d_j , computed using a distance function
- This is accomplished as follows:
 - determine the k nearest neighbors of d_j in a training set
 - lacksquare use the classes of these neighbors to determine a class for d_j

The kNN Classifier

An example of a 4-NN classification process



In the kNN algorithm, with each document-class pair $[d_j, c_p]$ we assign a score S_{d_j, c_p} , given by:

$$S_{d_j,c_p} = \sum_{d_t \in N_k(d_j)} similarity(d_j, d_t) \times \mathcal{T}(d_t, c_p)$$

where

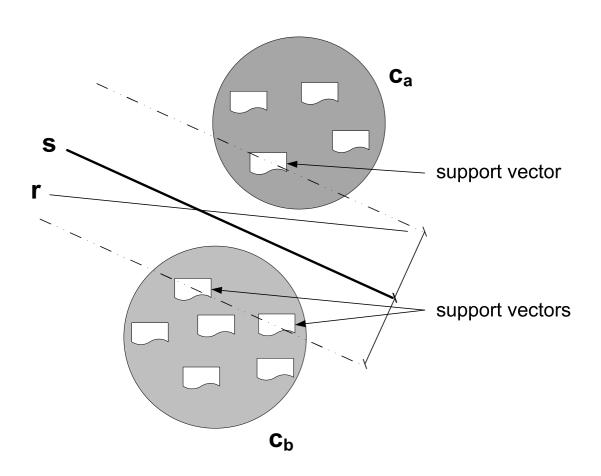
- $ightharpoonup N_k(d_j)$ is the set of the k nearest neighbors of d_j in the training set
- lacksquare $\mathcal{T}(d_t,c_p)$, the training set function, returns 1 if d_t belongs to class c_p , and 0 otherwise
- The classifier assigns to document d_j the class(es) c_p with the highest score(s)

- The cosine measure between the two document vectors is commonly used as the similarity function
- \blacksquare One problem with kNN is performance
- To determine the nearest documents, the classifier has to compute distances between the document to be classified and *all* training documents
- \blacksquare Another issue is how to choose the "best" value for k

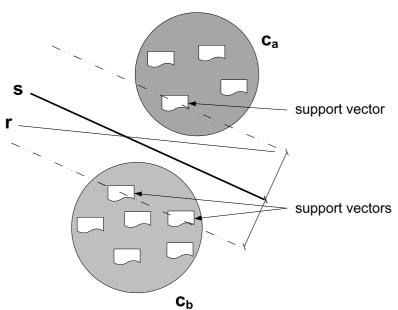
Classification Algorithms The SVM Classifier

- Support Vector Machines (SVMs) constitute a vector space method for binary classification problems
- Consider a set of documents represented in a t-dimensional space
- The idea is to find a decision surface (hyperplane) that best separate the elements of two classes
- Then, a new document d_j can be classified by computing its position relative to the hyperplane

Consider a simple 2D example whose training data points are linearly separable, as illustrated below

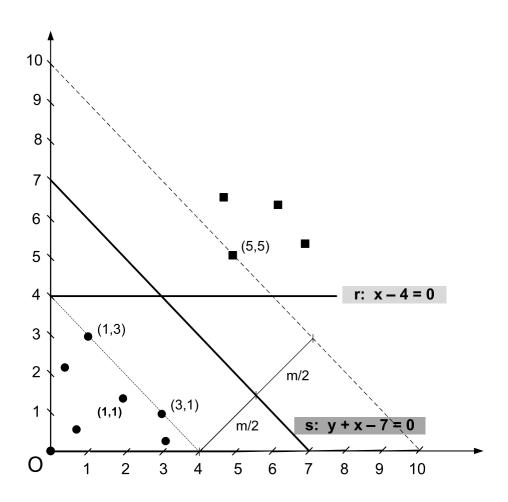


- Line s maximizes the distances to the closest documents of each class
- Then, s constitutes the best separating hyperplane, that we refer to the **decision hyperplane**
- In Figure, the parallel dashed lines delimit the region where to look for a solution
- We refer to them as the delimiting hyperplanes



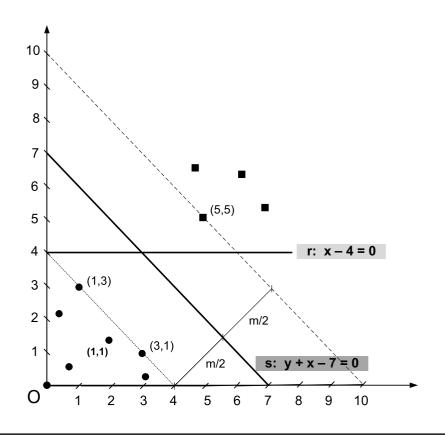
- Lines that cross the delimiting hyperplanes are candidates to be selected as the decision hyperplane
- Lines that are parallel to the this space are the best candidates
- Documents that belong to the delimiting hyperplanes are called support vectors

