

# SIoT – Securing the Internet of Things through Distributed System Analysis

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# Agenda

- Introduction
- Goal
- Solution
- Results
- Conclusion

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  - IoT
  - C language
  - Buffer Overflow
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# IoT



- Capabilities
  - It's made up with constrained devices
- Computing Paradigm
  - A distributed system and usually exchange a large number of messages
- Programming language
  - Apps are often written in C, which is inherently unsafe

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- Capabilities
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  - A distributed system and usually exchange a large number of messages
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  - Apps are often written in C, which is inherently unsafe

C is unsafe because it does not check array-bounds

# Agenda

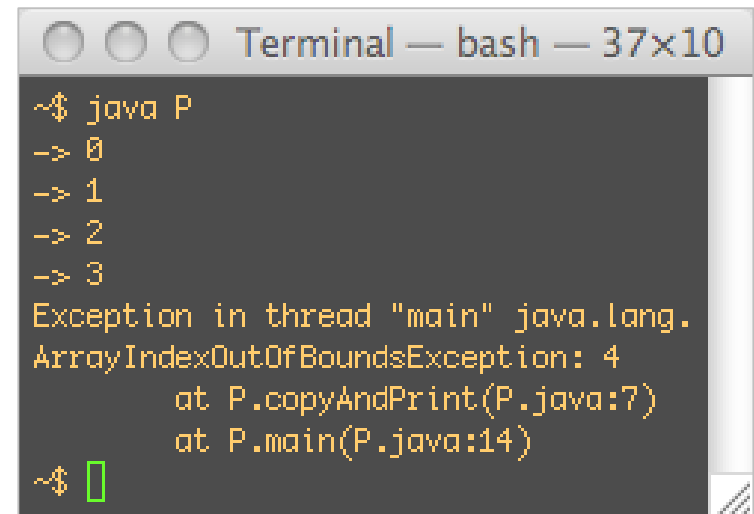
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# Java

Q: What happens when we run this Java program?

```
public class P {  
    final static int SIZE = 4;  
  
    static void copyAndPrint(byte[] v) {  
        byte[] buf = new byte[SIZE];  
        for (int i = 0; i < v.length; i++) {  
            buf[i] = v[i];  
            System.out.println("-> " + buf[i]);  
        }  
    }  
  
    public static void main(String args[]) {  
        byte[] v = {0, 1, 2, 3, 4};  
        copyAndPrint(v);  
    }  
}
```



```
Terminal — bash — 37x10  
~$ java P  
-> 0  
-> 1  
-> 2  
-> 3  
Exception in thread "main" java.lang.  
ArrayIndexOutOfBoundsException: 4  
    at P.copyAndPrint(P.java:7)  
    at P.main(P.java:14)  
~$
```



# C language

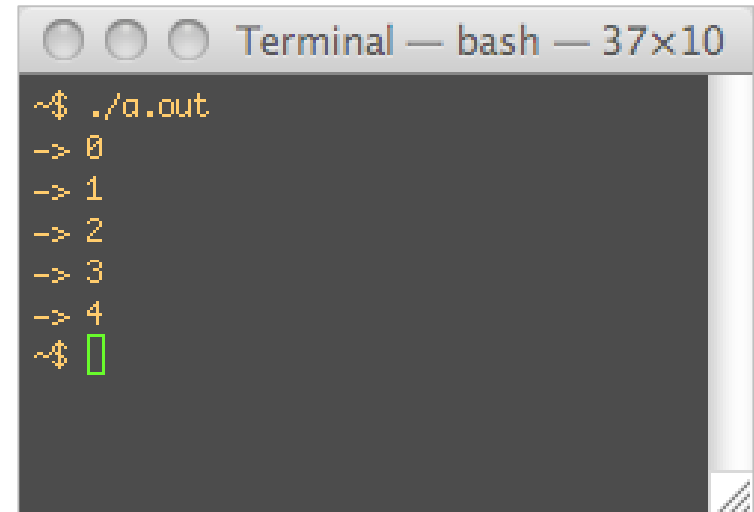
Q: What about this C program?

```
#include <stdio.h>
```

```
#define SIZE 4
```

```
void copyAndPrint(char v[], int n) {  
    char buf[SIZE];  
    int i;  
    for (i = 0; i < n; i++) {  
        buf[i] = v[i];  
        printf("-> %d\n", buf[i]);  
    }  
}
```

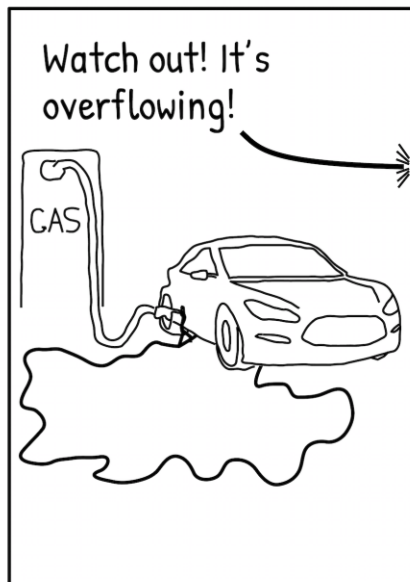
```
int main() {  
    char v[] = {0, 1, 2, 3, 4};  
    copyAndPrint(v, SIZE + 1);  
}
```



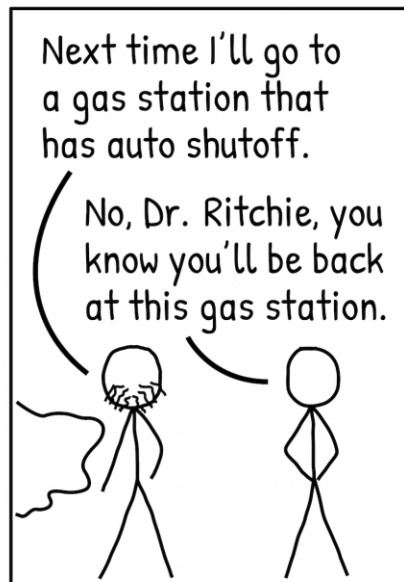
```
Terminal — bash — 37x10  
~$ ./a.out  
-> 0  
-> 1  
-> 2  
-> 3  
-> 4  
~$ █
```



## Q: Why is that?



Buffer Overflow.



# C unsafety: Outcomes



- Morris worm
  - Buffer over-write that compromised around 10% of computers connected to the Internet back in 1988
- Heartbleed
  - Buffer over-read that compromised half a million web servers in 2014
- IoT vulnerability
  - Due the unsafe nature of C, IoT apps are vulnerable to buffer overflow attacks, too

# C unsafety: Outcomes



- Morris worm
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Buffer Overflow?

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# Buffer Overflow



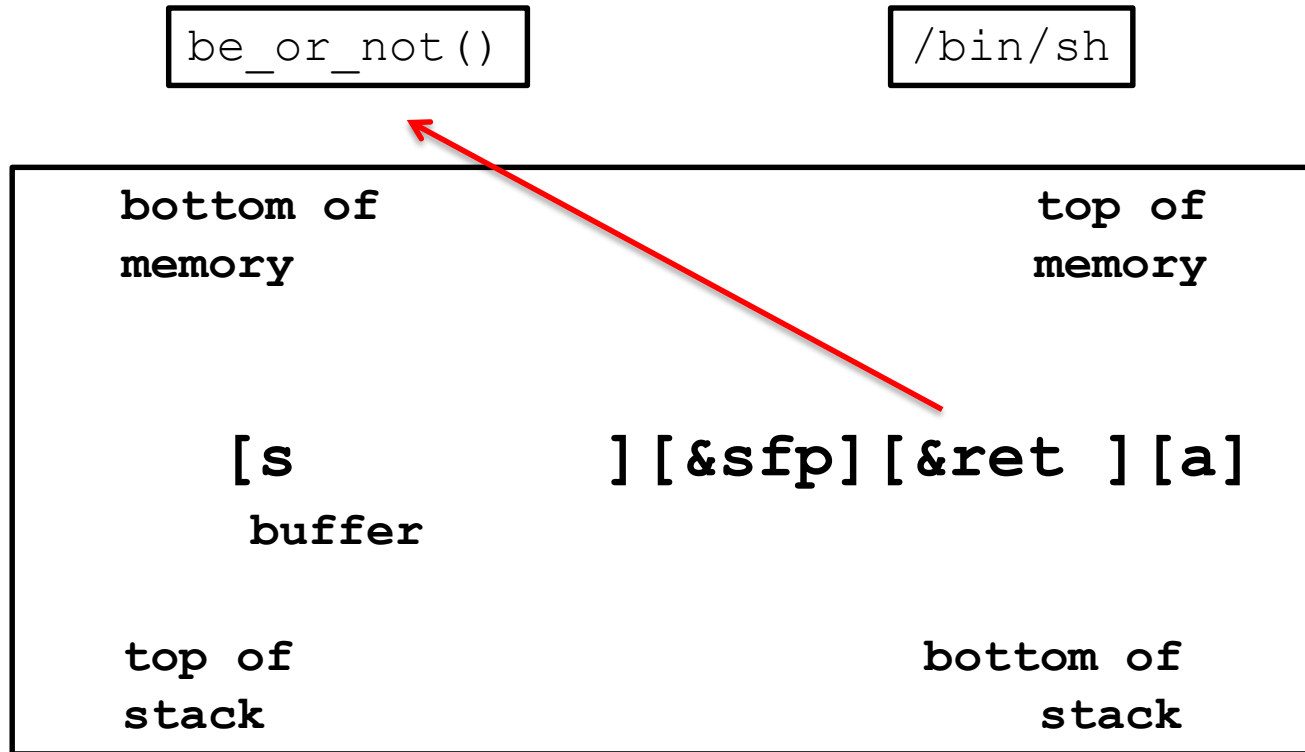
- A buffer overflow happens when the memory space that guides the execution flow is overwritten
- The idea is to manipulate arrays w/o bound checks

```
#include <stdio.h>

int main(int argc, char **argv) {
    char buf[8]; // creates 8-byte block memory
    gets(buf);   // reads unlimited number of bytes

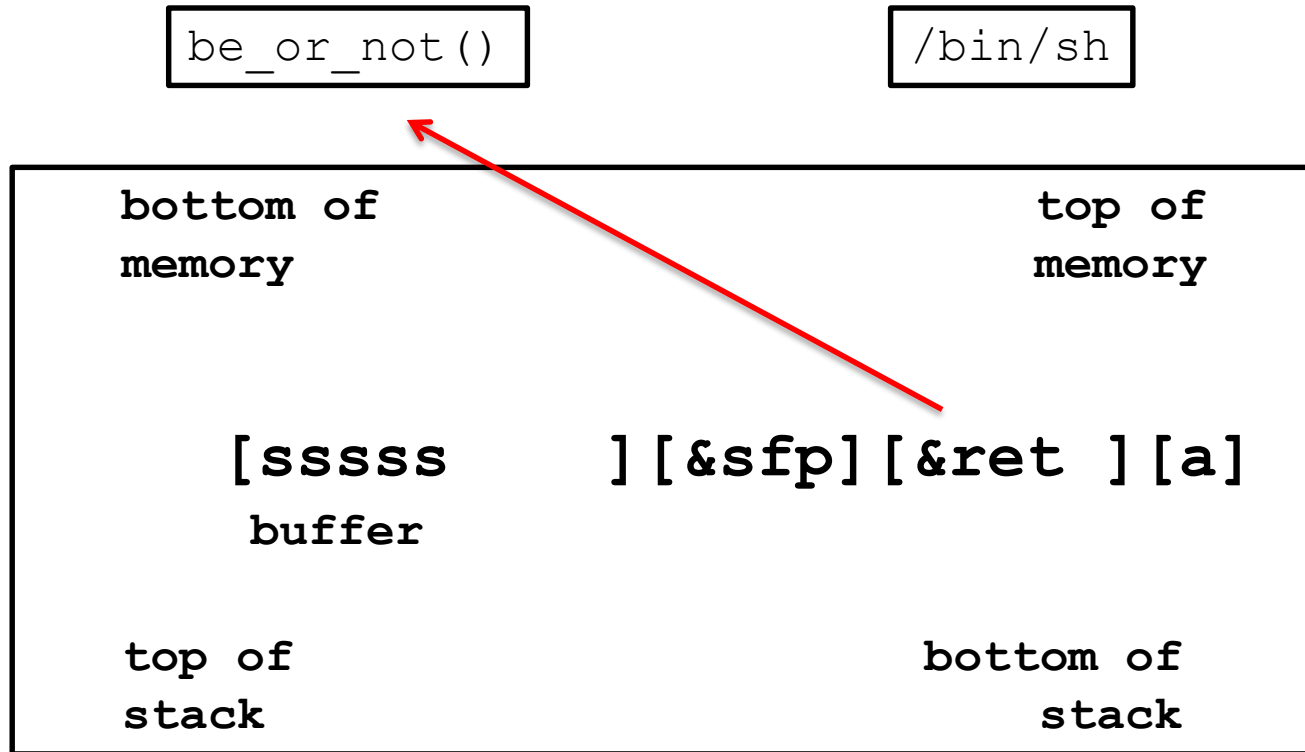
    return 0;
}
```

# BOF (Cont.)

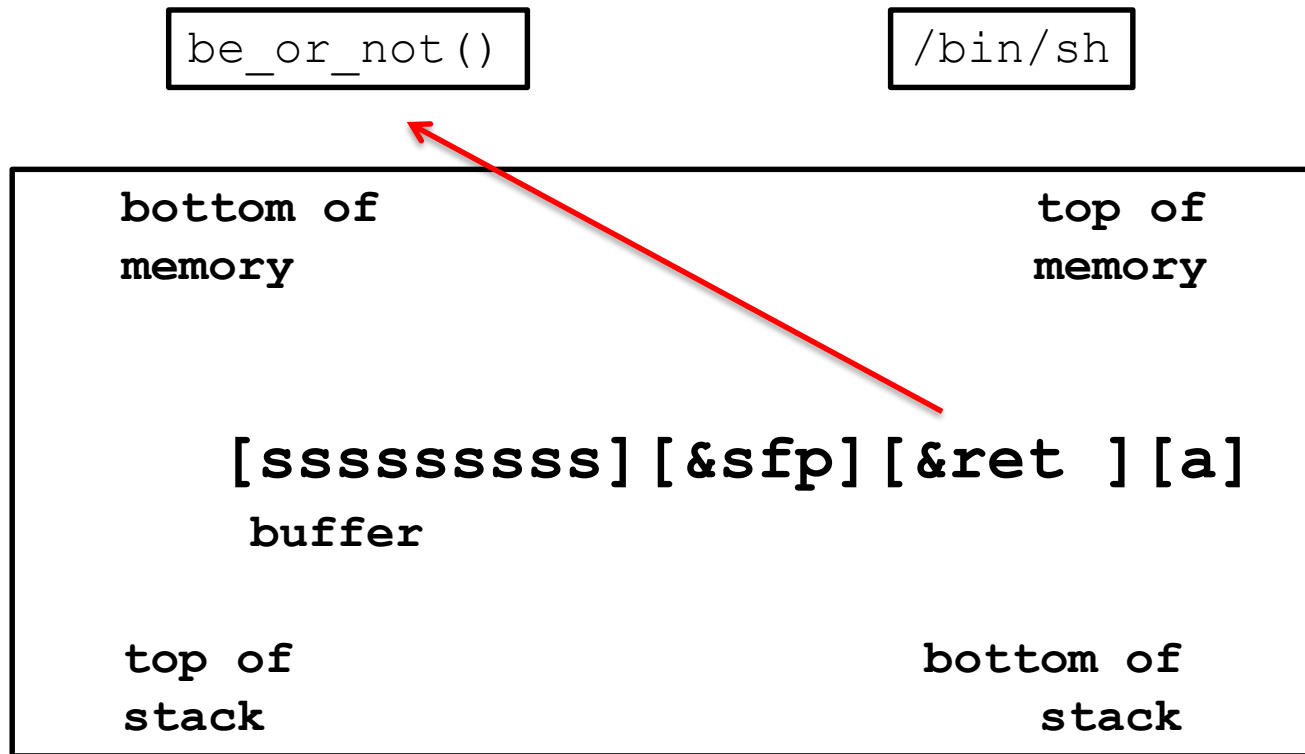




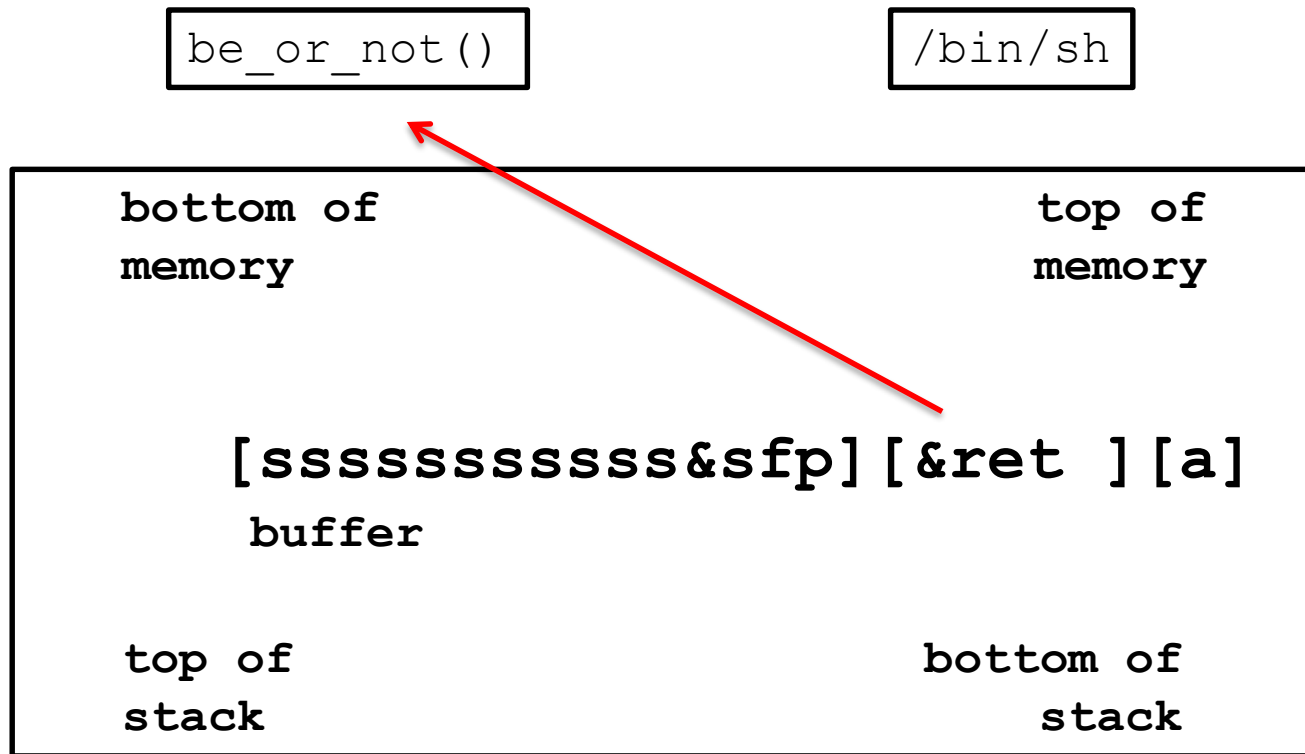
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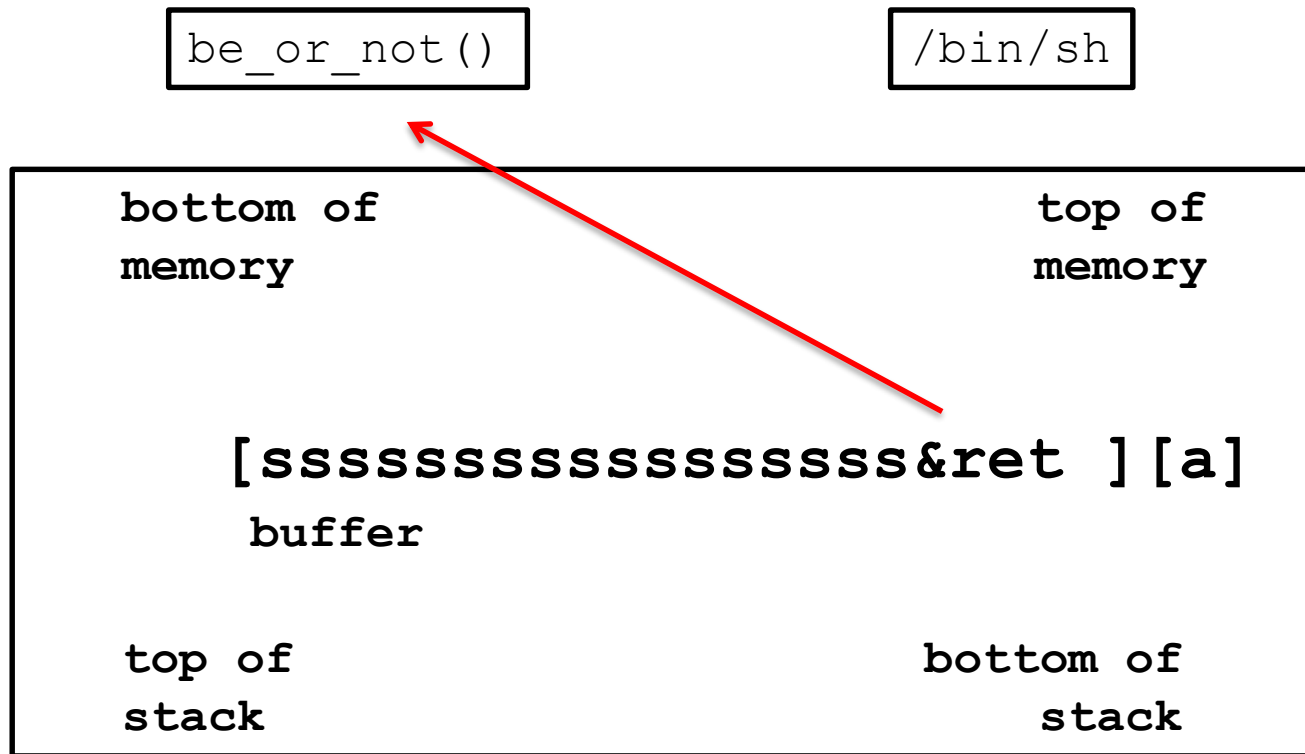
# BOF (Cont.)



