

Assignment 2 - due September 20th

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Exercise 1. (*) Bruno's exercise: Given Euclidean spaces V_1 and V_2 , define $V_1 \oplus V_2$ as the Euclidean space with elements in $V_1 \times V_2$ and coordinate-wise operations:

- $(\mathbf{v}_1, \mathbf{v}_2) + (\mathbf{u}_1, \mathbf{u}_2) = (\mathbf{v}_1 + \mathbf{u}_1, \mathbf{v}_2 + \mathbf{u}_2)$.
- $\alpha(\mathbf{v}_1, \mathbf{v}_2) = (\alpha\mathbf{v}_1, \alpha\mathbf{v}_2)$.
- $\langle (\mathbf{v}_1, \mathbf{v}_2), (\mathbf{u}_1, \mathbf{u}_2) \rangle = \langle \mathbf{v}_1, \mathbf{u}_1 \rangle + \langle \mathbf{v}_2, \mathbf{u}_2 \rangle$.

If $K_1 \subseteq V_1$ and $K_2 \subseteq V_2$ are cones, show that

- (a) $K_1 \oplus K_2$ is a cone.
- (b) $(K_1 \oplus K_2)^* = K_1^* \oplus K_2^*$ (no need to assume anything about these cones).
- (c) Decide if K_1 and K_2 convex and/or closed is if and only if the same holds for $K_1 \oplus K_2$.

Exercise 2. (*) Suppose we decide to add a constraint of the form $\text{rank } \mathbf{X} = 1$ to an SDP. The goal of this exercise is to show that this can leave the problem (most likely) intractable. Consider a simple loopless graph $G = (V, E)$, with adjacency matrix \mathbf{A} .

- (a) Let $\mathcal{P} = \{\mathbf{x} \in \{0, 1\}^V : \mathbf{x}^T \mathbf{A} \mathbf{x} = 0\}$. What graph parameter is $\max\{\mathbf{1}^T \mathbf{x} : \mathbf{x} \in \mathcal{P}\}$?

Given \mathbf{x} , let $\hat{\mathbf{X}}$ denote

$$\hat{\mathbf{X}} = \begin{pmatrix} 1 & \mathbf{x}^T \\ \mathbf{x} & \mathbf{x}\mathbf{x}^T \end{pmatrix} \in \mathbb{S}^{\{0\} \cup V} \text{ (this means rows and columns are indexed by } \{0\} \cup V \text{).}$$

- (b) Argue why, for all $\mathbf{x} \in \mathcal{P}$, we have that $\hat{\mathbf{X}} \in \mathbb{S}_+^{\{0\} \cup V}$.
- (c) Let $\{\mathbf{e}_0, \mathbf{e}_1, \dots, \mathbf{e}_n\}$ be the canonical basis for $\mathbb{R}^{\{0\} \cup V}$. Argue why, for all $\mathbf{x} \in \mathcal{P}$, we have that $\hat{\mathbf{X}}\mathbf{e}_0 = \text{diag } \hat{\mathbf{X}}$.
- (d) Argue why, for all $\mathbf{x} \in \mathcal{P}$, we have $\hat{\mathbf{X}}_{ab} = 0$ for all $ab \in E(G)$.
- (e) In the following program, we will optimize over matrices in $\mathbb{S}^{\{0\} \cup V}$ that satisfy the properties you showed above that $\hat{\mathbf{X}}$ satisfy for when $\mathbf{x} \in \mathcal{P}$ (but that are not necessarily defined as such).

$$\begin{aligned} & \max && \sum_{a \in V} \mathbf{X}_{0a} \\ & \text{subject to} && \mathbf{X}_{00} = 1, \\ & && \mathbf{X}\mathbf{e}_0 = \text{diag } \mathbf{X}, \\ & && \mathbf{X}_{ab} = 0 \text{ for all } ab \in E(G), \\ & && \mathbf{X} \in \mathbb{S}_+^{\{0\} \cup V}. \end{aligned}$$

Explain why the optimum of this SDP might still not be equal to the parameter you found in (a) (you could give a shady reason, or provide an example and make me happy.)

- (f) Argue why adding the constraint $\text{rank } \mathbf{X} = 1$ to program above will make its optimum value equal to the parameter you found in (a). Conclude that solving an SDP with a rank = 1 constraint is NP-hard.
- (g) For a bonus, show that the optimum of the SDP in (e) is $\vartheta(G)$ (or at least prove one side of an inequality).

Exercise 3. (*) Show that the Lorentz cone is self dual.

Exercise 4. Let $p(x)$ be a polynomial of degree d , real coefficients. We would like to find out if $p(x) \geq 0$ for all x . This would happen if there are polynomials $q_1(x), \dots, q_m(x)$ so that

$$p(x) = \sum_{i=1}^m q_i(x)^2.$$

- (a) Write this decision problem as the problem of finding a feasible solution to an SDP. (Hint: let $[x]_d$ be the “vector” whose k th entry is the monomial x^{k-1} . Note that $q(x)^2 = [x]_d^T \mathbf{q} \mathbf{q}^T [x]_d$ where \mathbf{q} is the vector with coefficients of $q(x)$.)
- (b) Every real polynomial can be factored over \mathbb{R} as polynomials with real coefficients which are either linear or quadratic. Using this, show that $p(x) \geq 0$ for all $x \in \mathbb{R}$ if and only if it can be written as a sum of squares. (Hint: could linear terms appear?)
- (c) Let $p(x)$. Express the global minimum $\min\{p(y) : y \in \mathbb{R}\}$ as the optimum of an SDP.
- (d) For a bonus point, formulate the problem of deciding if $p(x_1, \dots, x_n)$ and total degree d can be written as the sum of squares of polynomials in n variables as the feasibility of an SDP.

Exercise 5. Prove Vinicius’s exercise: for any cone, \mathbb{K}^{**} is the closure of the convex hull of \mathbb{K} (ie, show that \mathbb{K}^{**} is the smallest closed and convex cone that contains \mathbb{K}). Hint: hyperplane separation?

Exercise 6. Assume \mathbb{K} is a closed, convex cone. From the exercise above, we know that $\mathbb{K}^{**} = \mathbb{K}$. Here, use this fact to prove that

- (a) If K is pointed, then \mathbb{K}^* has non-empty interior.
- (b) If K has non-empty interior, then \mathbb{K}^* is pointed.

(Hint: use that the existence of an interior point implies that the cone contains a basis of the space.)

Exercise 7. Given \mathbf{M} symmetric, with eigenvalues $\lambda_1 \geq \dots \geq \lambda_n$, show that $\lambda_1 + \dots + \lambda_k$ is equal to

$$\begin{aligned} \max \quad & \langle \mathbf{M}, \mathbf{X} \rangle \\ \text{subject to} \quad & \langle \mathbf{I}, \mathbf{X} \rangle = k \\ & \mathbf{X} \preceq \mathbf{I} \\ & \mathbf{X} \succeq \mathbf{0}. \end{aligned}$$