Figure below illustrates our example in a 2-dimensional system of coordinates



- The SVM optimization problem can be stated as follows
- Let \mathcal{H}_w be a hyperplane that separates all docs in class c_a from all docs in class c_b
- Further, Let
 - \blacksquare m_a be the distance of \mathcal{H}_w to the closest document in class c_a
 - \blacksquare m_b be the distance of \mathcal{H}_w to the closest document in class c_b
 - \blacksquare $m_a + m_b$, called the distance m, is the **margin** of the SVM
- The decision hyperplane \mathcal{H}_w maximizes the margin m

- In our example, the hyperplane r: x-4=0 separates the documents in the two sets
- It has distances to the closest documents in either class, points (1,3) and (5,5), equal to 1
 - \blacksquare Thus, its margin m is 2
- The hyperplane s: y+x-7=0 provides a margin equal to $3\sqrt{2}$, which is maximum for this case
- Then, the hyperplane s is the decision hyperplane

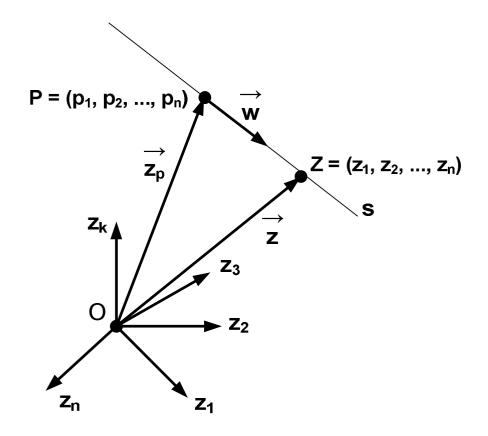


Lines and Hyperplanes in the \mathcal{R}^n

- Figure below illustrates a line s in the direction of a vector \vec{w} that contains a given point P (or \vec{z}_p)
- The parametric equation for the line s can be written as

$$s: \vec{z} = t \vec{w} + \vec{z}_p$$
 where $-\infty < t < +\infty$

As the parameter t varies from $-\infty$ to $+\infty$, the point \vec{z} traverses the line



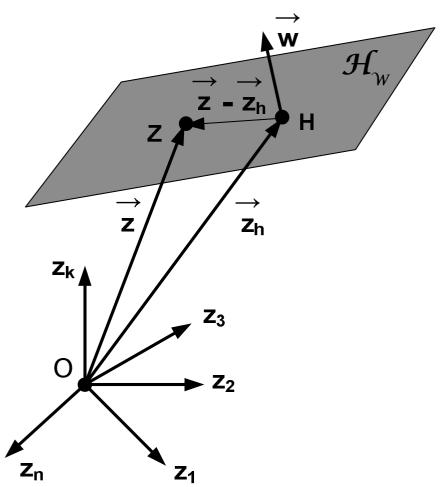
Lines and Hyperplanes in the \mathcal{R}^n

- Figure below illustrates a hyperplane \mathcal{H}_w that contains a point H and is perpendicular to the vector \vec{w}
- The normal equation for this hyperplane is

$$\mathcal{H}_w: (\vec{z} - \vec{z}_h)\vec{w} = 0$$

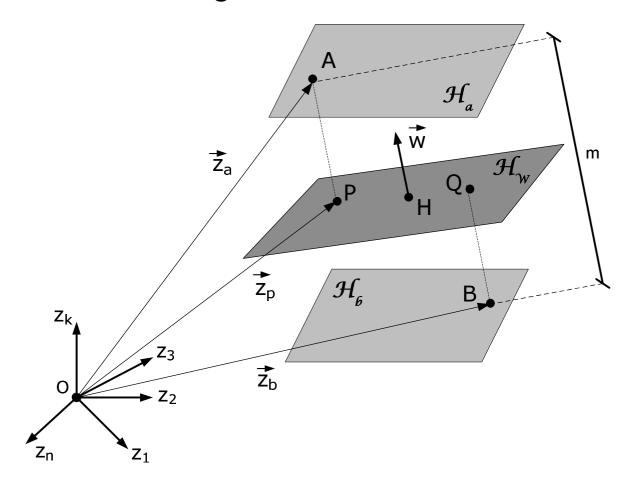
because the vectors $\vec{z} - \vec{z}_h$ and \vec{w} are perpendicular