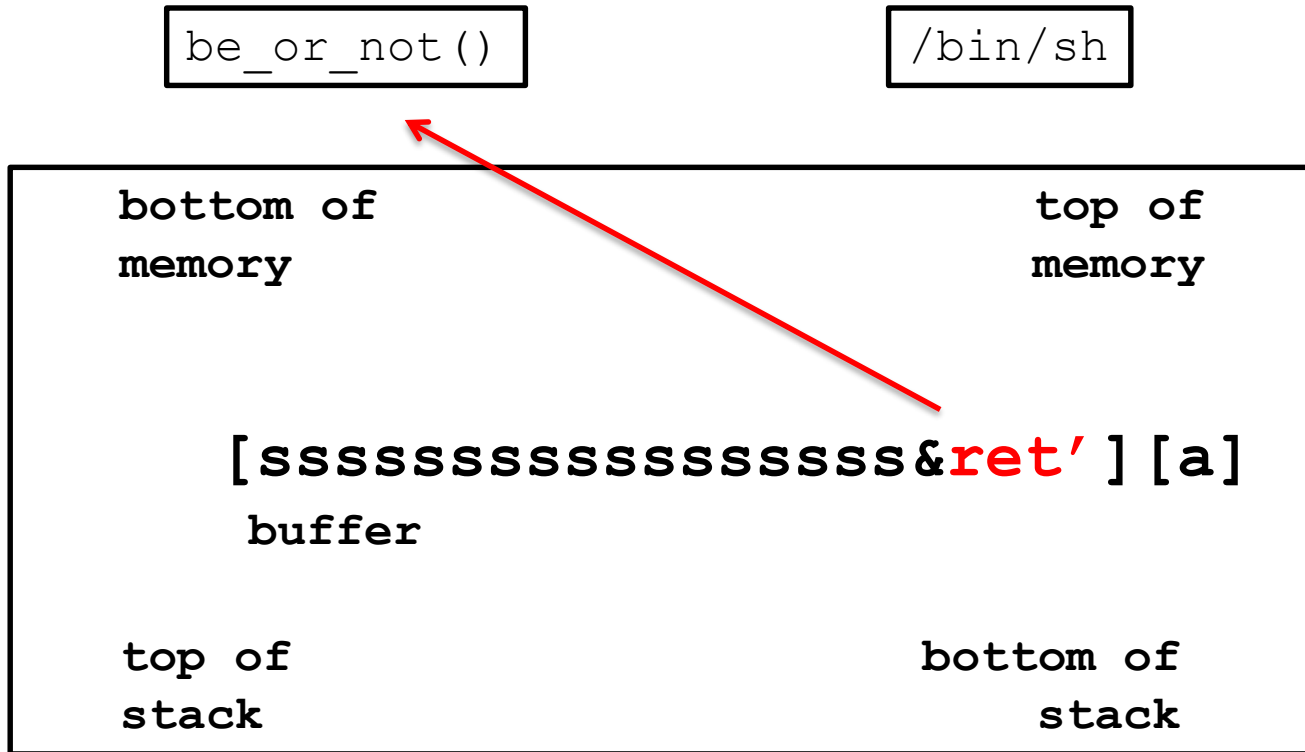
# BOF (Cont.)



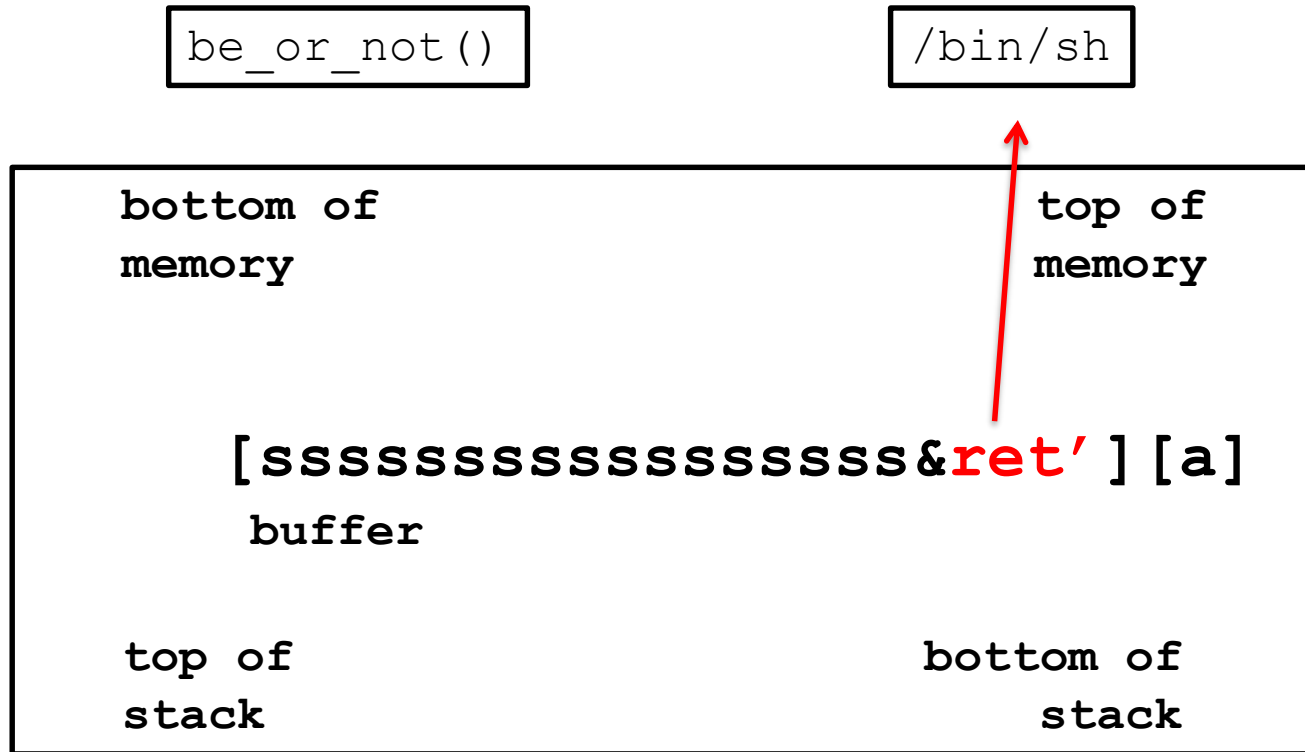
# BOF (Cont.)



# BOF (Cont.)



# BOF (Cont.)



Ok, I got it! IoT apps are written in C and then they're particularly vulnerable to BOFs.

There are a bunch of BOF prevention mechanisms out there, though.

Can't we just pick out one and apply in IoT?

No! Because they are inadequate *as-is* to IoT.

# BOF Prevention: existing proposals

- There are many proposals for BOF prevention in the context of Internet
  - E.g. `SAFECode`, `SoftBounds`, `AddressSanitizer`, etc.
- They are effective in that they protect memory accesses (`load/store`) via Array-Bound Checks



# BOF Prevention: existing proposals

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  - E.g. SAFECode, SoftBounds, AddressSanitizer
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## Problem

- They tend to slow down the programs too much
- E.g. AddressSanitizer (Serebryany et al. 2012) incurs on average 73% of overhead in a conventional machine

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- They tend to slow down the programs too much
- E.g. AddressSanitizer (Serebryany et al. 2012) incurs on average 73% of overhead in a conventional machine

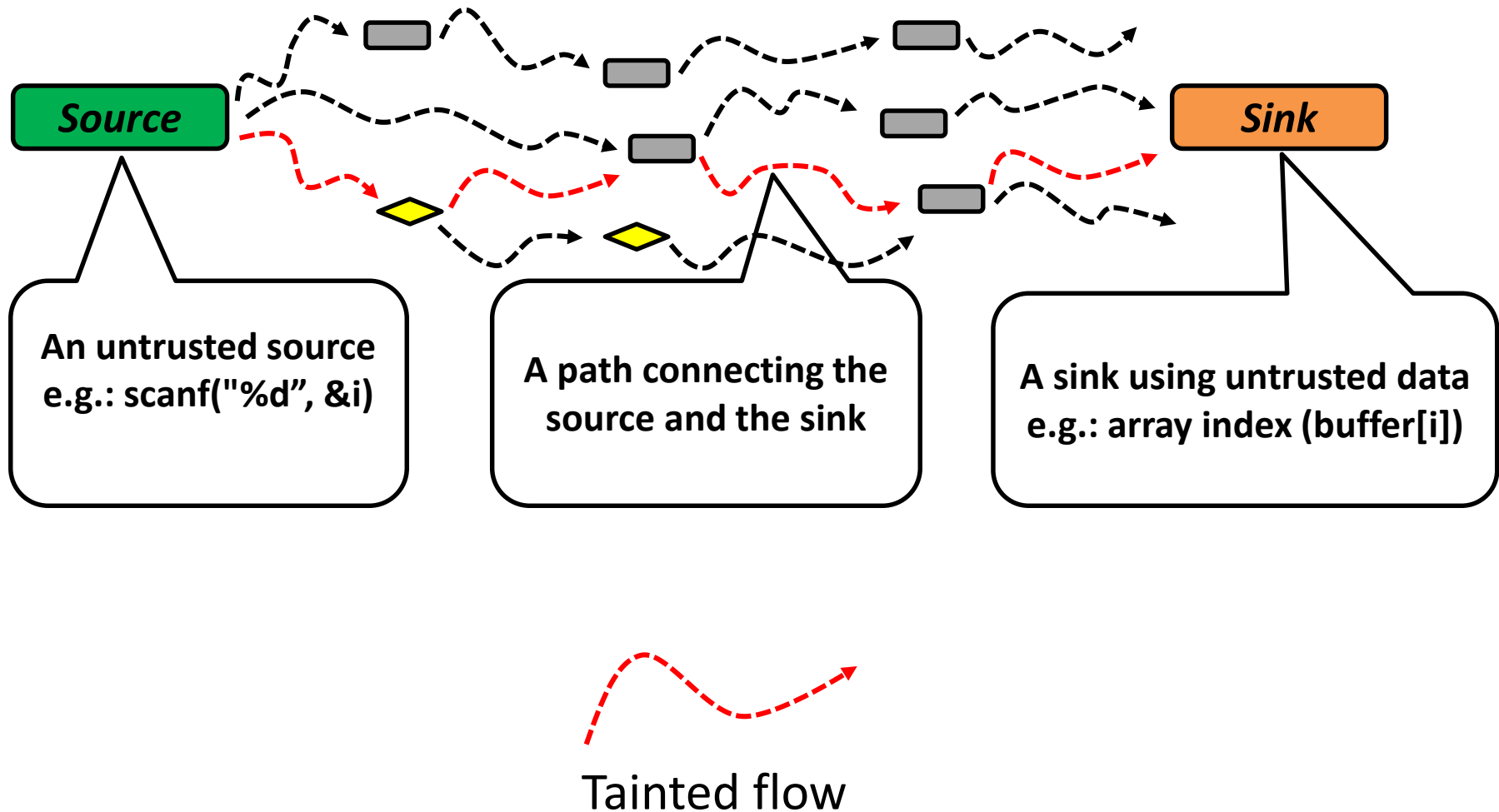
Constrained devices like *things* cannot afford this overhead

Q: How do existing proposals for preventing  
BOF work?

# How to protect code against BOFs

- Many of the existing proposals to secure code against BOFs have three phases
  1. They first find buffers reachable from untrusted sources, at compiling time

# Stage 1: buffers reachable from untrusted sources



# How to protect code against BOFs

- Many of the existing proposals to secure code against BOFs have three phases
  1. They first find buffers reachable from untrusted sources, at compiling time
  2. They thus guard buffers by inserting Array Bounds Checks (ABCs) prior to buffers use

# Stage 2: ABC insertion


## Vulnerable code

```
int main(int argc, char
**argv) {
    int buffer[BUFSIZE];
    int a,i,j;
    ...
    for(i;i<j;i++){
        ...

        buffer[i] = a;
        ...
    }
    ...
}
```

## ABC-protected code

```
int main(int argc, char
**argv) {
    int buffer[BUFSIZE];
    int a,i,j,,;
    ...
    for(i;i<j;i++){
        ...
        if((i >= 0)&&(i < BUFSIZE))
            buffer[i] = a;
        ...
    }
    ...
}
```



# How to protect code against BOFs

- Many of the existing proposals to secure code against BOFs have three phases
  1. They first find buffers reachable from untrusted sources, at compiling time
  2. They thus guard buffers by inserting Array Bounds Checks (ABCs) prior to buffers use
  3. If an ABC is not satisfied at execution time, they then abort programs



## Stage 3: Illegal memory access is aborted

```
void foo(const char *arg) {  
    char buffer[100];  
    if (strlen(arg) >= sizeof(buffer))  
        abort();  
    strcpy(buffer, arg);  
}
```



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# Goal

- Our goal is to come up with a BOF prevention mechanism tailor-made for IoT
- Solutions must therefore be
  1. Secure against BOFs
  2. Light enough to be run in battery-powered devices

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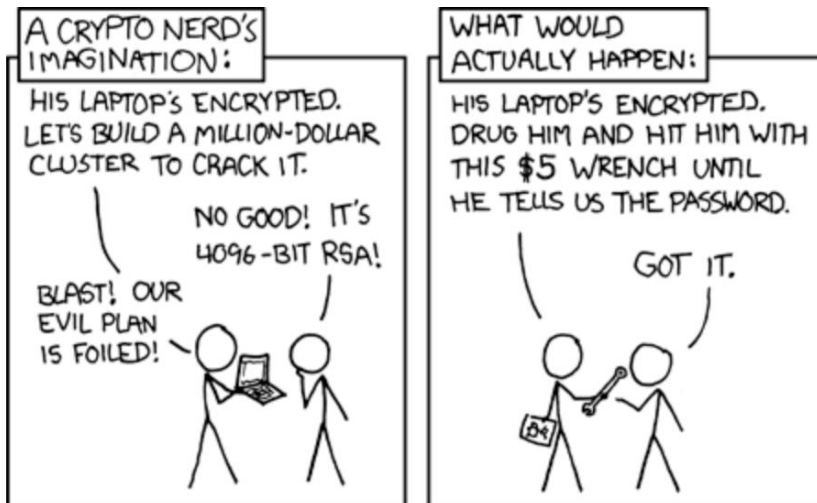
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# Assumptions/Attack Model

- Nodes run authentic programs
  - E.g. they could employ Trusted Platform Module (TPM)
- The communication channel is secure
  - Crypto solutions like DTLS (Kothmayr et al.), TinyPBC (Oliveira et al.), or SPINS (Perrig et al.) could be adopted



# Assumptions/Attack Model (Cont.)

- Attackers have control over the input data that the nodes receive from its environment
  - This includes data captured by the sensors or input from the user interfaces
  - But excludes data coming from network interfaces as we assume a secure communication channel.





# How to lose weight?

SloT challenge #1

# Idea

- Recall existing proposals find buffers reachable from (untrusted) sources
- They analyze programs of a distributed system as disjoint/independent programs
  - E.g., they end up analyzing a client and its respective server programs individually
- Therefore the list of untrusted sources include not only conventional (e.g. `get`) and network (e.g. `recv`) sources

## Idea (Cont.)

- The higher the number of untrusted sources, the higher the number of reachable arrays
- And the higher the number of reachable arrays, the higher the number of ABCs and thus the overhead

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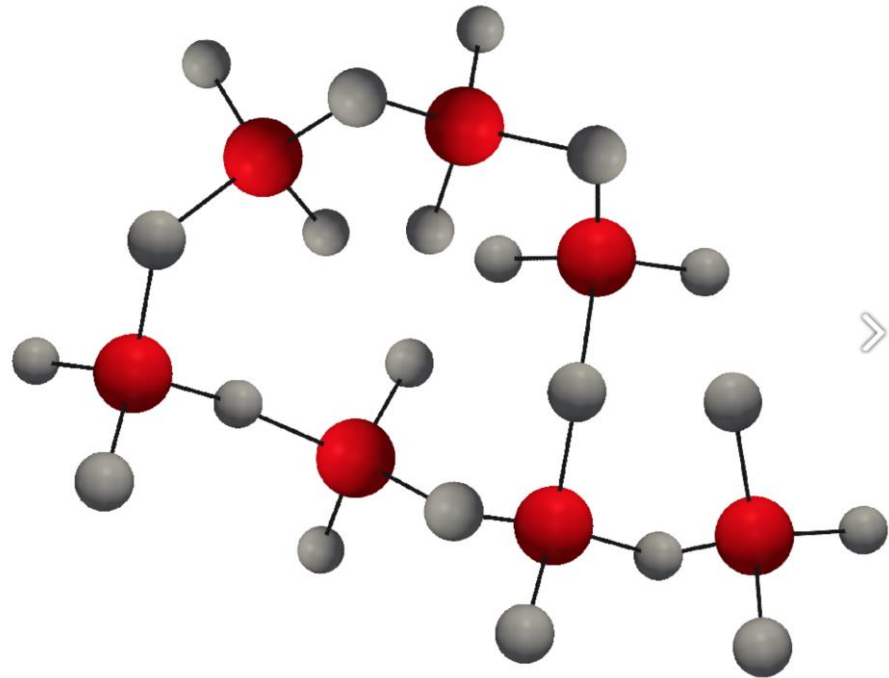
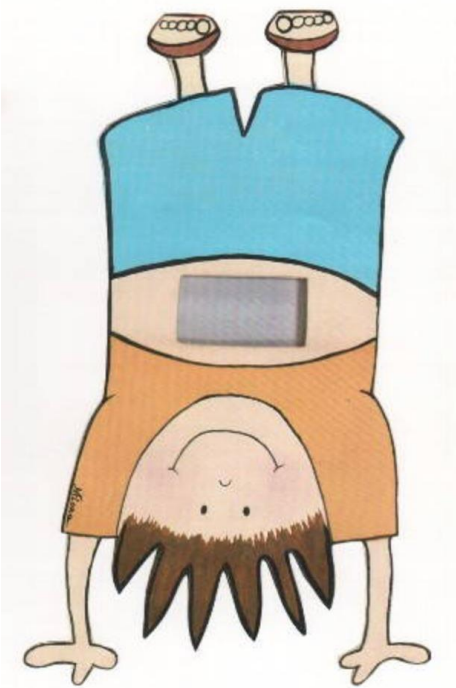
So, what if we decrease the number of untrusted sources?