The points \vec{z} that satisfy this equation belong to \mathcal{H}_w



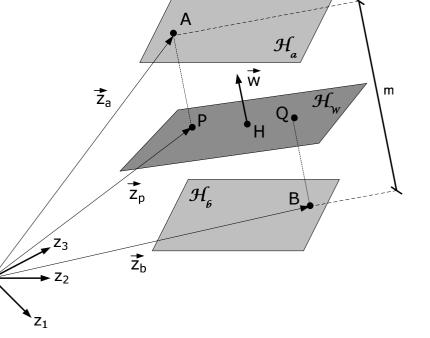
SVM Technique – Formalization

The SVM optimization problem: given support vectors such as \vec{z}_a and \vec{z}_b , find the hyperplane \mathcal{H}_w that maximizes the margin m



SVM Technique – Formalization

- The origin of the coordinate system is point O
- The point A represent a doc from the class c_a and the point B a doc from the class c_b
- These points belong to the delimiting hyperplanes \mathcal{H}_a and \mathcal{H}_b
- \mathcal{H}_w is determined by a point H (represented by \vec{z}_h) and by a perpendicular vector \vec{w}
- Neither \vec{z}_h nor \vec{w} are known a priori



lacksquare The normal equation for hyperplane \mathcal{H}_w is then

$$\mathcal{H}_w: (\vec{z} - \vec{z}_h)\vec{w} = 0$$

This equation can be rewritten as

$$\mathcal{H}_w: \vec{z}\vec{w} + b = 0$$

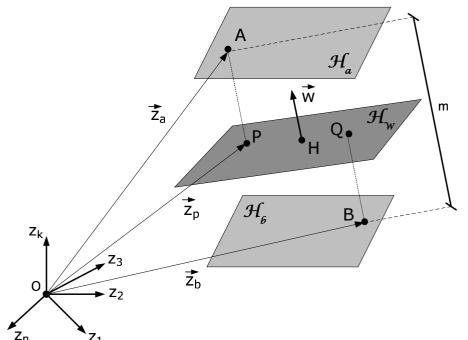
where \vec{w} and $b = -\vec{z}_h \vec{w}$ need to be determined

- The second form of the equation makes explicit that b is not a vectorial quantity
- This equation will be used interchangeably with the normal equation to refer to the hyperplane

- lacksquare Let P be the projection of point A on \mathcal{H}_w
- The line determined by points A and P is necessarily in the direction of vector \vec{w}
- Then, its parametric equation is

$$line(\overline{AP}): \vec{z} = t\vec{w} + \vec{z}_a$$

where
$$-\infty < t < +\infty$$



- For the point P specifically, we have $\vec{z}_p = t_p \vec{w} + \vec{z}_a$, where t_p is the value of t for point P
- Since $P \in \mathcal{H}_w$, we obtain

$$(t_p \vec{w} + \vec{z}_a)\vec{w} + b = 0$$

Solving for t_p ,

$$t_p = -\frac{\vec{z}_a \vec{w} + b}{|\vec{w}|^2}$$

lacksquare By substituting t_p back into Equation $ec{z}_p = t_p ec{w} + ec{z}_a$,

$$\vec{z}_a - \vec{z}_p = \frac{\vec{z}_a \vec{w} + b}{|\vec{w}|} \times \frac{\vec{w}}{|\vec{w}|}$$

Since $\vec{w}/|\vec{w}|$ is a unit vector in the direction of \vec{w} , we have

$$\overline{AP} = |\vec{z}_a - \vec{z}_p| = \frac{\vec{z}_a \vec{w} + b}{|\vec{w}|}$$

which is the distance of point A to hyperplane \mathcal{H}_w

This distance is normalized by $|\vec{w}|$ and, as a result, does not depend on the size of \vec{w}

- Consider the hyperplane \mathcal{H}_b , which is opposite to \mathcal{H}_a relatively to \mathcal{H}_w
- We can write analogous equations for \mathcal{H}_b , although these equations should all be relative to $-\vec{w}$:

$$\mathcal{H}_w: \quad (\vec{z}_h - \vec{z})(-\vec{w}) = 0$$

$$line(\overline{BQ}): \quad \vec{z} = -t\vec{w} + \vec{z_b}$$

where Q is the projection of point B on \mathcal{H}_w

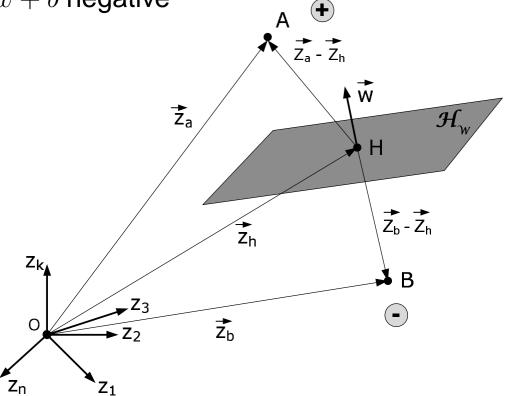
These two equations lead to

$$\overline{BQ} = |\vec{z}_b - \vec{z}_q| = -\frac{\vec{z}_b \vec{w} + b}{|\vec{w}|}$$

which is analogous to the expression for the segment \overline{AP}

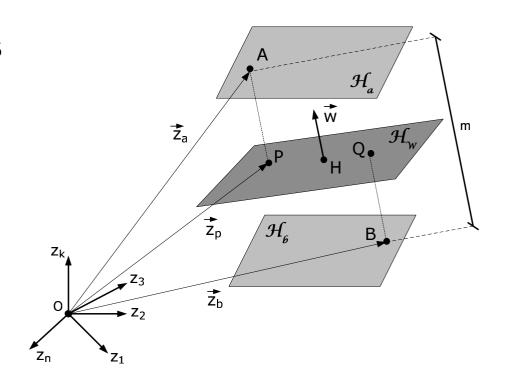
- Notice that the expression $\vec{z}_b \vec{w} + b$ is necessarily negative
- This is because \vec{z}_b is in the opposite region of \vec{z}_a , relatively to \mathcal{H}_w

- Signs in the SVM system:
 - The region above \mathcal{H}_w is composed of points \vec{z} that make $\vec{z}\vec{w} + b$ positive
 - The region below the hyperplane is composed of points that make $\vec{z}\vec{w}+b$ negative



- The margin m of the SVM is given by $m=\overline{AP}+\overline{BQ}$ and is independent of the size of \vec{w}
- That is, there are vectors \vec{w} of varying sizes that maximize m
- To impose restrictions on $|\vec{w}|$, we can set

$$\vec{z}_a \vec{w} + b = 1$$
$$\vec{z}_b \vec{w} + b = -1$$



- Notice that this restricts the solution to hyperplanes that split the margin m in the middle
- Under these conditions, the expression for the margin m becomes

$$m = \frac{2}{|\vec{w}|}$$

For a point C that is located farther away from the \mathcal{H}_w than a support vector, it must be either

$$\vec{z}_c \vec{w} + b > 1 \text{ or } \vec{z}_c \vec{w} + b < -1$$

depending on whether the point is in the positive or in the negative region

- Let $\mathcal{T} = \{\ldots, [c_j, \vec{z}_j], [c_{j+1}, \vec{z}_{j+1}], \ldots\}$, be the training set
- $lackbox{$\blacksquare$} c_j$ is the class (either c_a or c_b) associated with point \vec{z}_j , i.e., with a document d_j
- Then,

SVM Optimization Problem:

maximize $m=2/|\vec{w}|$ subject to

$$\vec{w}\vec{z}_j + b \ge +1 \text{ if } c_j = c_a$$

 $\vec{w}\vec{z}_j + b \le -1 \text{ if } c_j = c_b$

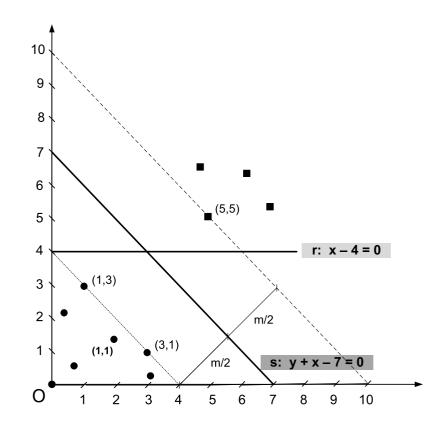
The vectors that make the equation equal to either 1 or
 -1 are the support vectors

- Let us consider again the simple example in Figure below
- For that case, the optimization problem can be especified as:

maximize $m = 2/|\vec{w}|$ subject to

$$\vec{w} \cdot (5,5) + b = +1$$

 $\vec{w} \cdot (1,3) + b = -1$



- If we represent vector \vec{w} as (x,y) then $|\vec{w}| = \sqrt{x^2 + y^2}$
- The parameter m stands for the distance between the delimiting hyperplanes and is equal to $3\sqrt{2}$
- Thus,

$$3\sqrt{2} = 2/\sqrt{x^2 + y^2}$$

$$5x + 5y + b = +1$$

$$x + 3y + b = -1$$

which yields b = -16/9 or b = -21/9

- The value that maximizes $2/|\vec{w}|$ is b=-21/9, which yields x=1/3,y=1/3
- Thus, the equation of the decision hyperplane is given by