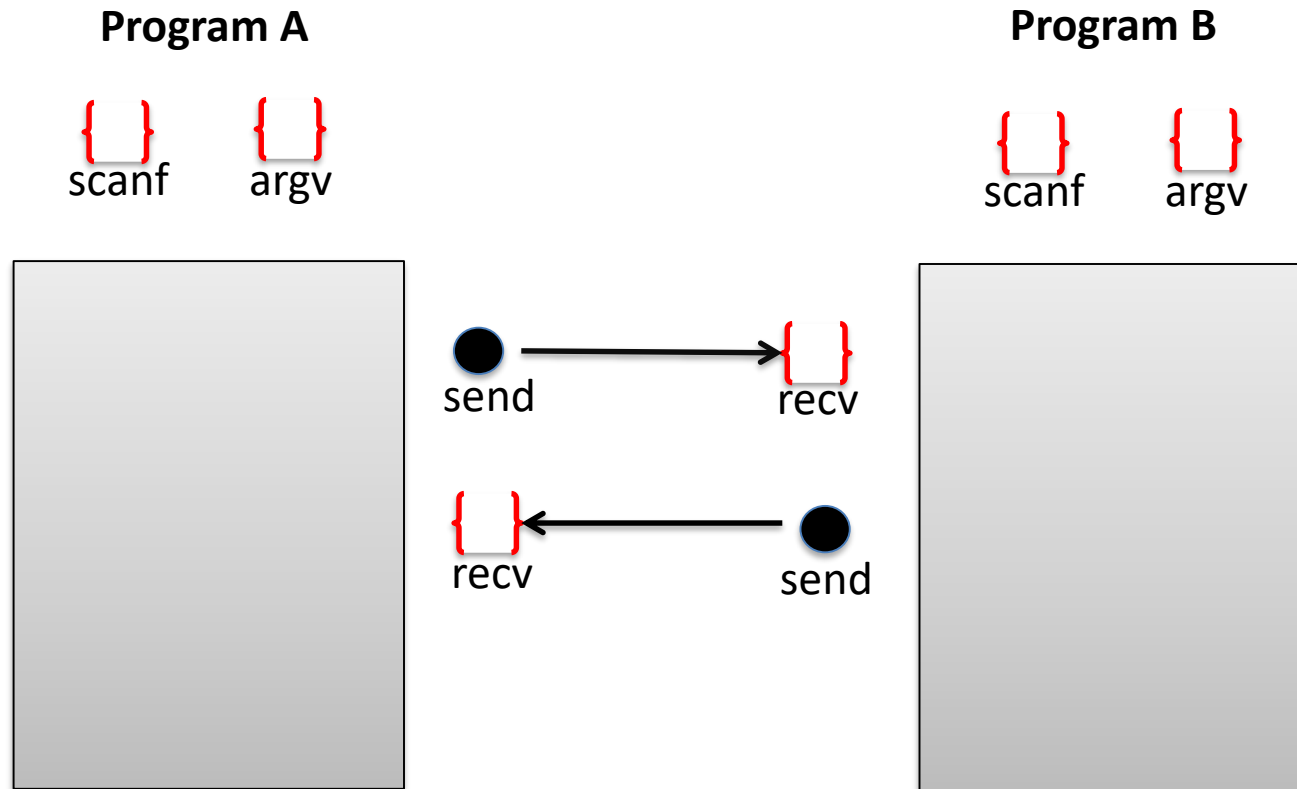
How can we turn untrusted sources into something else, though?

# SloT key contribution #1

- Look at a distributed system programs from another perspective

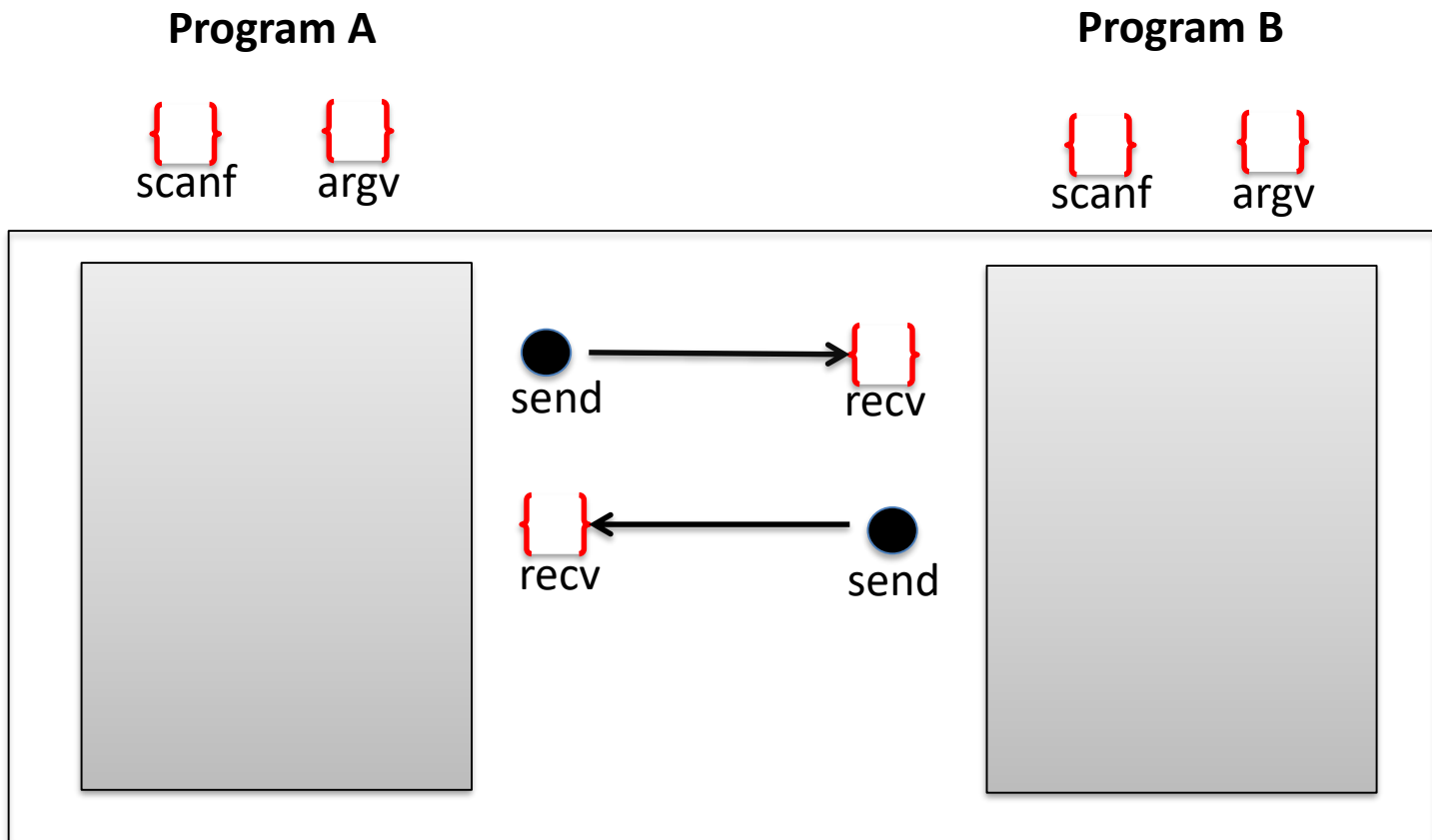


# Programs A and B: sources



# Distributed System AB: sources

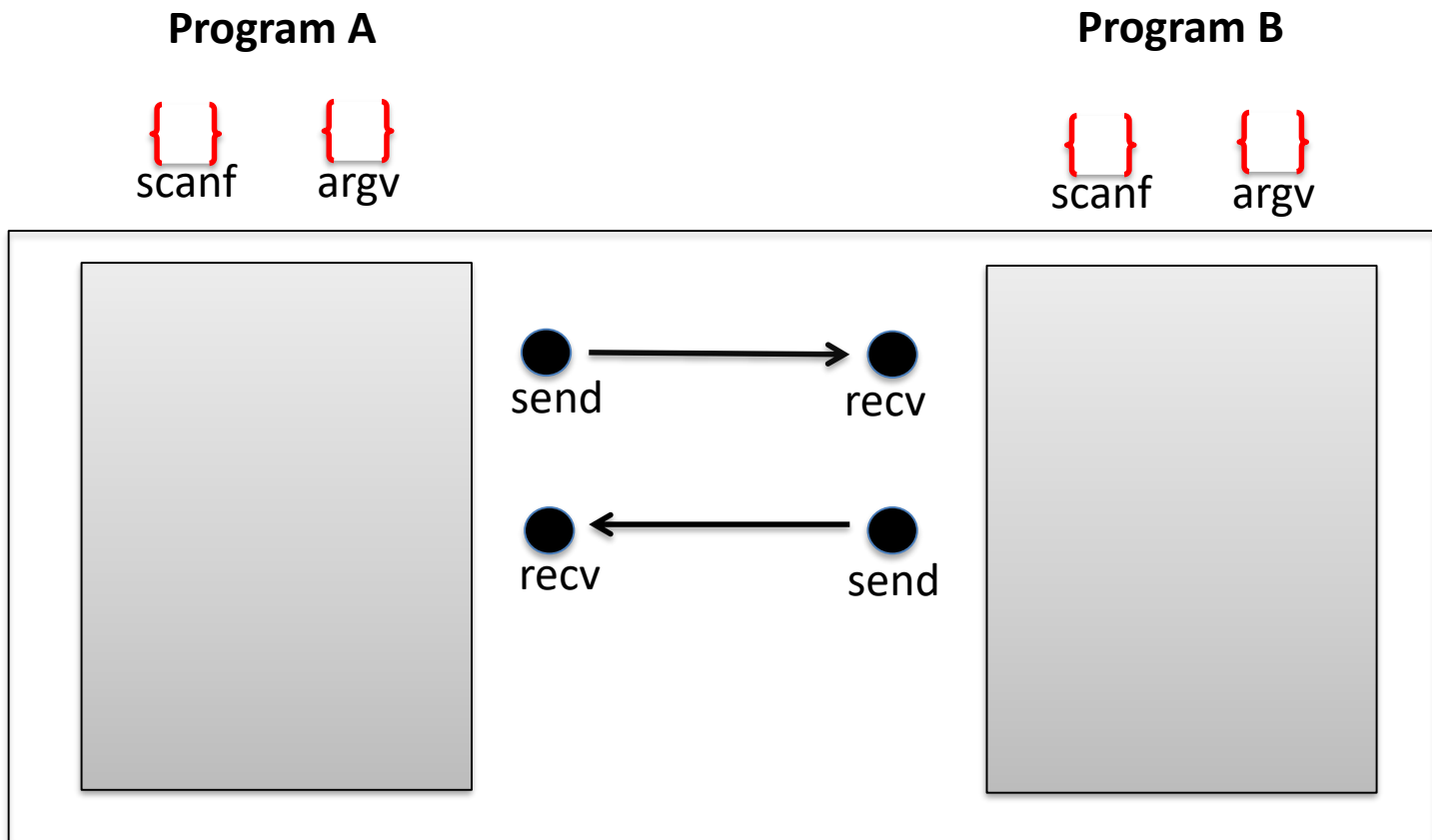
## Single System AB





# Distributed System AB: sources

## Single System AB



# Distributed System AB: sources



Single System AB

Program A

{ }  
scanf

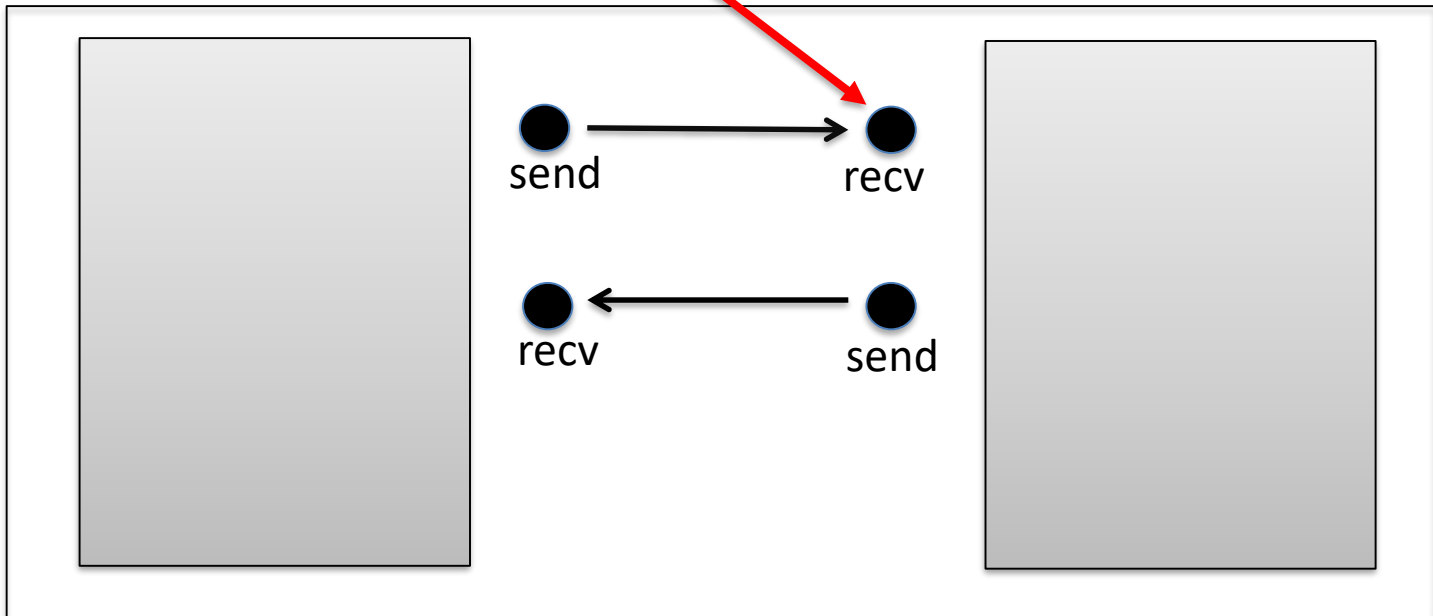
{ }  
argv

Rejected

Program B

{ }  
scanf

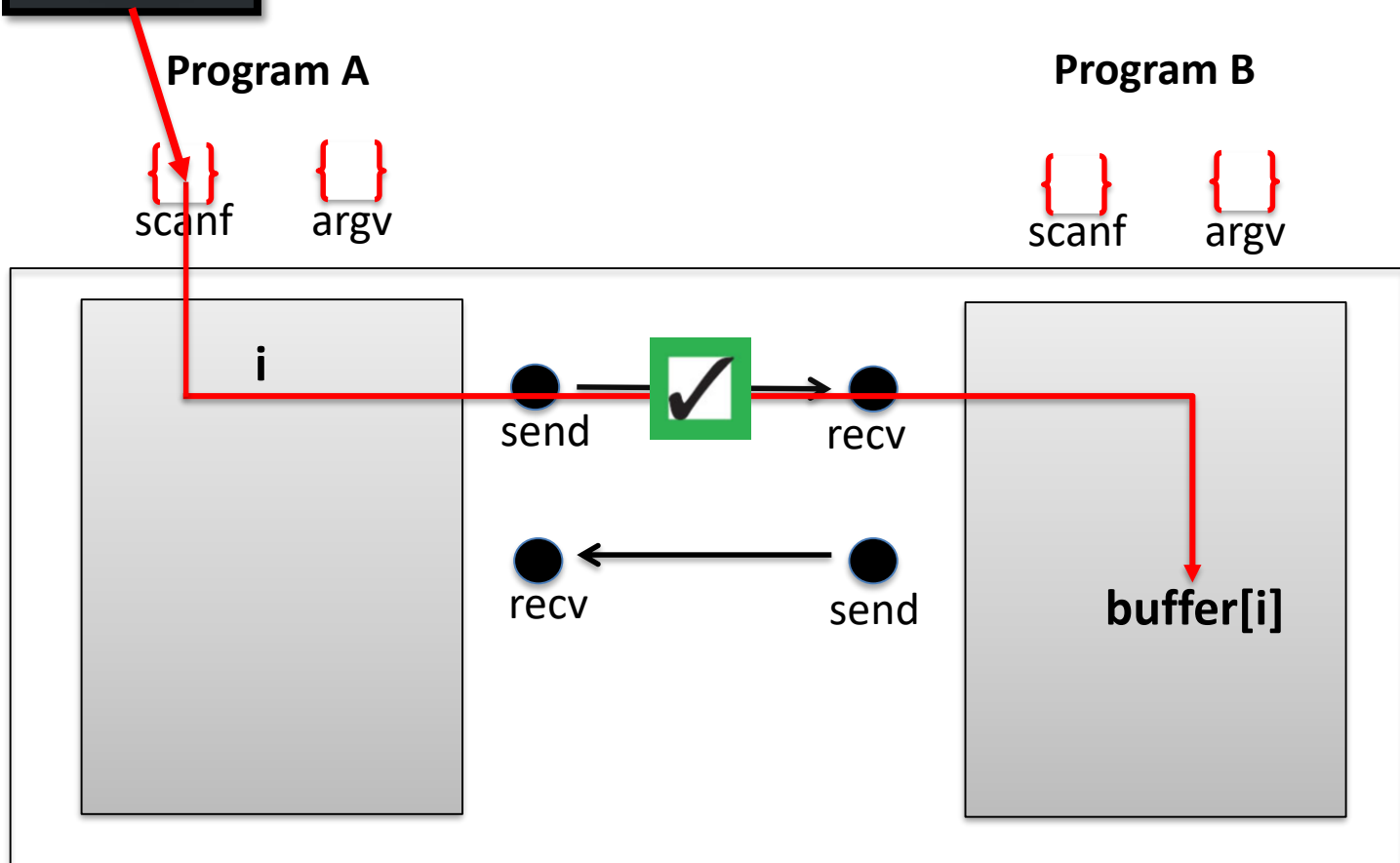
{ }  
argv



# Distributed System AB: sources



## Single System AB



# Distributed System AB

Program A

(a)

```
1 send(1);
2 ack = recv()
3 if (ack == 1) {
4     s = getc();
5     while (s != '\0') {
6         send(s)
7         ack = recv();
8         if (ack != 1) {
9             break;
10        } else {
11            s = getc();
12        }
13    }
14    send(s);
15 }
```

Program B

(b)

```
1 msg = recv();
2 if (msg == 1) {
3     send(1);
4     do {
5         msg = recv();
6         putc(msg);
7         if (msg != '\0')
8             send(1);
9         else
10            break;
11    } while (1);
12 } else {
13     send(0);
14 }
```

No longer considered a vulnerability

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# SloT challenge #2

- Face the lack of data-structures to analyze distributed systems
- Control Flow Graphs (CFGs) are the core data-structure in program analysis
- CFGs are not expressive enough to represent programs that communicate over a network, though
  - E.g., they do not handle message exchange between nodes

# SloT key contribution #2

- Distributed Control Flow Graph (DCFG)
- DCFGs are data structures able to bind together the CFGs of all individual programs that constitute a system

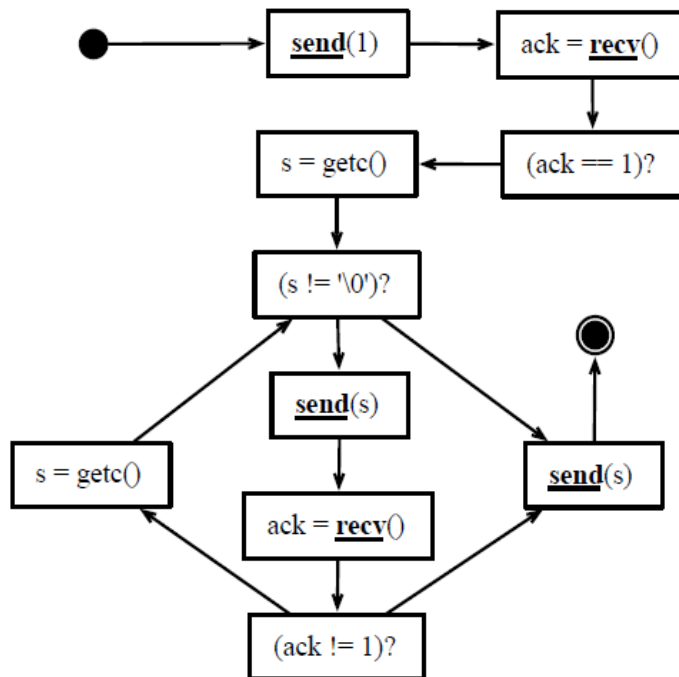
# CFG

(a)

```

1  send(1);
2  ack = recv();
3  if (ack == 1) {
4      s = getc();
5      while (s != '\0') {
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```

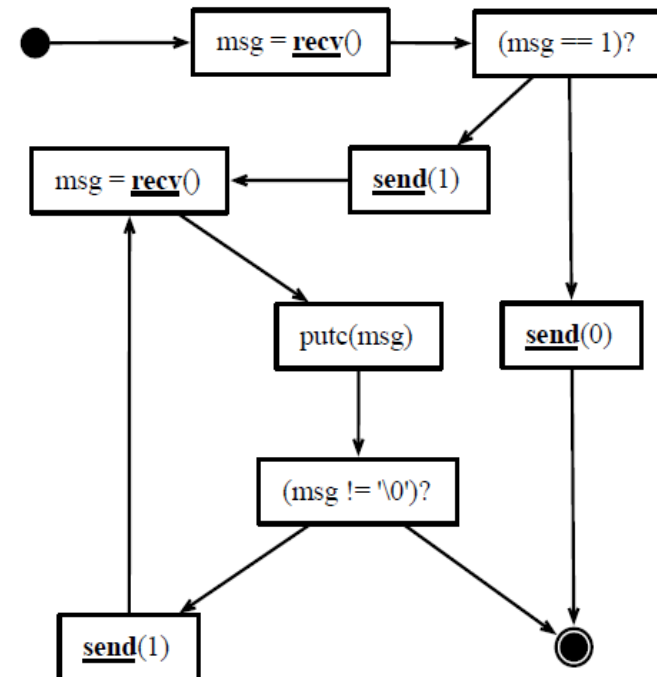


(b)

```

1  msg = recv();
2  if (msg == 1) {
3      send(1);
4      do {
5          msg = recv();
6          putc(msg);
7          if (msg != '\0')
8              send(1);
9          else
10             break;
11     } while (1);
12 } else {
13     send(0);
14 }

```





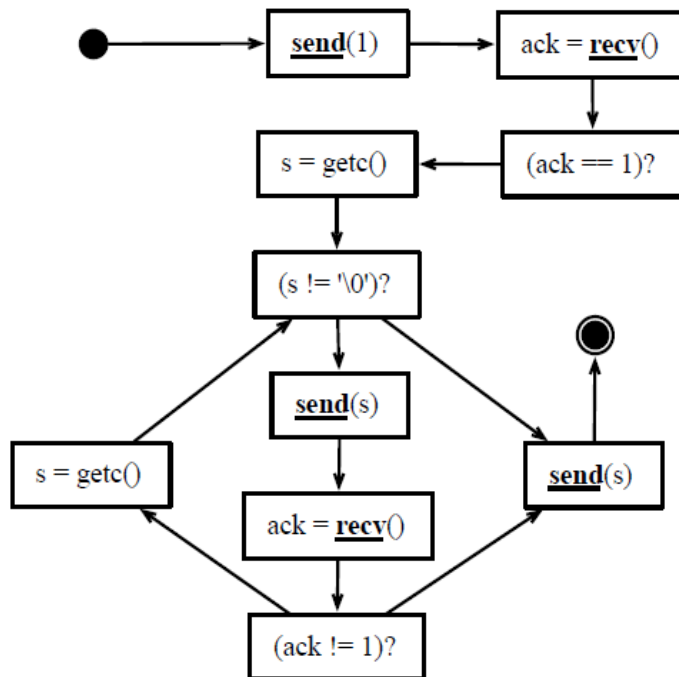
# DCFG

(a)

```

1  send(1);
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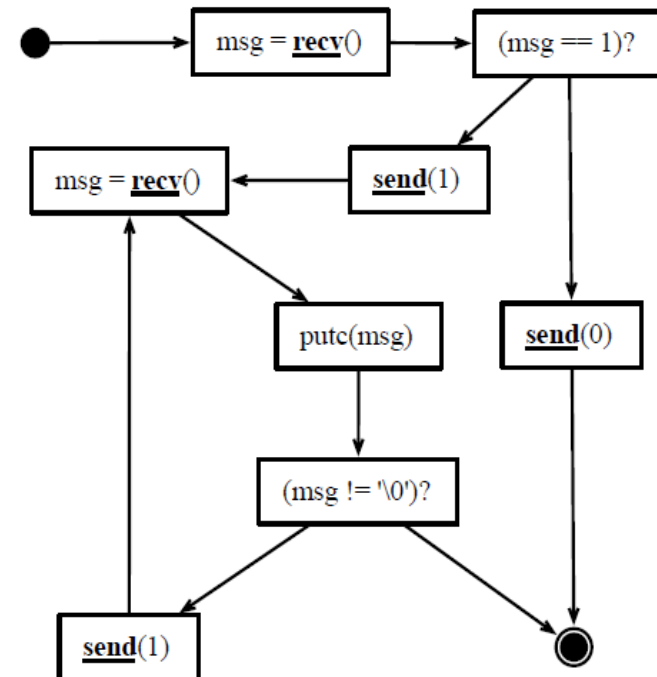


(b)

```

1  msg = recv();
2  if (msg == 1) {
3      send(1);
4      do {
5          msg = recv();
6          putc(msg);
7          if (msg != '\0')
8              send(1);
9          else
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11     } while (1);
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```



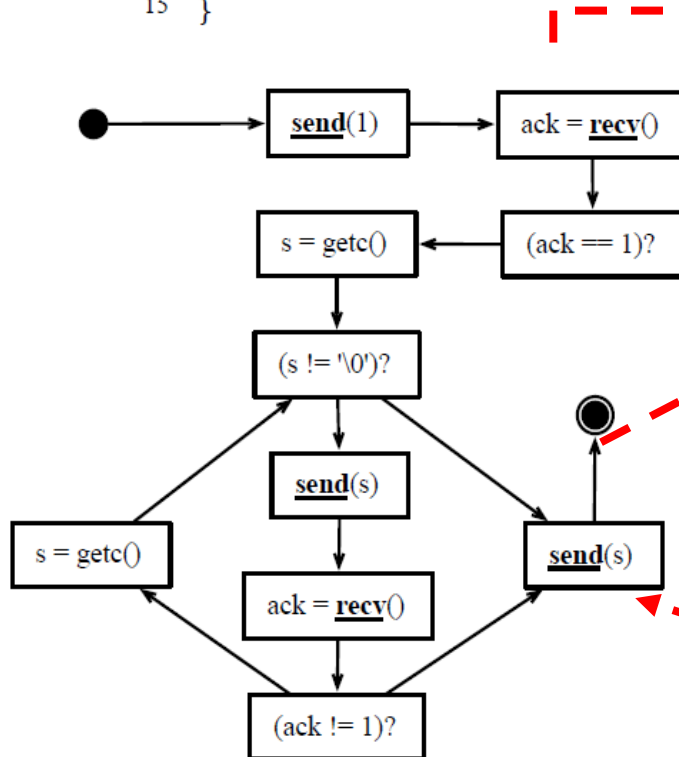
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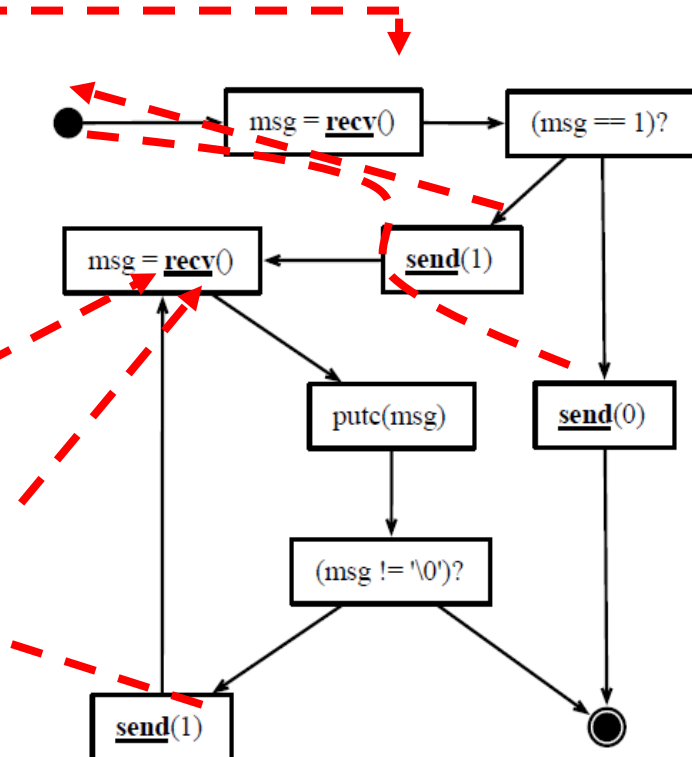


(b)

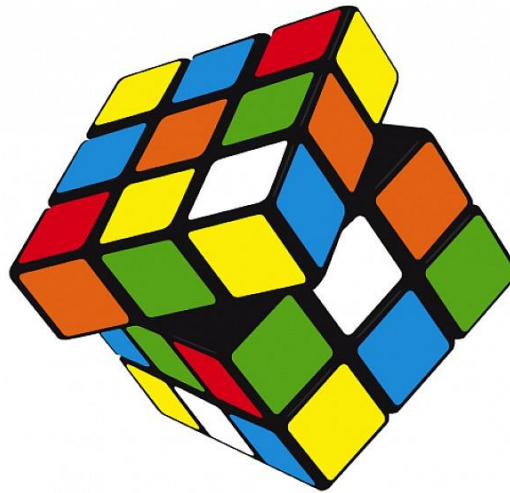
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9          else
10             break;
11     } while (1);
12 } else {
13     send(0);
14 }

```



It's not that easy, though



# SloT challenge #3

- To build a DCFG, we have to link the `sends` of a program A with the `recvs` of a program B and vice-versa

```
// node #1
n = 3
while (a^n + b^n != c^n) {
    a = update(a);
    b = update(b);
    c = update(c);
}
x = read()
```

?

```
// node #2
write(y);
```

How to find out which `sends` link to a `recv`?

# SloT key contribution #3

- Elevator, an algorithm to selectively link `sends/recvs`
  1. Elevator assigns levels to `sends` and `recvs`
  2. Program A's `sends` and Program B's `recvs` in the same level are thus linked together

# Elevator: Illustration

- Consider the Echo Client and Server programs

(a) Echo Client

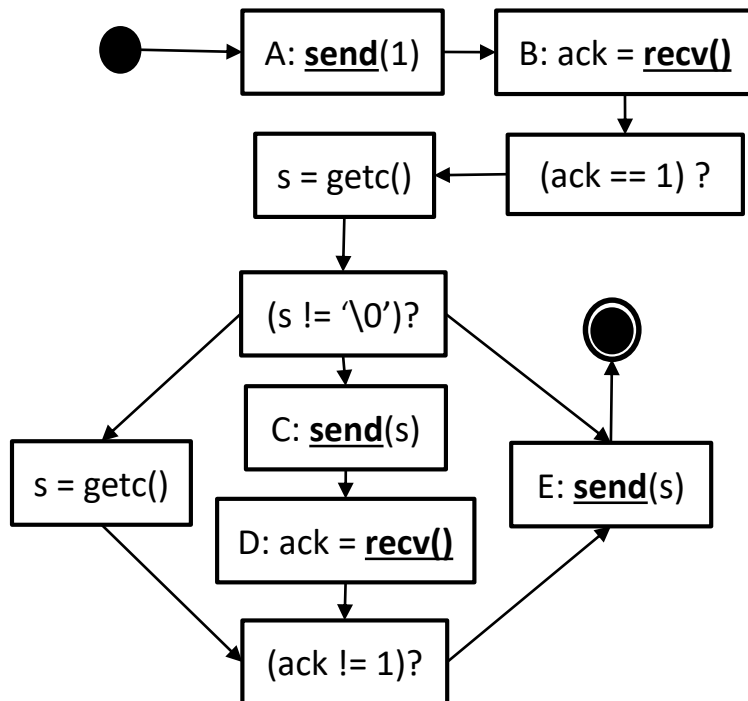
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12        }
13    }
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15 }
```

(b) Echo Server

```
1 msg = recv();
2 if (msg == 1) {
3     send(1);
4     do {
5         msg = recv();
6         putc(msg);
7         if (msg != '\0')
8             send(1);
9         else
10            break;
11    } while (1);
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```

# Echo Client CFG

CFG - Echo Client



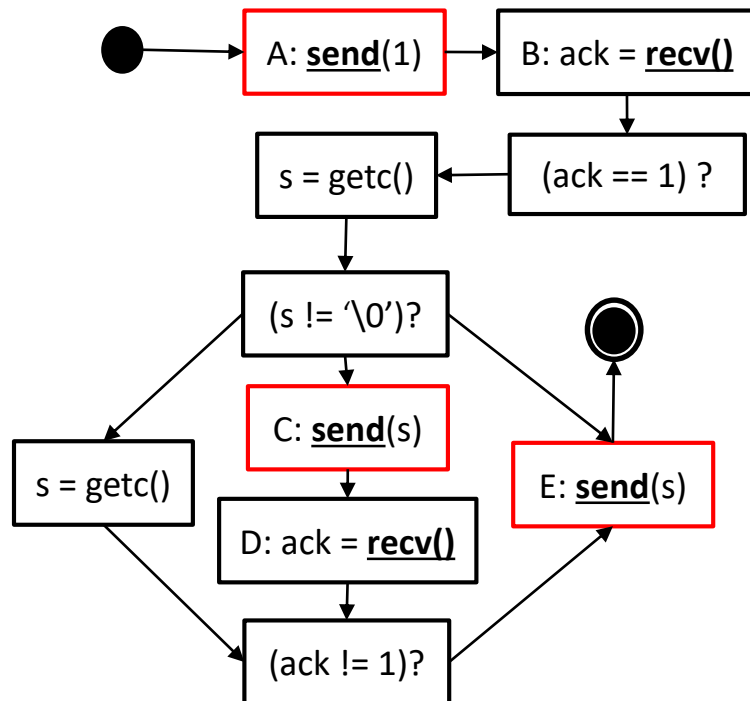
(a) Echo Client

```

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4      s = getc();
5      while (s != '\0') {
6          send(s)
7          ack = recv();
8          if (ack != 1) {
9              break;
10         } else {
11             s = getc();
12         }
13     }
14     send(s);
15 }
  
```

# Extract Echo Client's Send-Graph

CFG - Echo Client



(a) Echo Client

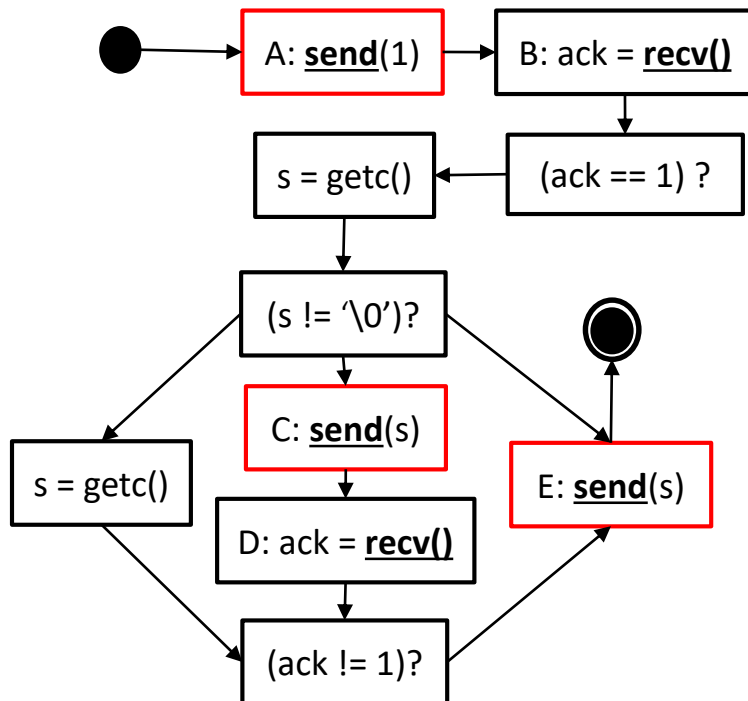
```

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4      s = getc();
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6          send(s)
7          ack = recv();
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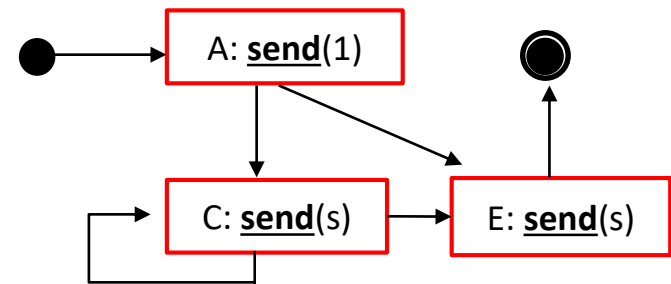


# Extract Echo Client's Send-Graph

CFG - Echo Client

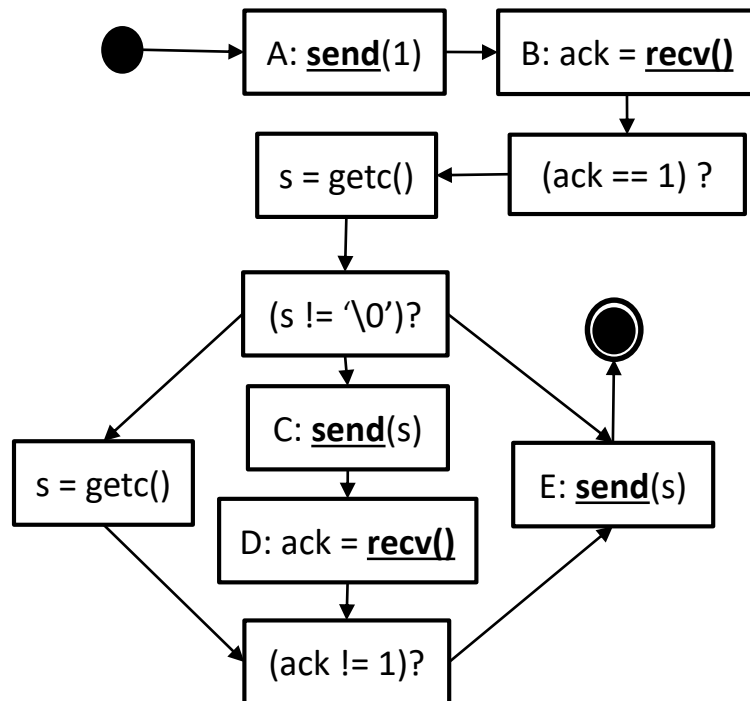


SG – Send-Graph

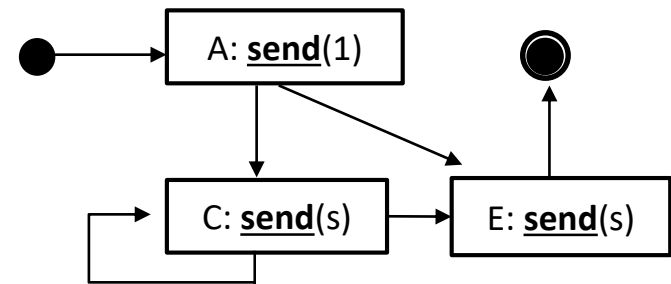


# Extract Echo Client's Receive-Graph

CFG - Echo Client

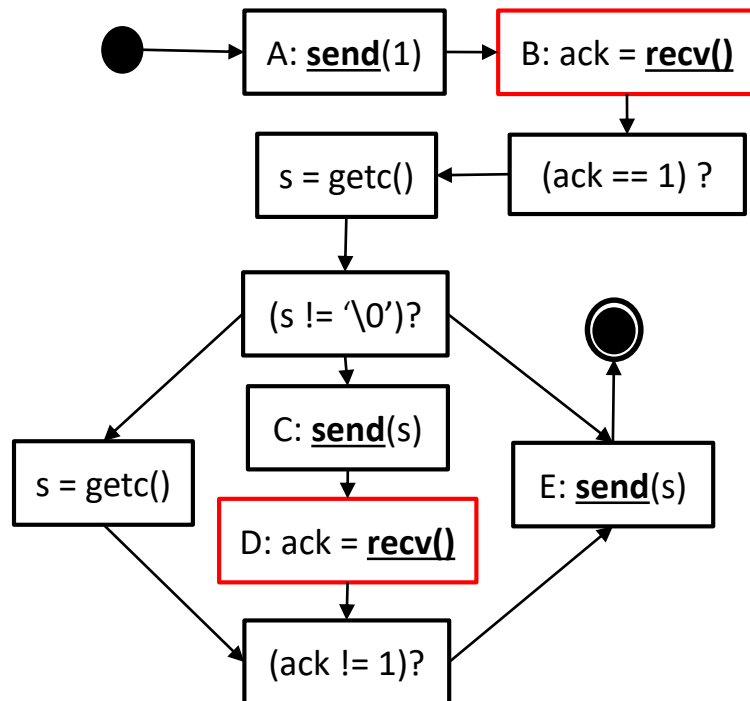


SG - Send-Graph

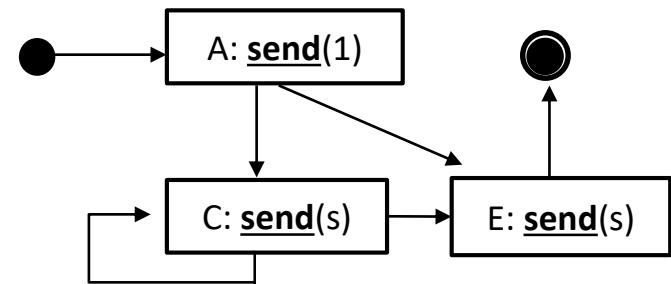


# Extract Echo Client's Receive-Graph

CFG - Echo Client

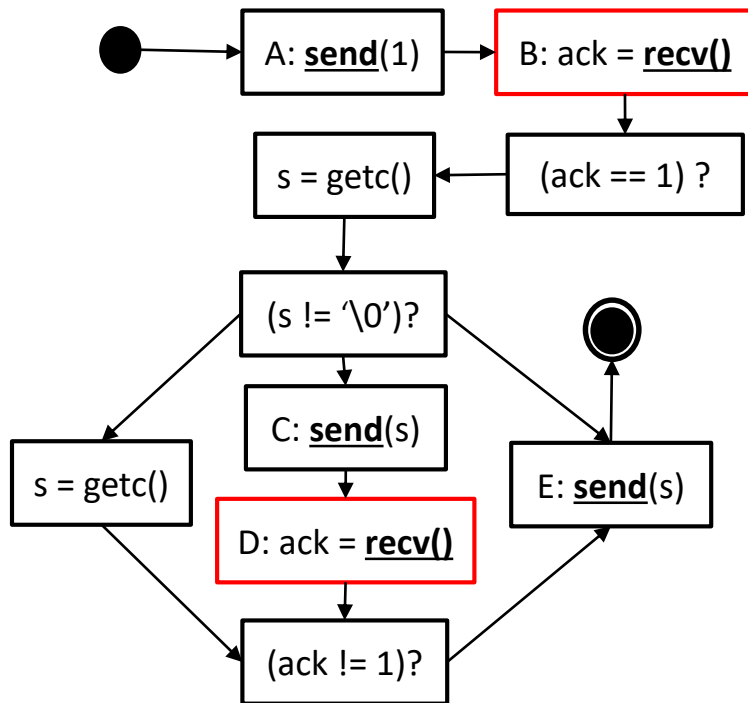


SG - Send-Graph

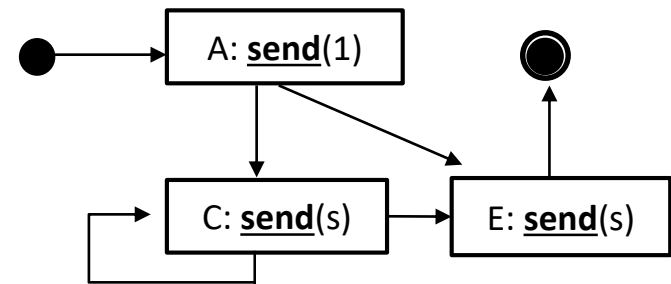


# Extract Echo Client's Receive-Graph

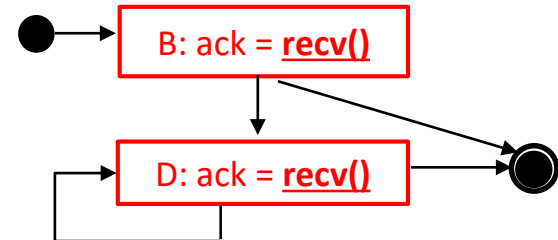
CFG - Echo Client



SG - Send-Graph

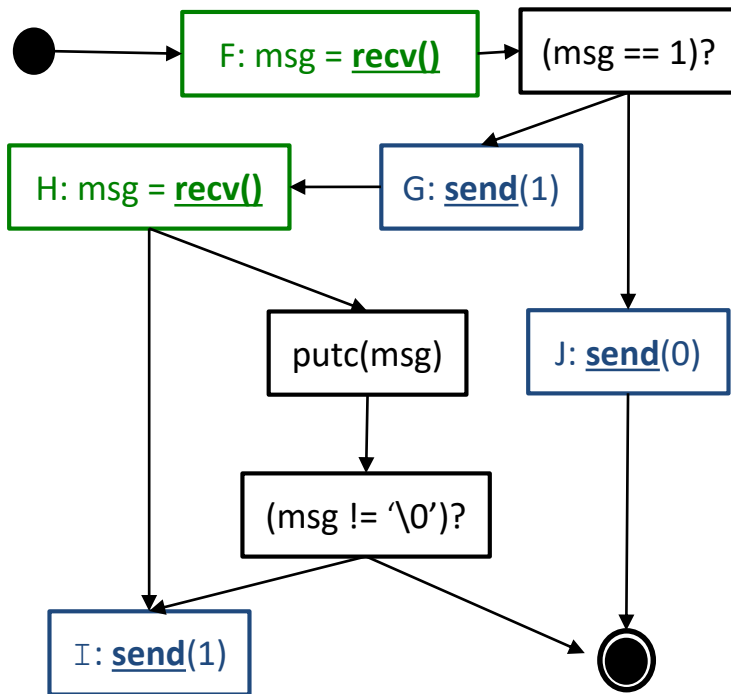


RG - Receive-Graph

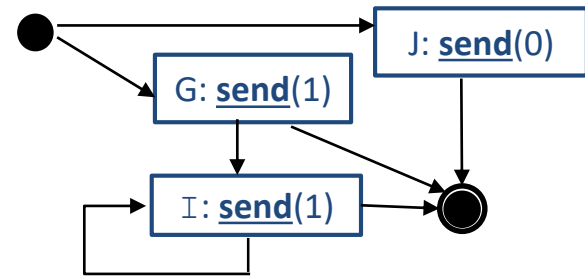


# Ditto for Echo Server

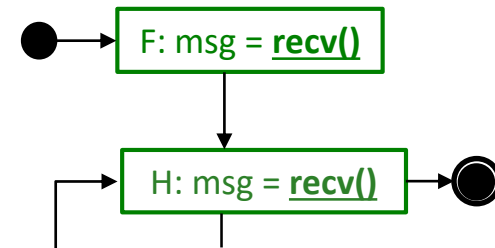
CFG - Echo Server



SG - Send-Graph

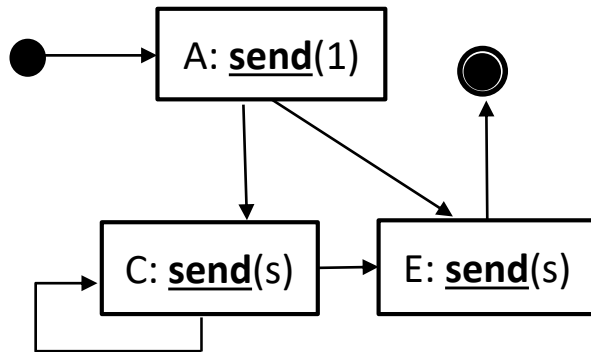


RG - Receive-Graph



# Level Assignment

Echo Client: Send-Graph

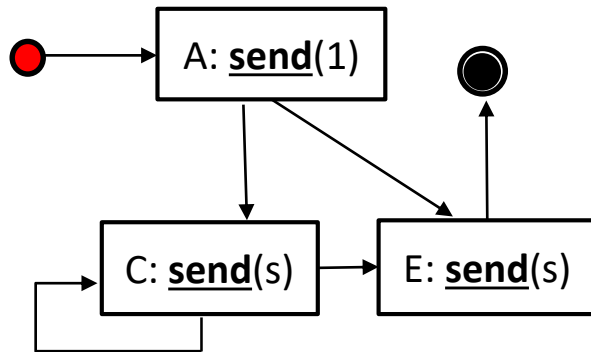