$$(1/3, 1/3) \cdot (x, y) + (-21/9) = 0$$

or

$$y + x - 7 = 0$$

Classification of Documents

The classification of a doc d_j , represented as a vector \vec{z}_j , is achieved by applying the decision function

$$f(\vec{z}_j) = sign(\vec{w}\vec{z}_j + b)$$

- If the sign is positive then the document d_j belongs to class c_a ; otherwise, it belongs to class c_b
- The SVM classifier might also enforce the margin to reduce classification errors
- In this case a new document d_j
 - \blacksquare is classified in class c_a only if $ec{w} ec{z}_j + b > 1$, and
 - is classified in class c_b only if $\vec{w} \vec{z}_j + b < -1$

Classification of Documents

- SVMs are directly applicable when documents are represented by weighted multidimensional vectors
- Moreover, we can apply a feature selection to select the set of terms that are relevant to the classification task
- Finally, SVMs can only take binary decisions: a document belongs or not to a given class
- With multiple classes, a different classifier needs to be learned for each class

Feature Selection or Dimensionality Reduction

Feature Selection

- Metrics for feature selection are a key component of the classification process
- To produce feature vectors, we need to select a subset of the features (terms) to represent the documents
- Feature selection contributes to
 - Reduce the dimensionality of the documents representation
 - Reduce overfitting

Term-Class Incidence Table

- Before proceeding, it is useful to define a term-class incidence table
- Let \mathcal{D}_t be the subset composed of all training documents
- Further, let
 - $ightharpoonup N_t$ be the number of documents in \mathcal{D}_t
 - \blacksquare t_i be the number of documents from \mathcal{D}_t that contain the term k_i
 - lacksquare $\mathcal{C} = \{c_1, c_2, \dots, c_L\}$ be the set of all L classes
- Assume that a training set function $\mathcal{T}: \mathcal{D}_t \times \mathcal{C} \to [0,1]$ has been specified

Term-Class Incidence Table

The term-class incidence table is given by

	docs in c_p	docs not in c_p	
docs that contain k_i	$c_{i,p}$	$t_i - c_{i,p}$	t_i
docs that do not contain k_i	$P-c_{i,p}$	$N_t - t_i - (P - c_{i,p})$	$N_t - t_i$
all docs	P	$N_t - P$	N_t

- The number of documents that contain term k_i and are classified in class c_p is given by $c_{i,p}$
- The number of documents that contain term k_i but are not in class c_p is given by $t_i-c_{i,p}$
- lacksquare P is the total number of training documents in class c_p

Term-Class Incidence Table

- $ightharpoonup P-c_{i,p}$ is the number of documents from c_p that do not contain term k_i
- The remaining quantities are calculated analogously
- The term-class incidence table contains the sizes of various subsets that constitute the doc training set

Feature Selection or Dimensionality Reduction Term Document Frequency

Term Document Frequency

- Here, the idea is to select the terms whose document frequency exceeds a frequency threshold FT
- That is, all terms k_i for which $t_i \geq FT$ are retained, all other terms are discarded
- Even if simple, selection of higher document frequency terms allows considerably reducing the dimensionality of the space with no loss in effectiveness

Feature Selection or Dimensionality Reduction Tf-ldf Weights

Tf-Idf Weights

- A term selection procedure that retains the terms of higher tf-idf weights in each document d_j
- Some experiments suggest that this feature selection allows reducing the dimensionality of the space by a factor of 10 with no loss in effectiveness
- Further, a reduction of dimensionality by a factor of 100 leads to just a small loss in effectiveness

Feature Selection or Dimensionality Reduction Mutual Information

- Mutual information is a measure of the relative entropy between the distributions of two random variables
- If those variables are independent, we say that their mutual information is zero
 - In this case, knowledge of one of the variables does not allow infering anything about the other variable

Mutual information is expressed as

$$I(k_i, c_p) = \log \frac{P(k_i, c_p)}{P(k_i)P(c_p)}$$

where all probabilities are interpreted relatively to a doc d_j randomly selected from the set of training docs:

- lacksquare $P(k_i, c_p)$: probability that $k_i \in d_j$ and $d_j \in c_p$
- \blacksquare $P(k_i)$: probability that $k_i \in d_j$
- $ightharpoonup P(c_p)$: probability that $d_j \in c_p$

Using the term-class incidence table, we can specify these probabilities as follows:

$$P(k_i, c_p) = \frac{c_{i,p}}{N_t} \qquad P(k_i) = \frac{t_i}{N_t} \qquad P(c_p) = \frac{P}{N_t}$$