```
Elevator (Graph G) /* toy version*/
  start.level := 0
  While { sets are different }
    For each vertex v in G
      If v is reachable from u
        then v.level := (u.level+1)
      end
    end
  end
end
```

$$\begin{aligned} level(mg, 0) &= \{start\} \\ level(mg, n) &= \{v \mid \overrightarrow{uv} \in mg \wedge u \in level(mg, n-1)\} \end{aligned}$$

# Level Assignment

SG – Echo Client



Level of Senders:

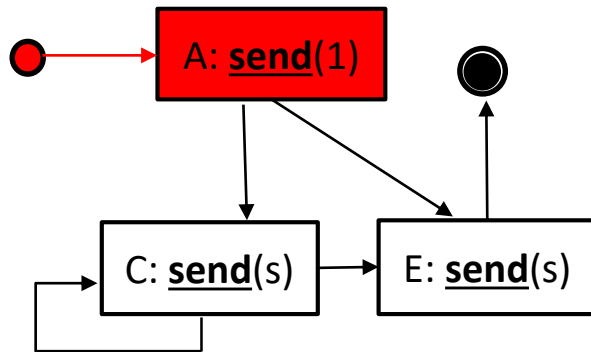
*level*      *set*

**0**      **{ start }**

```
Elevator (Graph G) /* toy version */
  start.level := 0
  While { sets are different }
    For each vertex v in G
      If v is reachable from u
        then v.level := (u.level+1)
      end
    end
  end
end
```

# Level Assignment

Echo Client: Send-Graph



Level of Senders:

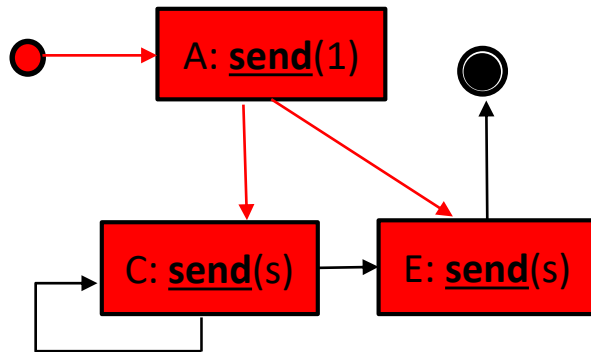
<i>level</i>	<i>set</i>
0	{ start }
1	{ A }

```
Elevator (Graph G) /* toy version */
  start.level := 0
  While { sets are different }
    For each vertex v in G
      If v is reachable from u
        then v.level := (u.level+1)
      end
    end
  end
end
```



# Level Assignment

Echo Client: Send-Graph



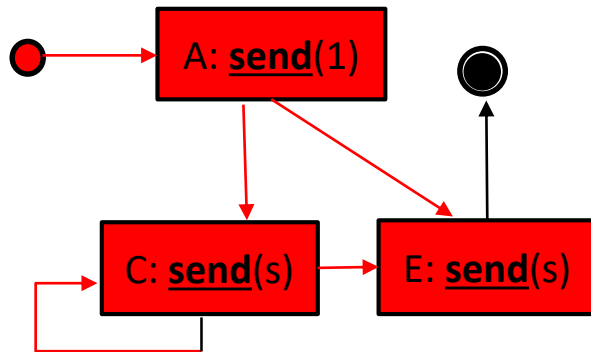
Level of Senders:

<i>level</i>	<i>set</i>
0	{ start }
1	{ A }
2	{ C, E }

```
Elevator (Graph G) /* toy version */
  start.level := 0
  While { sets are different }
    For each vertex v in G
      If v is reachable from u
        then v.level := (u.level+1)
      end
    end
  end
end
```

# Level Assignment

Echo Client: Send-Graph



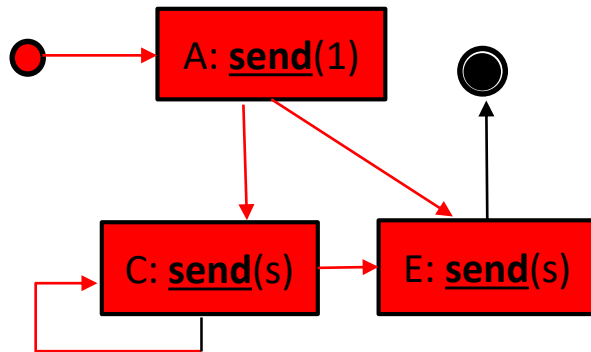
Level of Senders:

<i>level</i>	<i>set</i>
0	{ start }
1	{ A }
2	{ C, E }
3	{ C, E }

```
Elevator (Graph G) /* toy version */
  start.level := 0
  While { sets are different }
    For each vertex v in G
      If v is reachable from u
        then v.level := (u.level+1)
      end
    end
  end
end
```

# Level Assignment

Echo Client: Send-Graph



Level of Senders:

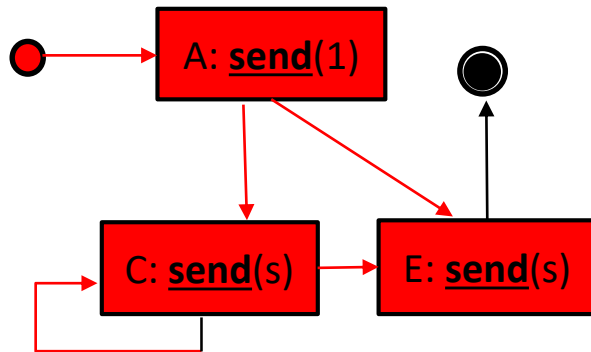
<i>level</i>	<i>set</i>
0	{ start }
1	{ A }
2	{ C, E }
3	{ C, E }

```
Elevator (Graph G) /* toy version */
  start.level := 0
  While { sets are different }
    For each vertex v in G
      If v is reachable from u
        then v.level := (u.level+1)
      end
    end
  end
end
```

the algorithm halts whenever sets stop changing

# Level Assignment

Echo Client: Send-Graph



Level of Senders:

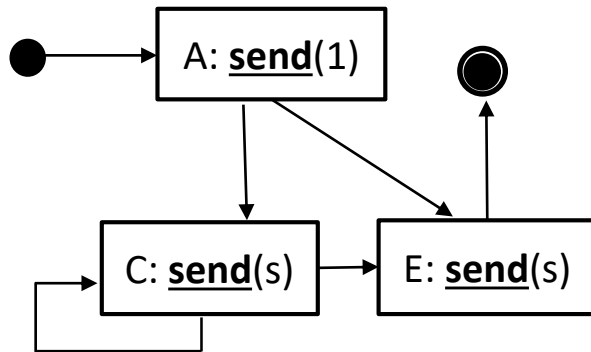
<i>level</i>	<i>set</i>
0	{ start }
1	{ A }
2	{ C, E }
3	{ C, E }

```

Elevator (Graph G) /* toy version*/
  start.level := 0
  While { sets are different }
    For each vertex v in G
      If v is reachable from u
        then v.level := (u.level+1)
      end
    end
  end
end
  
```

# Level Assignment: Ditto for Recv-Graph

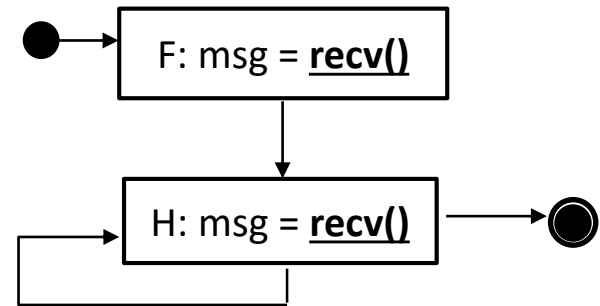
Echo Client: Send-Graph



Level of Senders:

<i>level</i>	<i>set</i>
0	{ start }
1	{ A }
2	{ C, E }
3	{ C, E }

Echo Server: Recv-Graph

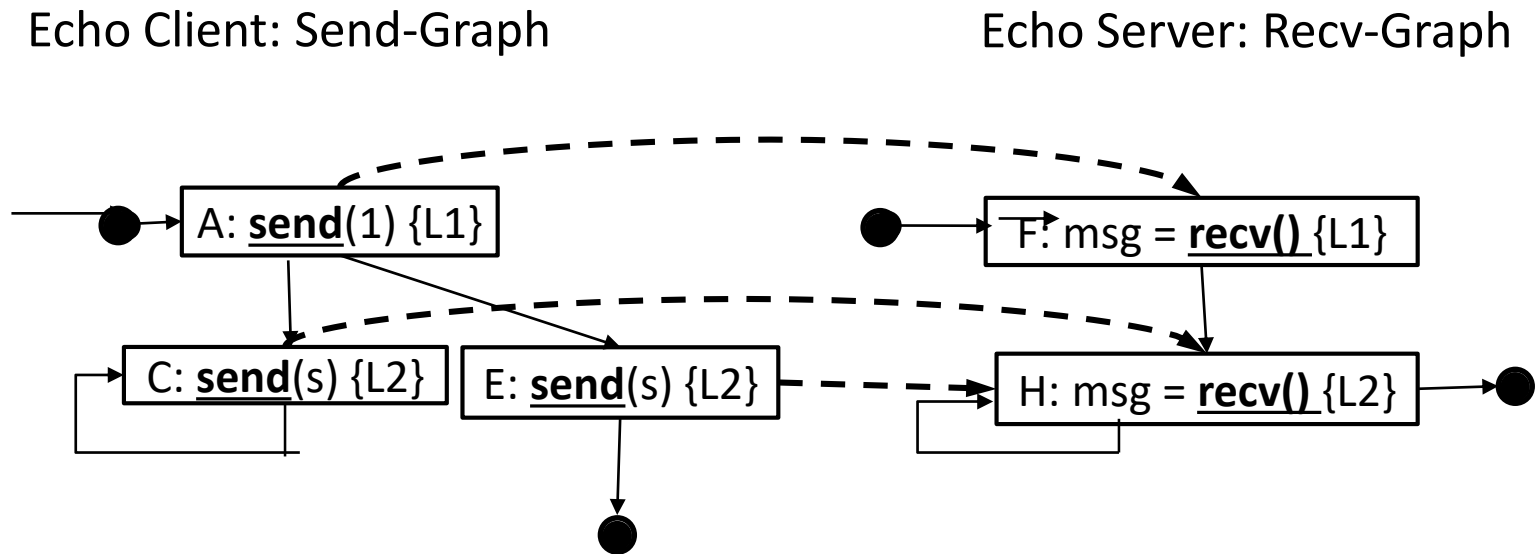


Level of Receivers:

<i>level</i>	<i>set</i>
0	{ root }
1	{ F }
2	{ H }
3	{ H }

# DCFG construction final step

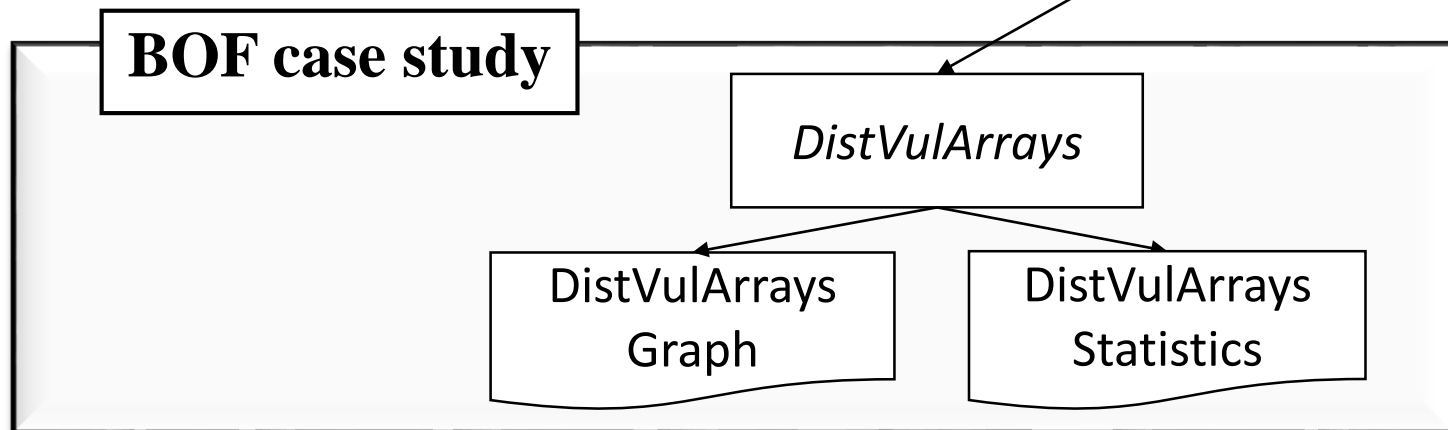
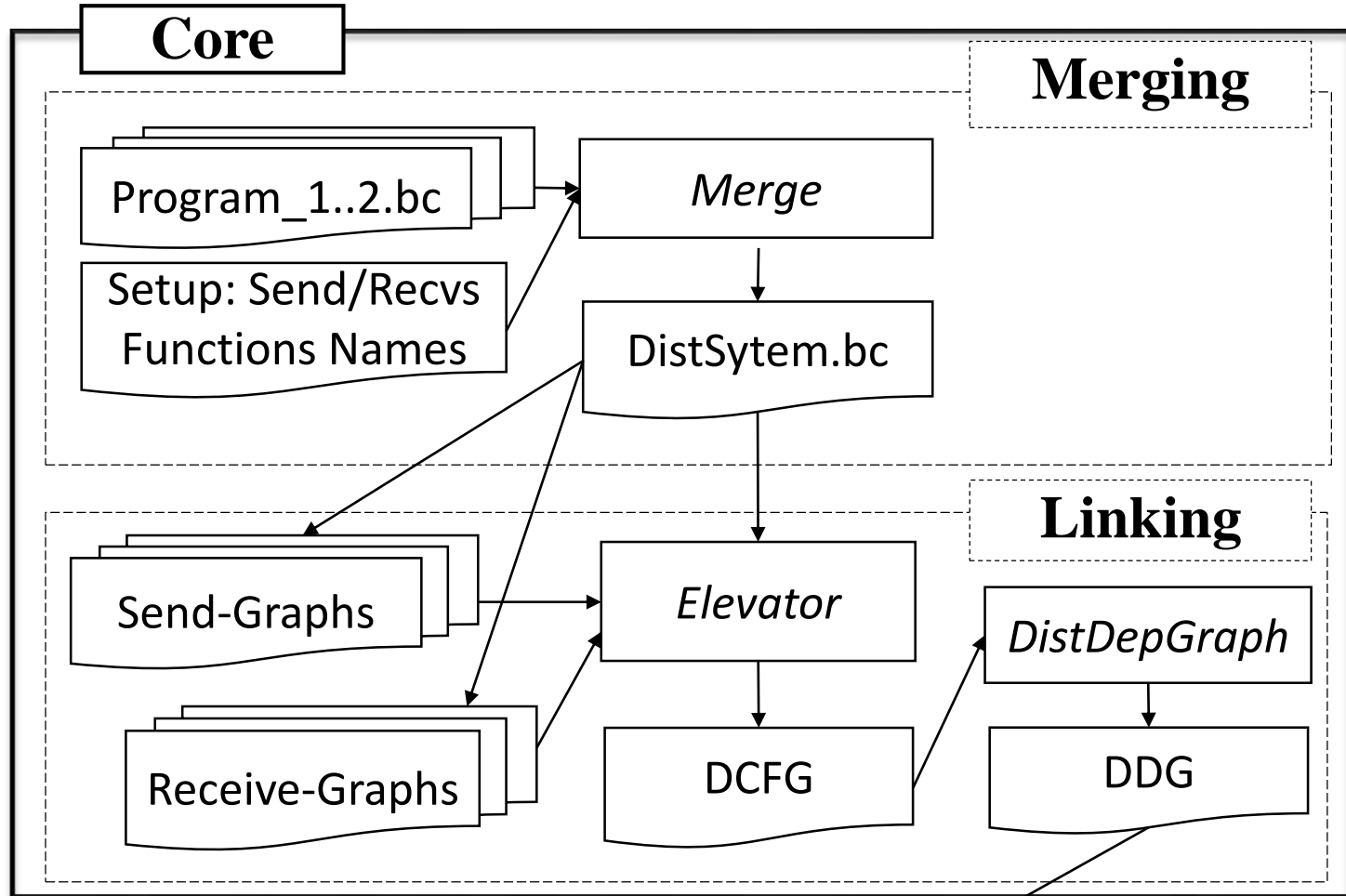
- Link Client's `sends` with Server's `recvs` if they are belong to the same level, and vice-versa



# Agenda

- Introduction
- Goal
- **Solution**
  - Conception
  - Refinement
  - **Development**
- Results
- Conclusion

# SloT Coding





# SloT is publicly available



ecosoc

Software security with low energy consumption

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**Wiki**

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## ★ SloT

*SloT is a framework to analyze networked systems.*

Updated Feb 11, 2015 by [teixeiraci](#)

## SloT

SloT is a framework to analyze networked systems. SloT's key insight is to look at a distributed system as a single body, and not as separate programs that exchange messages. By doing so, we can crosscheck information inferred from different nodes. This crosschecking increases the precision of traditional static analyses. To construct this global view of a distributed system we introduce a novel algorithm that discovers inter-program links efficiently. Such links lets us build a holistic view of the entire network, a knowledge that we can thus forward to a traditional tool. SloT was implemented on top of [LLVM](#).

Access the SloT [code](#), see the [README](#) to getting start and enjoy it!

<https://code.google.com/p/ecosoc/wiki/SloT>

# Agenda

- Introduction
- Goal
- Solution
- **Results**
- Conclusion

# Evaluation

- We have compared SloT against the state-of-the-art approach
  - Tainted flow analysis followed by ABCs insertion
  - We called this approach *Baseline*
  - Our hypothesis was that SloT would insert less ABCs than Baseline and thus end up being more efficient
- We have used real IoT code in our evaluation
  - I.e., ContikiOS applications



# SloT Static Analysis

- It takes on average 66s and consumed 170 MB of RAM
  - In a Intel Core i7 2.2GHz laptop
  - Memory obtained via Valgrind
  - Time taken through Unix time
- It's done offline and does not represent a burden to nodes

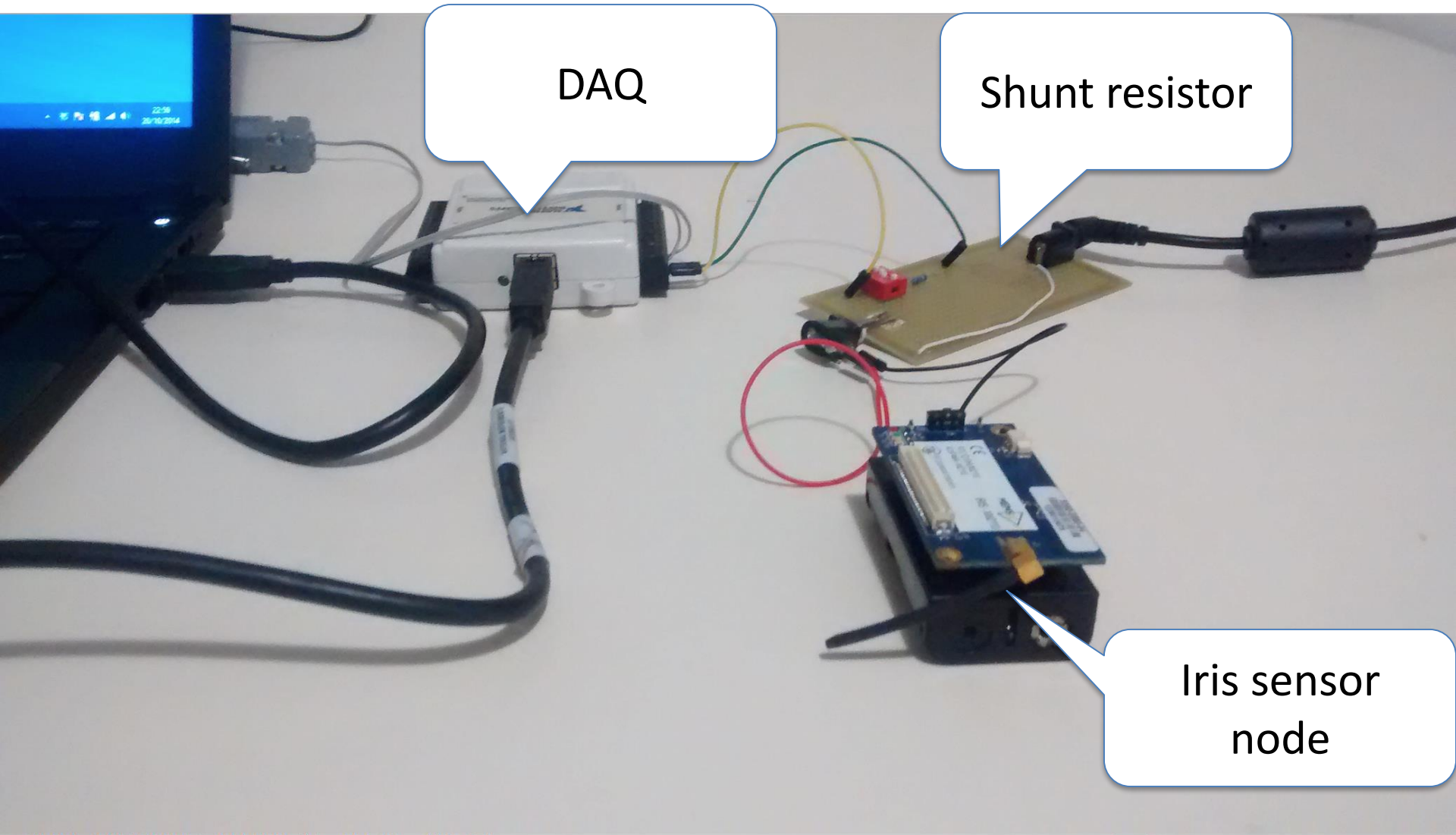
Application	Instructions	Time (s)	Memory (MB)
netdb client/server	57,877	66.24	210.03
ping / new-ipv6	47,422	63.58	167.36
ipv6-rpl-collect udp-sender/sink	48,800	80.08	173.37
ipv6-rpl-udp client/server	48,226	66.31	169.90
udp-ipv6 client/server	48,800	80.08	167.39
coap-client / rest-server	51,258	54.36	179.68

# ABCs Insertion

- SIoT reduces the number of ABCs insertion by around 10x compared to Baseline in our benchmark

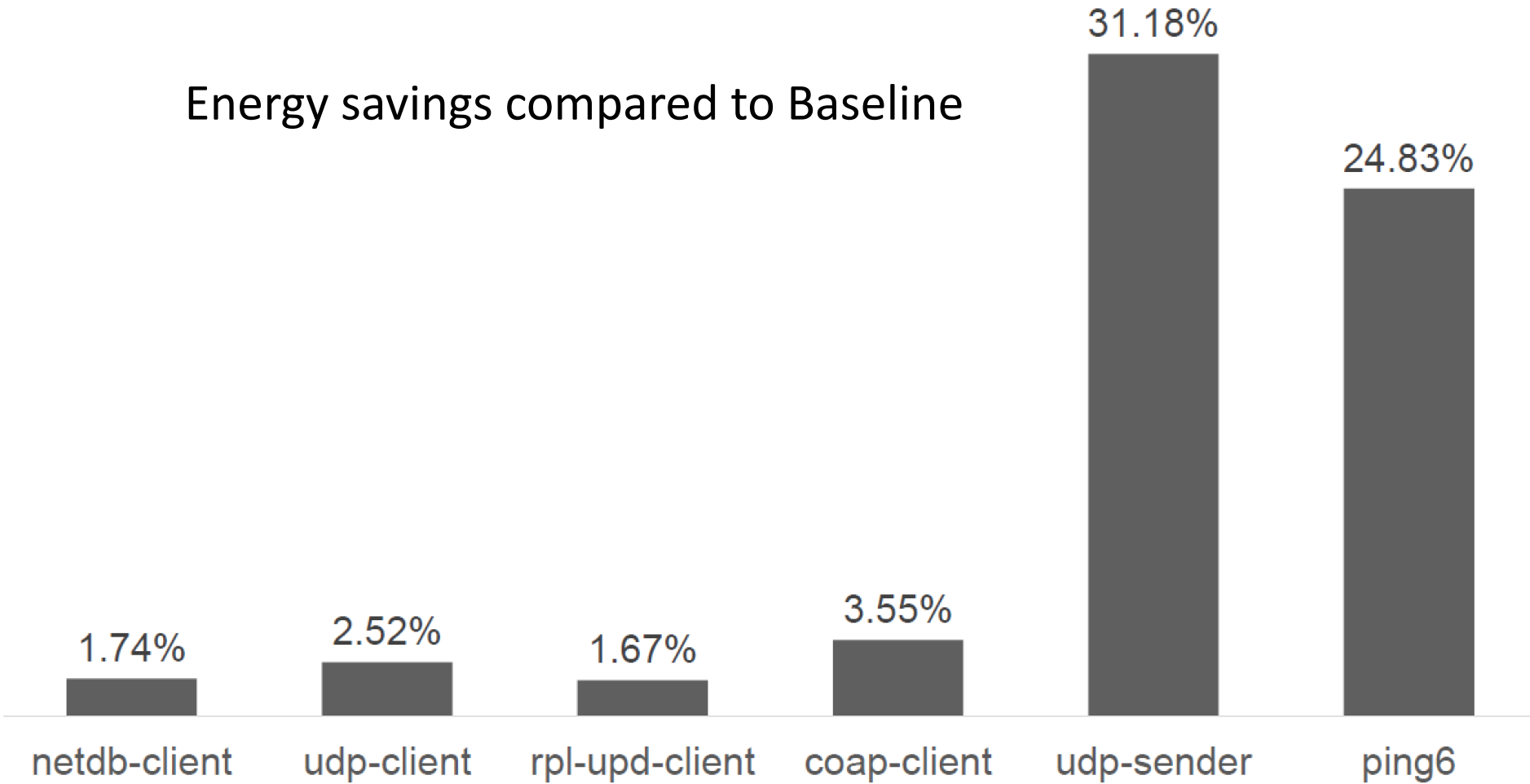
Applications	Memory Accesses	ABCs inserted		% ABCs Reduction SIoT vs Baseline
		Baseline	SIoT	
netdb client/server	22,819	172	16	90.70%
ping6 / new-ipv6	16,871	166	14	91.57%
ipv6-rpl-collect udp-sender / sink	17,301	168	14	91.67%
ipv6-rpl-udp client/server	17,162	170	14	91.76%
udp-ipv6 client/server	16,945	212	14	93.40%
coap-client / rest-server	18,693	214	14	93.46%

# Experiment Setup



# SloT Dynamic Analysis

Energy savings compared to Baseline



# Agenda

- Introduction
- Goal
- Solution
- Results
- Conclusion



# Conclusions

## SloT

1. Sees and analyze individuals programs of a distributed system as a single system
2. Protects IoT code around 20% more energy-efficiently than state-of-the-art approach
3. Is publicly available

Besides, we came up with

1. Distributed Control Flow Graphs – DCFGs
2. Elevator, an alg. that is able to link `sends/recvs`

# Thanks

[www.ecosoc.dcc.ufmg.br](http://www.ecosoc.dcc.ufmg.br)

[leonardo.barbosa@dcc.ufmg.br](mailto:leonardo.barbosa@dcc.ufmg.br)

---

**Algorithm 1:** Elevator

---

**Input:** CFGs  $\{\mathcal{C}_1, \mathcal{C}_2\}$ , Send-Graphs  $\{\mathcal{S}_1, \mathcal{S}_2\}$  and Receive-Graphs  $\{\mathcal{R}_1, \mathcal{R}_2\}$ .

**Output:** a DCFG  $\mathcal{D}$

▷ Set the SEND and RECV levels

**foreach**  $G_i \in \{\mathcal{S}_1, \mathcal{S}_2\} \cup \{\mathcal{R}_1, \mathcal{R}_2\}$  **do**

$n \leftarrow 0$

$L_{G_i,n} \leftarrow \{root\}$

▷ While the new generated set  $L_{G_i,n}$  is unique

**while**  $L_{G_i,n} \neq \emptyset$  **and**  $L_{G_i,n} \neq L_{G_i,0..n-1}$  **do**

**foreach** vertex  $v$  in  $L_{G_i,n}$  **do**

$S_{succs} \leftarrow$  successors of  $v$

$L_{G_i,n+1} \leftarrow L_{G_i,n+1} \cup S_{succs}$

$n \leftarrow n + 1$

▷ Link SENDs and RECVs of the same level

$\mathcal{D} \leftarrow \mathcal{C}_1 \cup \mathcal{C}_2$

**for**  $k \leftarrow 1$  **to**  $n$  **do**

**foreach**  $v_s \in L_{\mathcal{S}_1,k}$  **and**  $v_r \in L_{\mathcal{R}_2,k}$  **do**

        add an edge from  $v_s$  to  $v_r$  in  $\mathcal{D}$

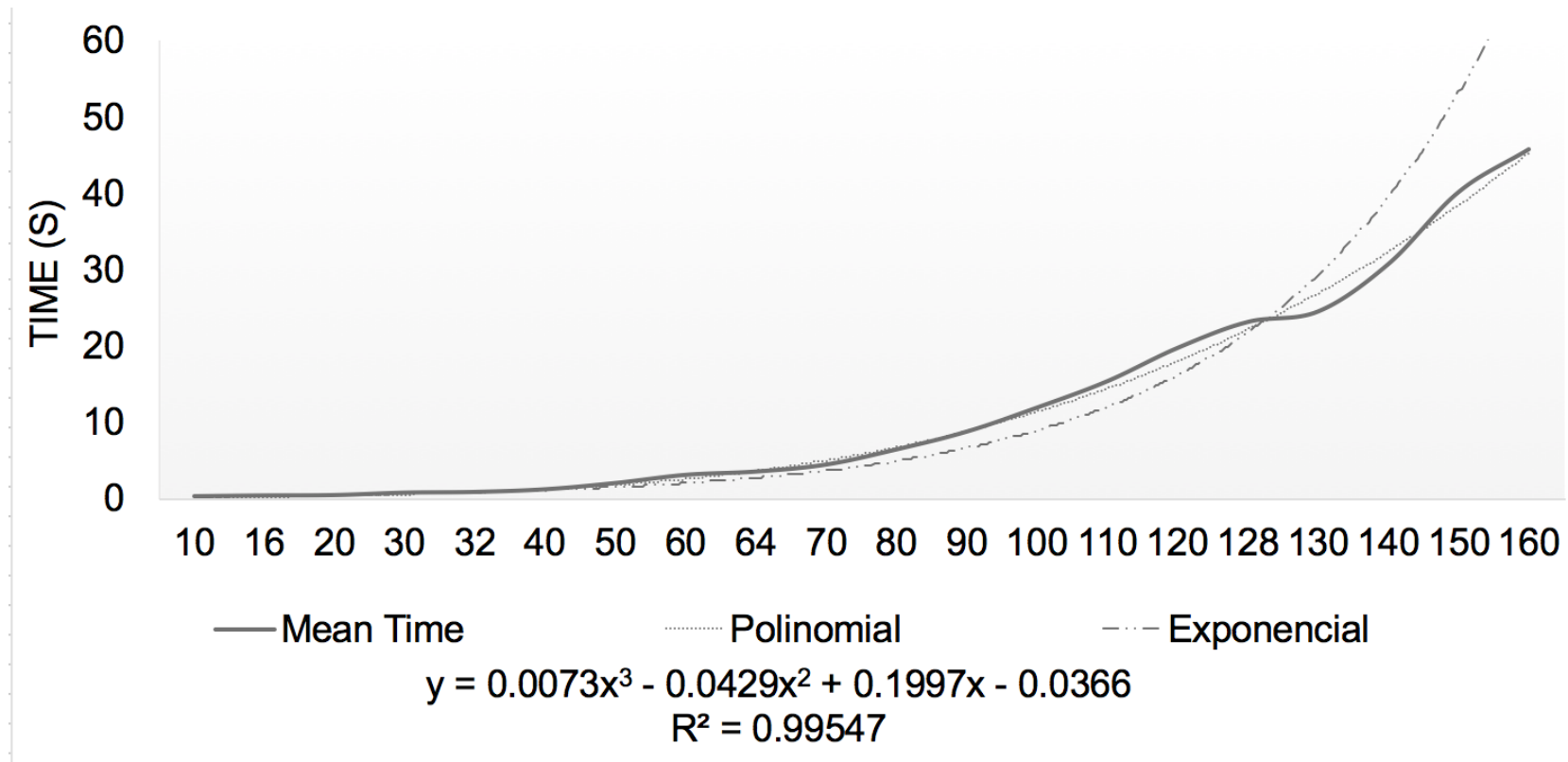
**foreach**  $v_r \in L_{\mathcal{R}_1,k}$  **and**  $v_s \in L_{\mathcal{S}_2,k}$  **do**

        add an edge from  $v_s$  to  $v_r$  in  $\mathcal{D}$

---

# Elevator Asymptotic Complexity

- Runtime as a function of the number of CGFs vertices
- In practice,  $O(n^3)$  where  $n$  is the number of vertices



# Related Work

- There are works that already focused on IoT software correctness and security
  - Coopriider et al. Safe TinyOS (Sensys'07)
  - Li and Regehr. Kleenet. (IPSN'10)
  - Sasnauskas et al. T-Check. (IPSN'10)
- These works don't look at IoT as a single system and we believe ours is complementary to their strategies
  - I.e., SloT can potentially improve their numbers

# ABC Cost

# ABCs' Computational Cost

buffer[i] = a; {  
    mrmovl -12(%ebp), %eax   Load 'i'  
    mrmovl -4(%ebp), %edx  
    rrmovl %eax, %edi  
    sall \$2, %edi  
    addl %ebp, %edi  
    rmmovl %edx, -2060(%edi)

# ABCs' Computational Cost

buffer[i] = a; {  
    mrmovl -12(%ebp), %eax   Load 'i'  
    mrmovl -4(%ebp), %edx   Load 'a'  
    rrmovl %eax, %edi  
    sall \$2, %edi  
    addl %ebp, %edi  
    rmmovl %edx, -2060(%edi)



# ABCs' Computational Cost

buffer[i] = a; {

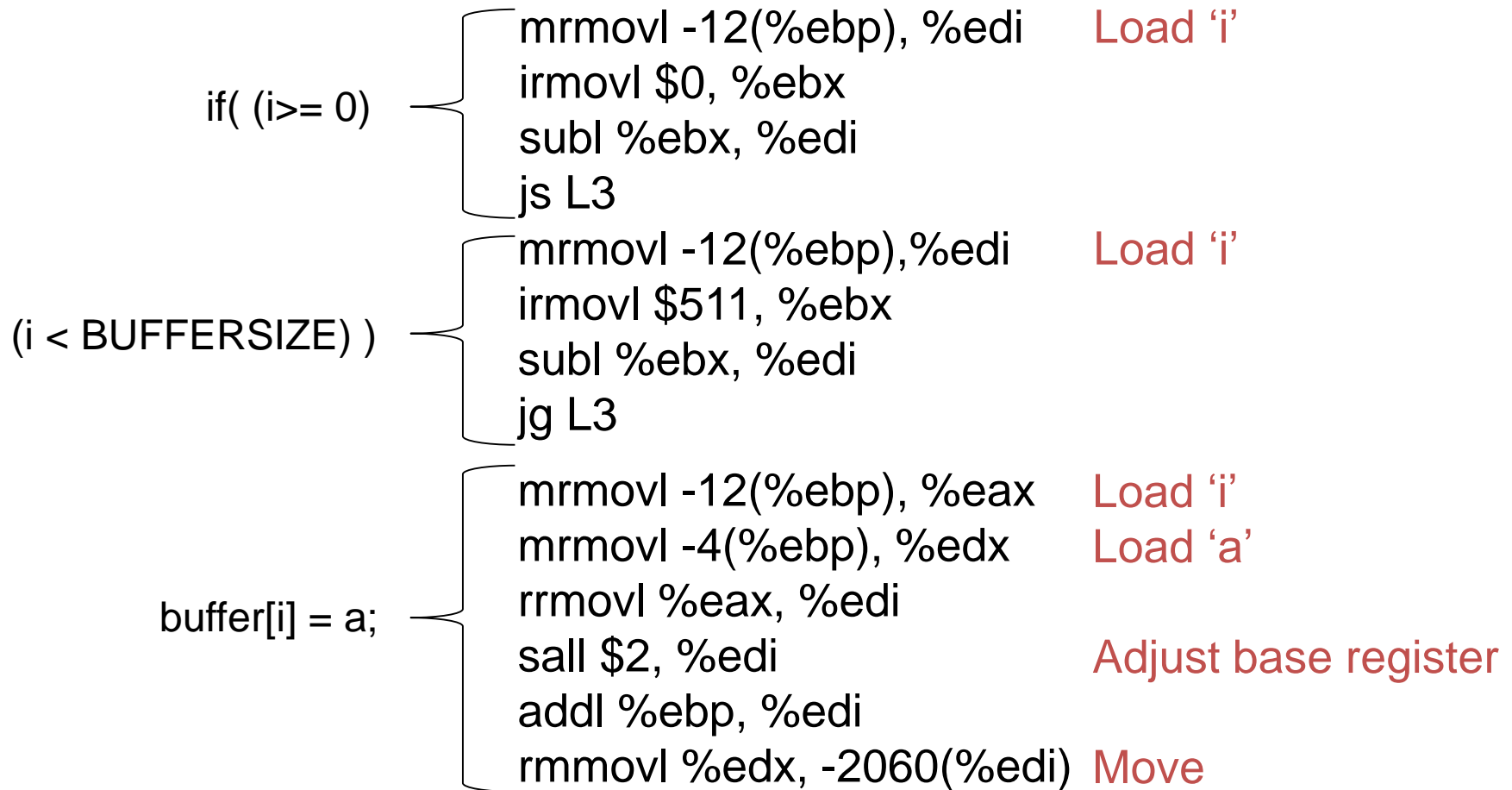
- mrmovl -12(%ebp), %eax      Load 'i'
- mrmovl -4(%ebp), %edx      Load 'a'
- rrmovl %eax, %edi
- sall \$2, %edi      Adjust base register
- addl %ebp, %edi
- rmmovl %edx, -2060(%edi)

# ABCs' Computational Cost

buffer[i] = a; {

mrmovl -12(%ebp), %eax	Load 'i'
mrmovl -4(%ebp), %edx	Load 'a'
rrmovl %eax, %edi	
sall \$2, %edi	Adjust base register
addl %ebp, %edi	
rmmovl %edx, -2060(%edi)	Move

# ABCs' Computational Cost



# ABCs' Computational Cost

if( (i >= 0)	<div>mrmovl -12(%ebp), %edi irmovl \$0, %ebx subl %ebx, %edi js L3</div>	Load 'i' Load lower index
(i < BUFFERSIZE) )	<div>mrmovl -12(%ebp), %edi irmovl \$511, %ebx subl %ebx, %edi jg L3</div>	Load 'i' Load upper index
buffer[i] = a;	<div>mrmovl -12(%ebp), %eax mrmovl -4(%ebp), %edx rrmovl %eax, %edi sall \$2, %edi addl %ebp, %edi rmmovl %edx, -2060(%edi)</div>	Load 'i' Load 'a'  Adjust base register Move

# ABCs' Computational Cost

if( (i >= 0)	mrmovl -12(%ebp), %edi	Load 'i'
	irmovl \$0, %ebx	Load lower index
	subl %ebx, %edi	
	js L3	Compare
(i < BUFFERSIZE) )	mrmovl -12(%ebp), %edi	Load 'i'
	irmovl \$511, %ebx	Load upper index
	subl %ebx, %edi	
	jg L3	Compare
buffer[i] = a;	mrmovl -12(%ebp), %eax	Load 'i'
	mrmovl -4(%ebp), %edx	Load 'a'
	rrmovl %eax, %edi	
	sall \$2, %edi	Adjust base register
	addl %ebp, %edi	
	rmmovl %edx, -2060(%edi)	Move

# Full BOF example

# Vulnerable Code

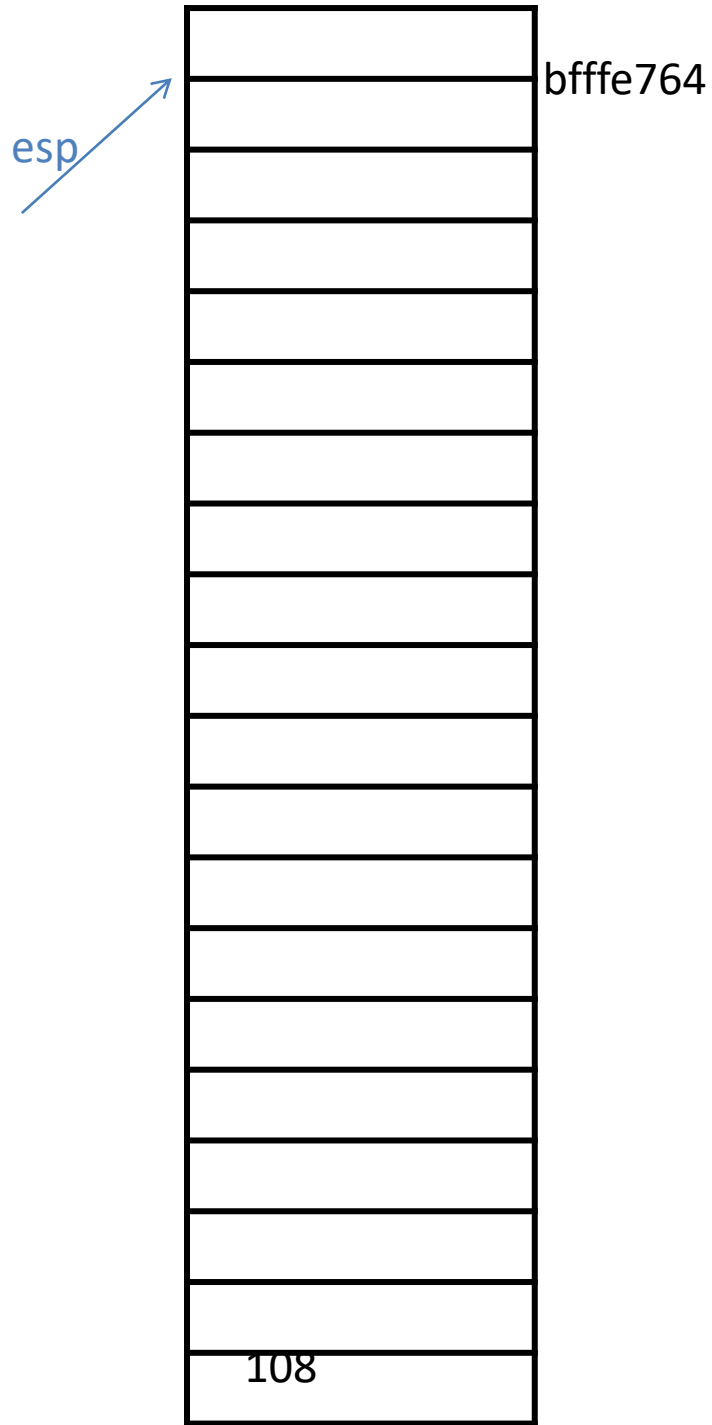
```
#include <stdio.h>