Our information metric relating the term k_i to the class c_p then becomes

$$I(k_i, c_p) = \log \frac{\frac{c_{i,p}}{N_t}}{\frac{t_i}{N_t} \times \frac{P}{N_t}} = \log \frac{c_{i,p} \times N_t}{t_i \times P}$$

To apply feature selection to term k_i , we compute its average mutual information across all classes as follows

$$MI_{avg}(k_i) = \sum_{p=1}^{L} P(c_p) I(k_i, c_p)$$
$$= \sum_{p=1}^{L} \frac{P}{N_t} \log \frac{c_{i,p} \times N_t}{t_i \times P}$$

An alternative is to use the maximum term information over all classes, as follows:

$$I_{max}(k_i) = max_{p=1}^{L} I(k_i, c_p)$$
$$= max_{p=1}^{L} \log \frac{c_{i,p} \times N_t}{t_i \times P}$$

- The feature selection process, in this case, works as follows:
 - terms with values of $MI_{avg}(k_i)$, or of $I_{max}(k_i)$, above a given threshold are retained;
 - the remaining terms are discarded.

Feature Selection or Dimensionality Reduction Information Gain

- Mutual information uses the probabilities associated with the occurrence of terms in documents
- Information Gain is a complementary metric, that also considers the probabilities associated with the absence of terms in documents
- It balances the effects of term/document occurrences with the effects of term/document absences

The information gain $IG(k_i, C)$ of term k_i over the set C of all classes is defined as follows

$$IG(k_i, \mathcal{C}) = H(\mathcal{C}) - H(\mathcal{C}|k_i) - H(\mathcal{C}|\neg k_i)$$

where

- \blacksquare $H(\mathcal{C})$ is the entropy of the set of classes \mathcal{C}
- $H(C|k_i)$ and $H(C|\neg k_i)$ are the conditional entropies of C in the presence and in the absence of term k_i
- In information theory terms, $IG(k_i, C)$ is a measure of the amount of knowledge gained about C due to the fact that k_i is known

Using the term-class incidence table defined previously, and recalling the expression for entropy, we can write,

$$IG(k_i, C) = -\sum_{p=1}^{L} P(c_p) \log P(c_p)$$

$$-\left[-\sum_{p=1}^{L} P(k_i, c_p) \log P(c_p|k_i)\right]$$

$$-\left[-\sum_{p=1}^{L} P(\neg k_i, c_p) \log P(c_p|\neg k_i)\right]$$

Applying Bayes rule, this can rewritten as

$$IG(k_i, \mathcal{C}) = -\sum_{p=1}^{L} \left[P(c_p) \log P(c_p) - P(k_i, c_p) \log \frac{P(k_i, c_p)}{P(k_i)} - P(\neg k_i, c_p) \log \frac{P(\neg k_i, c_p)}{P(\neg k_i)} \right]$$

where all probabilities are interpreted relatively to a doc d_j randomly selected from the training set

- That is,
 - $ightharpoonup P(\neg k_i, c_p)$: probability that $k_i \not\in d_j$ and $d_j \in c_p$
 - \blacksquare $P(\neg k_i)$: probability that $k_i \not\in d_j$
- Using the term-class incidence table defined previously, we can specify these probabilities as follows:

$$P(\neg k_i, c_p) = \frac{P - c_{i,p}}{N_t}$$

$$P(\neg k_i) = \frac{N_t - t_i}{N_t}$$

Information Gain

Based on the previous Equation, we can write

$$IG(k_i, C) = -\sum_{p=1}^{L} \left[\frac{P}{N_t} \log \frac{P}{N_t} - \frac{c_{i,p}}{N_t} \log \frac{c_{i,p}}{t_i} - \frac{P - c_{i,p}}{N_t} \log \frac{P - c_{i,p}}{N_t - t_i} \right]$$

- The feature selection process works as follows:
 - \blacksquare terms with values of $IG(k_i, \mathcal{C})$ above a given threshold are retained
 - the remaining terms are discarded

Evaluation Metrics

Evaluation Metrics

- Evaluation is a very important step in the development of any text classification method
- Without proper evaluation, there is no way to determine how good is a newly proposed text classifier
- That is, evaluation is a key step to validate a newly proposed classification method
- Here, we describe some of the most used metrics to assess the quality of single label text classifiers
- We start defining a contingency table, that will be to describe the most used evaluation metrics

Contingency Table

Let

- \blacksquare \mathcal{D} be a collection of documents
- \blacksquare \mathcal{D}_t be the subset composed of training documents
- $ightharpoonup N_t$ be the number of documents in \mathcal{D}_t
- $\mathcal{C} = \{c_1, c_2, \dots, c_L\}$ be the set of all L classes