void foo(FILE *badfile){
    char buffer[12];
    ...
    fread(buffer,sizeof(char),517,badfile);
    ...
    return 1;
}

int main() {
    FILE *badfile;
    badfile = fopen("file","r");
    foo(badfile);
    fclose(badfile);
    return 1;
}
```

```
foo:
    pushl    %ebp
    movl %esp, %ebp
    subl $40, %esp
    ...
    movl 8(%ebp), %edx
    movl %edx, 12(%esp)
    movl $517, 8(%esp)
    movl $1, 4(%esp)
    movl %eax, (%esp)
    call fread
    movl $1, %eax
    leave
    ret

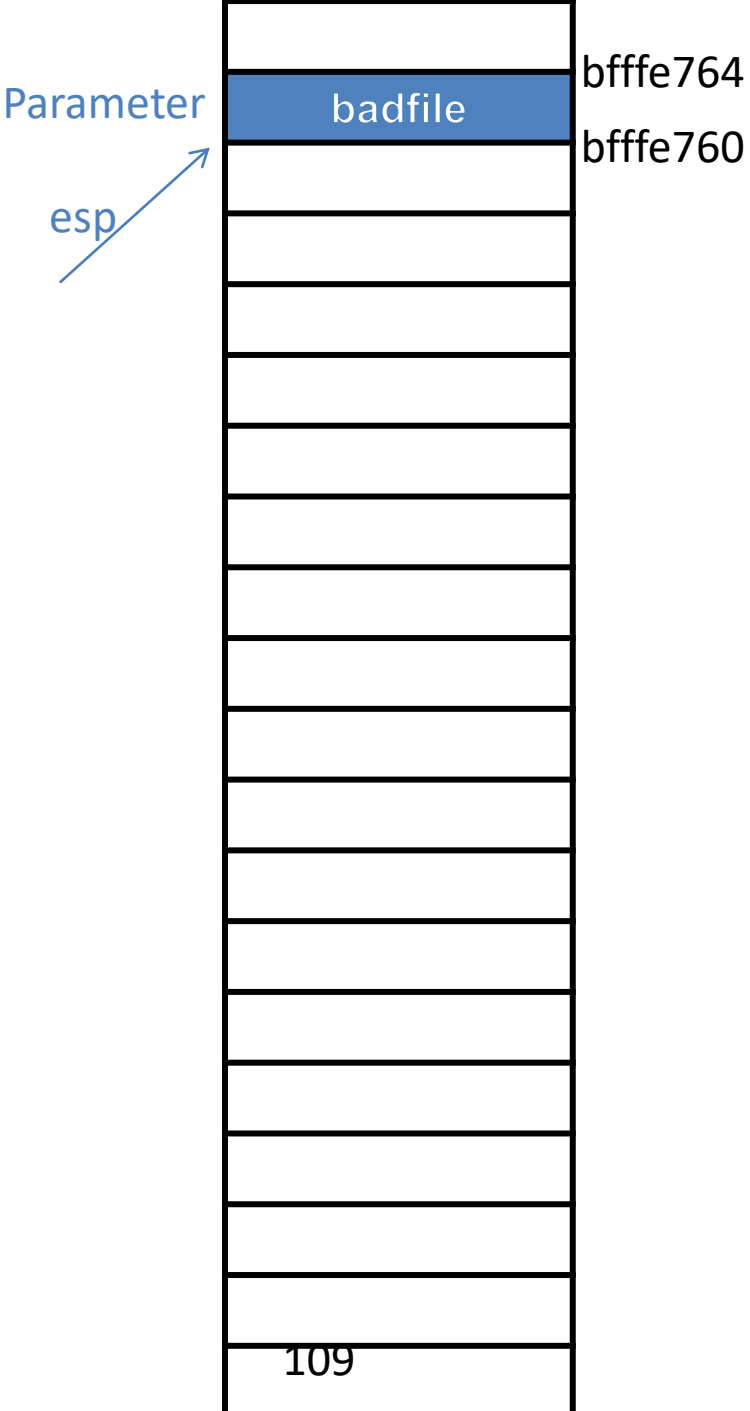
main:
    ...
    movl %eax, (%esp)
    call foo
    ...
    $1, %eax
    leave
    ret
```





```
foo:
    pushl    %ebp
    movl %esp, %ebp
    subl $40, %esp
    ...
    movl 8(%ebp), %edx
    movl %edx, 12(%esp)
    movl $517, 8(%esp)
    movl $1, 4(%esp)
    movl %eax, (%esp)
    call fread
    movl $1, %eax
    leave
    ret

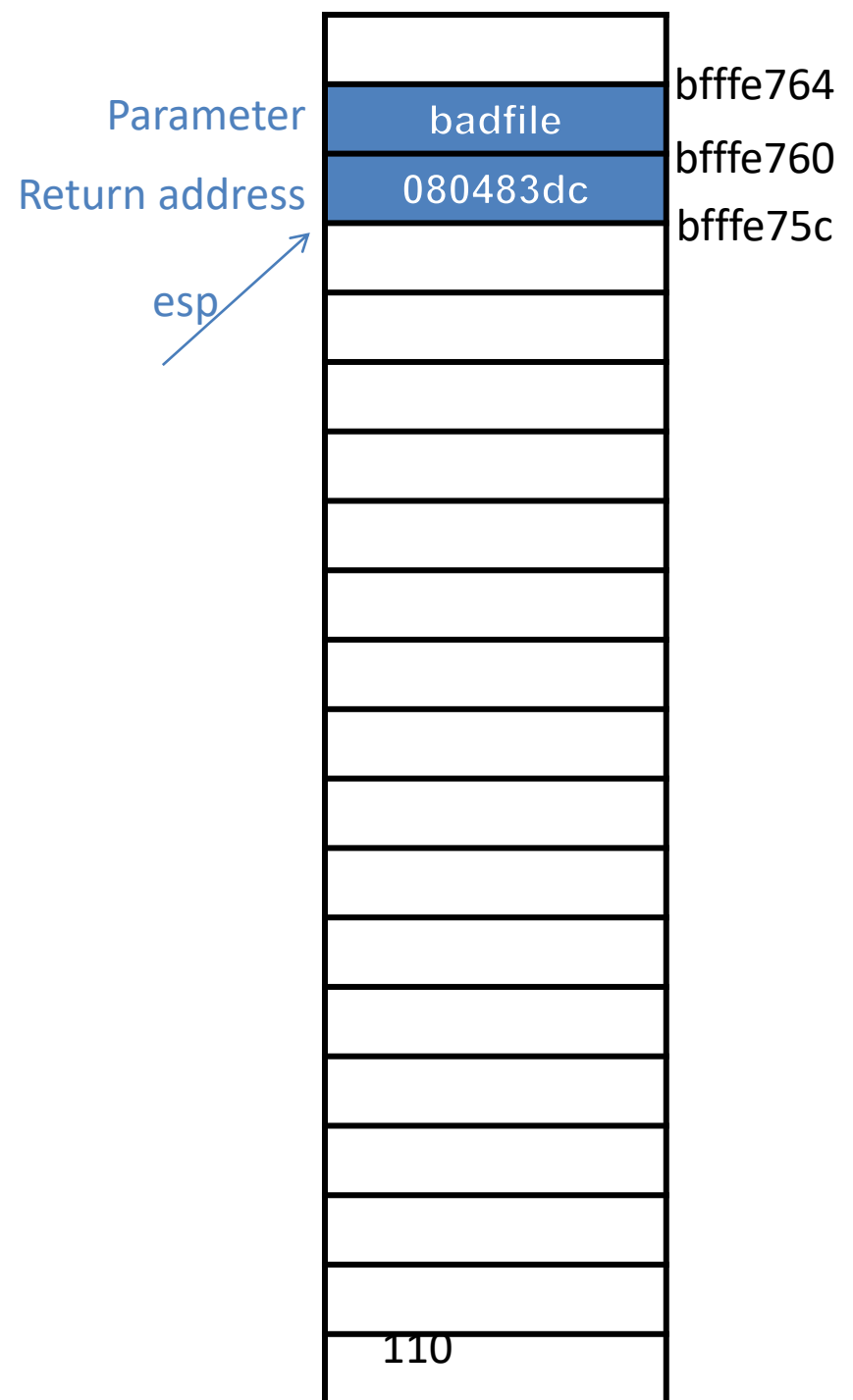
main:
    ...
    movl %eax, (%esp)
    call foo
    ...
    $1, %eax
    leave
    ret
```



```
main:
```

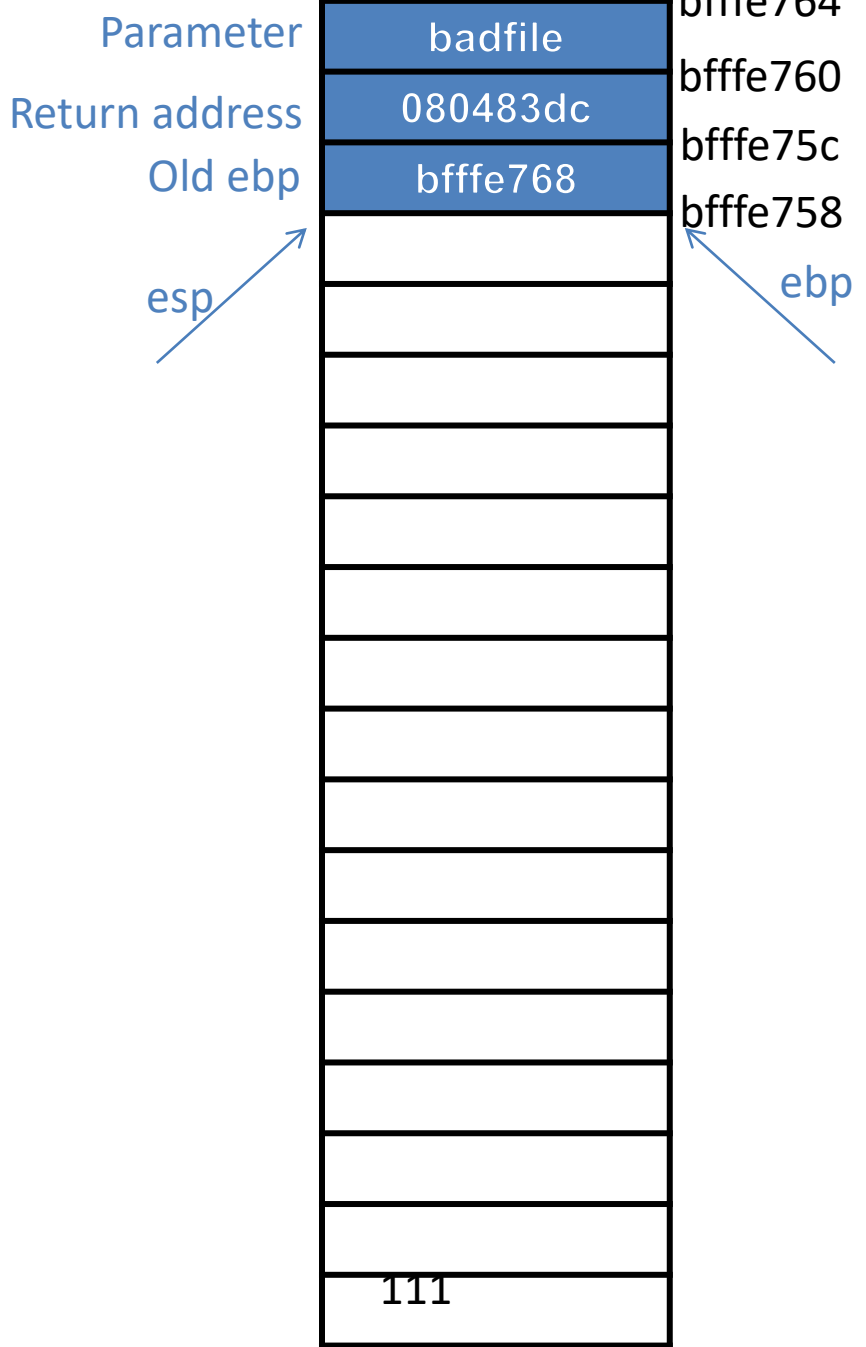
```
pushl    %ebp
movl %esp, %ebp
subl $40, %esp
...
movl 8(%ebp), %edx
movl %edx, 12(%esp)
movl $517, 8(%esp)
movl $1, 4(%esp)
movl %eax, (%esp)
call fread
movl $1, %eax
leave
ret
```

```
...
movl %eax, (%esp)
call foo
...
$1, %eax
leave
ret
```



```
foo:
    pushl    %ebp
    movl %esp, %ebp
    subl $40, %esp
    ...
    movl 8(%ebp), %edx
    movl %edx, 12(%esp)
    movl $517, 8(%esp)
    movl $1, 4(%esp)
    movl %eax, (%esp)
    call fread
    movl $1, %eax
    leave
    ret

main:
    ...
    movl %eax, (%esp)
    call foo
    ...
    $1, %eax
    leave
    ret
```



foo :

```
pushl    %ebp
movl    %esp, %ebp
subl    $40, %esp
...
movl    8(%ebp), %edx
movl    %edx, 12(%esp)
movl    $517, 8(%esp)
movl    $1, 4(%esp)
movl    %eax, (%esp)
call    fread
movl    $1, %eax
leave
ret
```

# main

```
...
movl %eax, (%esp)
call foo
...
$1, %eax
leave
ret
```

## Parameter

## Return address

Old ebp

badfile

080483dc

bffffe768

bffe764

bffffe760

bffffe75c

bffffe758

ebp

bffffe730

esp

---

112

```
main:
```

```
pushl    %ebp
movl %esp, %ebp
subl $40, %esp
...
movl 8(%ebp), %edx
movl %edx, 12(%esp)
movl $517, 8(%esp)
movl $1, 4(%esp)
movl %eax, (%esp)
call fread
movl $1, %eax
leave
ret
```