Assume that have been specified

- \blacksquare A training set function $\mathcal{T}:\mathcal{D}_t\times\mathcal{C}\to[0,1]$
- lacksquare A text classifier function $\mathcal{F}:\mathcal{D} imes\mathcal{C} o[0,1]$

Further, let

- lacksquare P_t be the number of docs from the training set \mathcal{D}_t in class c_p
- $ightharpoonup P_f$ be the number of docs from the training set assigned to class c_p by the classifier

Contingency Table

- Consider the application of the classifier to all documents in the training set
- The contingency table is given by

	$\mathcal{T}(d_j, c_p) = 1$	$\mathcal{T}(d_j, c_p) = 0$	
$\mathcal{F}(d_j, c_p) = 1$	$c_{f,t}$	$P_f - c_{f,t}$	P_f
$\mathcal{F}(d_j, c_p) = 0$	$P_t - c_{f,t}$	$N_t - P_f - P_t + c_{f,t}$	$N_t - P_f$
all docs	P_t	$N_t - P_t$	N_t

- where $c_{f,t}$ is the number of docs that both the training and classifier functions assigned to class c_p
- The number of training docs in class c_p that were miss-classified by the classifier is given by $P_t c_{f,t}$
- The remaining quantities are calculated analogously

Evaluation MetricsContingency Table

The accuracy and error metrics are defined relative to a given class c_p , as follows

$$Acc(c_p) = \frac{c_{f,t} + (N_t - P_f - P_t + c_{f,t})}{N_t}$$

 $Err(c_p) = \frac{(P_f - c_{f,t}) + (P_t - c_{f,t})}{N_t}$

Notice that necessarily

$$Acc(c_p) + Err(c_p) = 1$$

- Accuracy and error, despite their common use, have disadvantages
- Consider, for instance, a binary classification problem with only two categories c_p and c_r
- Assume that out of 1,000 documents there are only 20 in class c_p
- Then, a classifier that assumes that all docs are not in class c_p has an accuracy of 98% and an error of just 2%
- These values suggest that we have a very good classifier, but this is not the case

Consider now a second classifier that correctly predicts 50% of the documents in c_p , as illustrated below

	$\mathcal{T}(d_j, c_p) = 1$	$\mathcal{T}(d_j, c_p) = 0$	
$\mathcal{F}(d_j, c_p) = 1$	10	0	10
$\mathcal{F}(d_j, c_p) = 0$	10	980	990
all docs	20	980	1,000

In this case, accuracy and error are given by

$$Acc(c_p) = \frac{10 + 980}{1,000} = 99\%$$

 $Err(c_p) = \frac{10 + 0}{1,000} = 1\%$

- This classifier is much better than one that guesses that all documents are not in class c_p
- However, its accuracy is just 1% better (it increased from 98% to 99%)
- This suggests that the two classifiers are almost equivalent, which is not the case.

Evaluation Metrics Precision and Recall

Precision and Recall

- Precision and recall in text classification are variants of the precision and recall metrics in IR
- Precision P and recall R are computed relative to a given class c_p , as follows

$$P(c_p) = \frac{c_{f,t}}{P_f} \qquad R(c_p) = \frac{c_{f,t}}{P_t}$$

- Precision is the fraction of all docs assigned to class c_p by the classifier that really belong to class c_p
- Recall is the fraction of all docs that belong to class c_p that were correctly assigned to class c_p

Precision and Recall

Consider again the the classifier illustrated below

	$\mathcal{T}(d_j, c_p) = 1$	$\mathcal{T}(d_j, c_p) = 0$	
$\mathcal{F}(d_j, c_p) = 1$	10	0	10
$\mathcal{F}(d_j, c_p) = 0$	10	980	990
all docs	20	980	1,000

Precision and recall figures are given by

$$P(c_p) = \frac{10}{10} = 100\%$$

 $R(c_p) = \frac{10}{20} = 50\%$

That is, the classifier has precision of 100% and recall of 50% for class c_p

Precision and Recall

- Precision and recall defined in this way are computed for every category in set C
- This yields a great number of values, making the tasks of comparing and evaluating algorithms more difficult
- It is often convenient to combine precision and recall into a single quality measure
- One of the most commonly used such measures is the *F-measure*, which we discuss now

Evaluation MetricsF-measure

F-measure

- The F-measure combines precision and recall values
- It allows for the assignment of different weights to each of these measures
- It is defined as follows:

$$F_{\alpha}(c_p) = \frac{(\alpha^2 + 1)P(c_p)R(c_p)}{\alpha^2 P(c_p) + R(c_p)}$$

where α defines the relative importance of precision and recall

- When $\alpha = 0$, only precision is considered. When $\alpha = \infty$, only recall is considered
- When $\alpha = 0.5$, recall is half as important as precision, and so on