```
...
movl %eax, (%esp)
call foo
...
$1, %eax
leave
ret
```

## Parameter

## Return address

Old ebp

badfile

080483dc

bffffe768

badfile

---

113

bffff764

bffffe760

bffffe75c

bffffe758

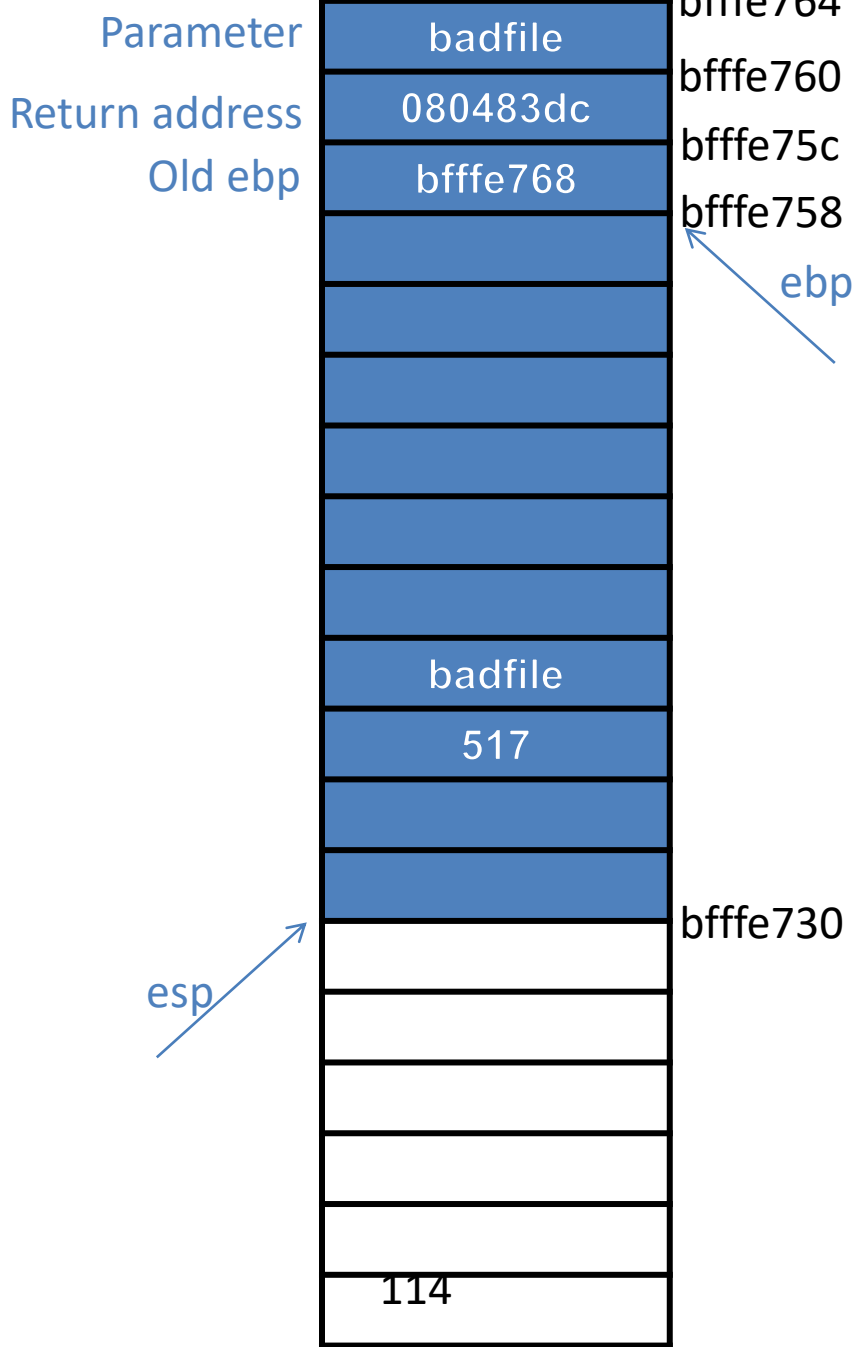
ebp

bffffe730

esp

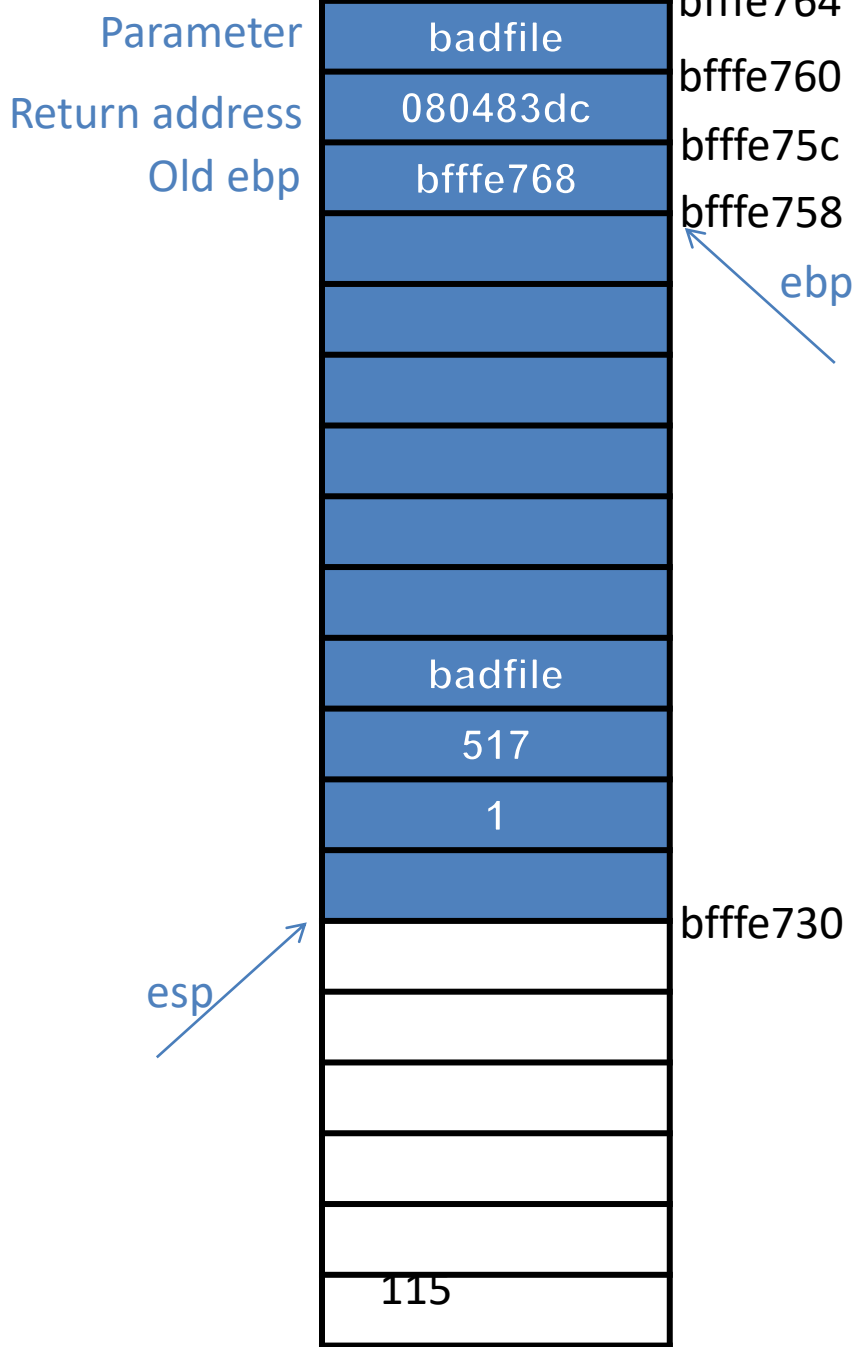
```
foo:
    pushl    %ebp
    movl %esp, %ebp
    subl $40, %esp
    ...
    movl 8(%ebp), %edx
    movl %edx, 12(%esp)
    movl $517, 8(%esp)
    movl $1, 4(%esp)
    movl %eax, (%esp)
    call fread
    movl $1, %eax
    leave
    ret

main:
    ...
    movl %eax, (%esp)
    call foo
    ...
    $1, %eax
    leave
    ret
```



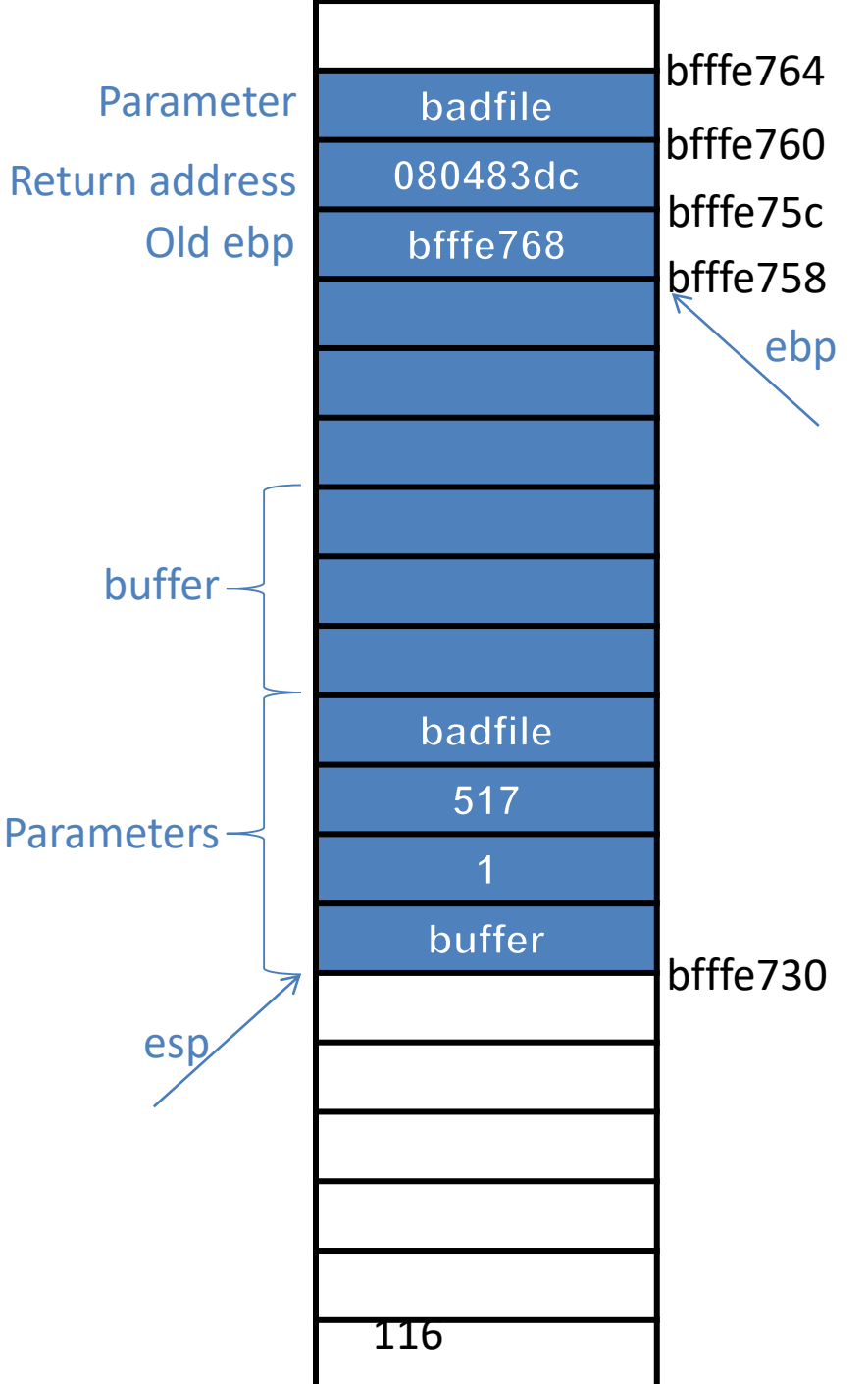
```
foo:
    pushl    %ebp
    movl %esp, %ebp
    subl $40, %esp
    ...
    movl 8(%ebp), %edx
    movl %edx, 12(%esp)
    movl $517, 8(%esp)
    movl $1, 4(%esp)
    movl %eax, (%esp)
    call fread
    movl $1, %eax
    leave
    ret

main:
    ...
    movl %eax, (%esp)
    call foo
    ...
    $1, %eax
    leave
    ret
```



```
foo:
    pushl    %ebp
    movl %esp, %ebp
    subl $40, %esp
    ...
    movl 8(%ebp), %edx
    movl %edx, 12(%esp)
    movl $517, 8(%esp)
    movl $1, 4(%esp)
    movl %eax, (%esp)
    call fread
    movl $1, %eax
    leave
    ret

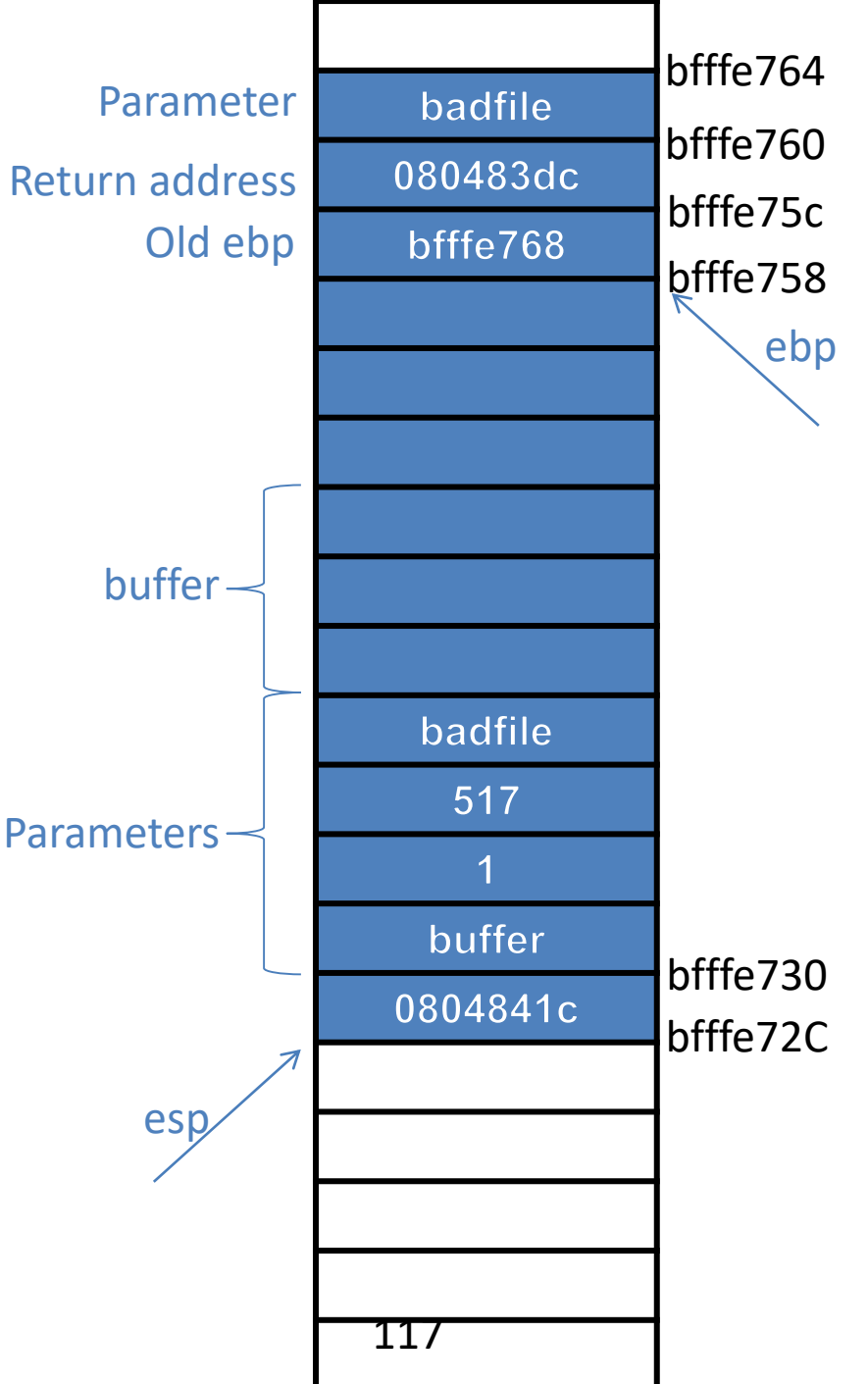
main:
    ...
    movl %eax, (%esp)
    call foo
    ...
    $1, %eax
    leave
    ret
```





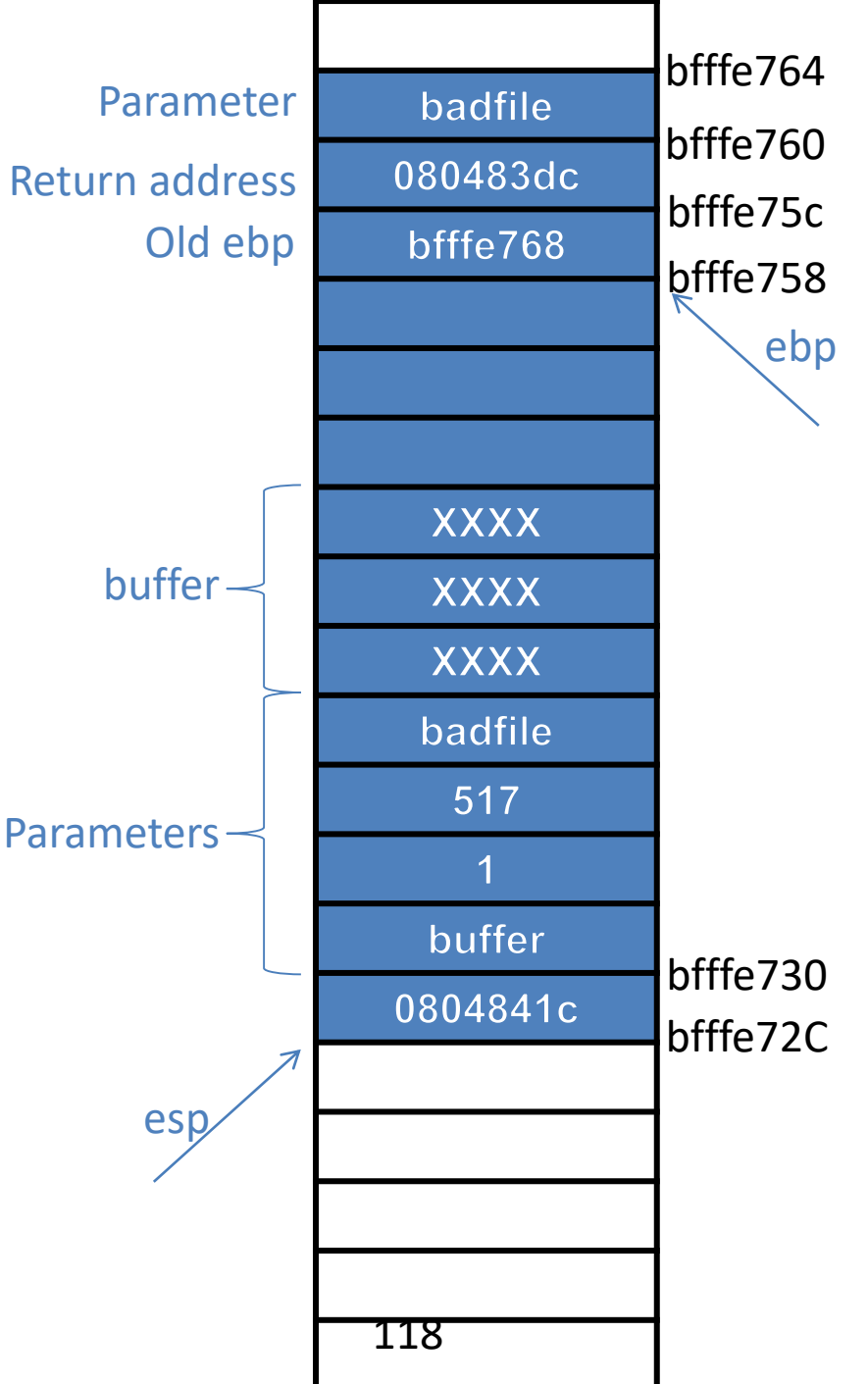
```
foo:
    pushl    %ebp
    movl %esp, %ebp
    subl $40, %esp
    ...
    movl 8(%ebp), %edx
    movl %edx, 12(%esp)
    movl $517, 8(%esp)
    movl $1, 4(%esp)
    movl %eax, (%esp)
    call fread
    movl $1, %eax
    leave
    ret

main:
    ...
    movl %eax, (%esp)
    call foo
    ...
    $1, %eax
    leave
    ret
```



```
foo:
    pushl    %ebp
    movl %esp, %ebp
    subl $40, %esp
    ...
    movl 8(%ebp), %edx
    movl %edx, 12(%esp)
    movl $517, 8(%esp)
    movl $1, 4(%esp)
    movl %eax, (%esp)
    call fread
    movl $1, %eax
    leave
    ret

main:
    ...
    movl %eax, (%esp)
    call foo
    ...
    $1, %eax
    leave
    ret
```



```
...
movl %eax, (%esp)
call foo
...
$1, %eax
leave
ret
```