F-measure

- The most used form of the F-measure is obtained by assigning equal weights to precision and recall
- This is accomplished by making $\alpha = 1$, and is is called the F_1 -measure:

$$F_1(c_p) = \frac{2P(c_p)R(c_p)}{P(c_p) + R(c_p)}$$

F-measure

Consider again the the classifier illustrated below

	$\mathcal{T}(d_j, c_p) = 1$	$\mathcal{T}(d_j, c_p) = 0$	
$\mathcal{F}(d_j, c_p) = 1$	10	0	10
$\mathcal{F}(d_j, c_p) = 0$	10	980	990
all docs	20	980	1,000

For this example, we write

$$F_1(c_p) = \frac{2 * 1 * 0.5}{1 + 0.5} \sim 67\%$$

Evaluation MetricsF-measure

- It is also common to derive a unique F_1 value for a classifier
- This is accomplished computing the average of F_1 values across all individual categories
- There are two average functions that are considered in the literature:
 - \blacksquare Micro-average F1, or $micF_1$
 - Macro-average F_1 , or $macF_1$

Macro-average F_1 is computed as

$$macF_1 = \frac{\sum_{p=1}^{|\mathcal{C}|} F_1(c_p)}{|\mathcal{C}|}$$

Thus, macro-average F_1 simply averages F_1 across all categories

To compute micro-average F_1 we consider recall and precision figures over all categories, as follows

$$P = \frac{\sum_{c_p \in \mathcal{C}} c_{f,t}}{\sum_{c_p \in \mathcal{C}} P_f}$$

$$R = \frac{\sum_{c_p \in \mathcal{C}} c_{f,t}}{\sum_{c_p \in \mathcal{C}} P_t}$$

Then, micro-average F_1 can be computed by

$$micF_1 = \frac{2PR}{P+R}$$

- In micro-average F_1 , every single document is given the same importance
- In macro-average F_1 , every single category is given the same importance
- Macro-average F_1 captures better the ability of the classifier to perform well for many classes
- This becomes important whenever the distribution of classes is very skewed
- In this case, both average metrics should be considered

Evaluation MetricsCross-Validation

Cross-Validation

- Cross-validation has become a standard method to guarantee the statistical validation of the results
- It consists of building k different classifiers: $\Psi_1, \Psi_2, \ldots, \Psi_k$
- The classifiers are built by dividing the training set \mathcal{D}_t into k disjoint sets or folds of sizes

$$N_{t1}, N_{t2}, \ldots, N_{tk}$$

Cross-Validation

- The classifier Ψ_i uses the training set minus the ith fold for tunning and run its test on the ith fold
- Each classifier is evaluated independently using precision-recall or F_1 figures
- The cross-validation is done by computing the average of the k measures
- The most commonly adopted value of k is 10, in which case the method is called ten-fold cross-validation

Evaluation Metrics Standard Collections

- Several standard benchmark collections are available for experimenting classification techniques
- In the immediately following, we present some of the most used benchmark collections

Reuters-21578

- It is the most widely used collection in the classification experiments
- It is constituted of news articles from Reuters for the 1987 year
- The collection is classified under several categories related to economics (e.g., acquisitions, earnings, etc)
- It contains 9,603 documents for training and 3,299 for testing, with 90 categories co-occuring in both training and test
- Class proportions range from 1,88% to 29,96% in the training set and from 1,7% to 32,95% in the testing set

Reuters Corpus Volume 1 (RCV1) and Volume 2 (RCV2)

- The RCV1 is another collection of news stories recently released by Reuters
- It contains approximately 800,00 documents organized in 103 topical categories
- It is expected to substitute the previous Reuters-21578 collection in text classification experiments
- RCV2 is a modified version of the original released collection, in which some corrections were made

OHSUMED

- OHSUMED is another popular collection used for testing text classification algorithms
- It is a subset of the Medline digital library, containing medical documents (title or title + abstract)
- There are 23 classes corresponding to MesH diseases used to index the documents

20 NewsGroups

- A third largely used collection is 20 Newsgroups
- This is a collection of approximately 20,000 messages posted to Usenet newsgroups, partitioned (nearly) evenly across 20 different newsgroups
- The categories are the newsgroups themselves

- Other collections reported in the text classification literature
 - WebKB hypertext collection
 - ACM-DL
 - a subset of the ACM Digital Library
 - samples of Web Directories such as Yahoo and ODP