

SIoT – Securing the Internet of Things through Distributed System Analysis

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Agenda

- Introduction
- Goal
- Solution
- Results
- Conclusion

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 - IoT
 - C language
 - Buffer Overflow
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IoT



- Capabilities
 - It's made up with constrained devices
- Computing Paradigm
 - A distributed system and usually exchange a large number of messages
- Programming language
 - Apps are often written in C, which is inherently unsafe

IoT



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 - It's made up with constrained devices
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 - A distributed system and usually exchange a large number of messages
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C is unsafe because it does not check array-bounds

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Java

Q: What happens when we run this Java program?

```
public class P {  
    final static int SIZE = 4;  
  
    static void copyAndPrint(byte[] v) {  
        byte[] buf = new byte[SIZE];  
        for (int i = 0; i < v.length; i++) {  
            buf[i] = v[i];  
            System.out.println("-> " + buf[i]);  
        }  
    }  
  
    public static void main(String args[]) {  
        byte[] v = {0, 1, 2, 3, 4};  
        copyAndPrint(v);  
    }  
}
```



```
Terminal — bash — 37x10  
~$ java P  
-> 0  
-> 1  
-> 2  
-> 3  
Exception in thread "main" java.lang.  
ArrayIndexOutOfBoundsException: 4  
    at P.copyAndPrint(P.java:7)  
    at P.main(P.java:14)  
~$ [ ]
```



C language

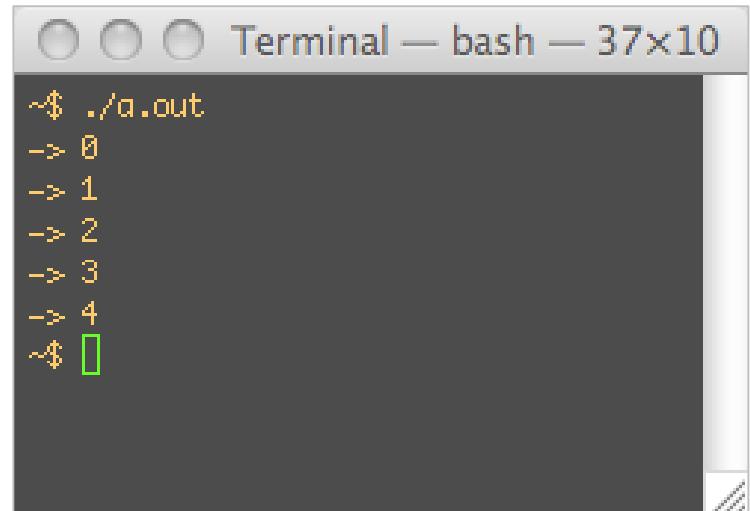
Q: What about this C program?

```
#include <stdio.h>

#define SIZE 4

void copyAndPrint(char v[], int n) {
    char buf[SIZE];
    int i;
    for (i = 0; i < n; i++) {
        buf[i] = v[i];
        printf("-> %d\n", buf[i]);
    }
}

int main() {
    char v[] = {0, 1, 2, 3, 4};
    copyAndPrint(v, SIZE + 1);
}
```

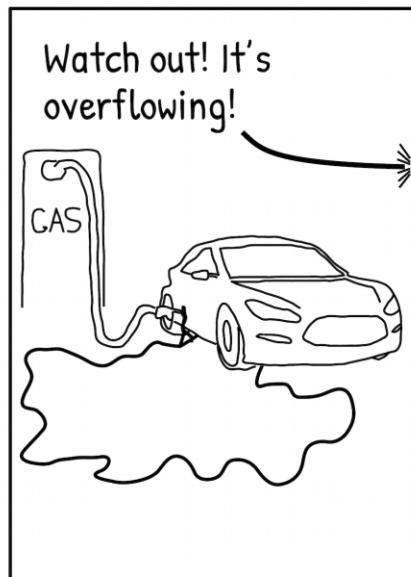


A screenshot of a terminal window titled "Terminal — bash — 37x10". The window shows the output of a C program. The program defines a character array `v` with values 0, 1, 2, 3, 4. It then calls a function `copyAndPrint` with `v` and a size of `SIZE + 1`. The function iterates through the array, printing each character followed by a newline. The terminal shows the output: "-> 0", "-> 1", "-> 2", "-> 3", "-> 4". The prompt is then shown again.

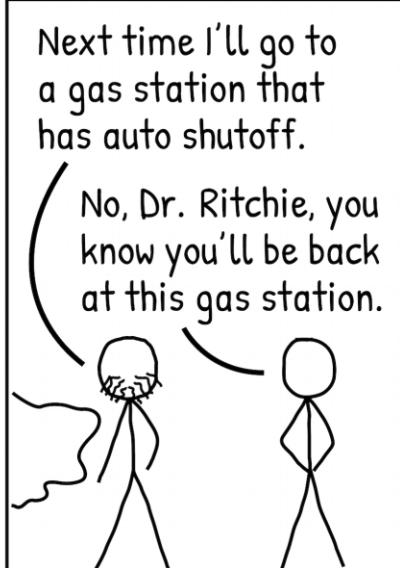
```
~$ ./a.out
-> 0
-> 1
-> 2
-> 3
-> 4
~$
```



Q: Why is that?



Buffer Overflow.



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C unsafety: Outcomes



- Morris worm
 - Buffer over-write that compromised around 10% of computers connected to the Internet back in 1988
- Heartbleed
 - Buffer over-read that compromised half a million web servers in 2014
- IoT vulnerability
 - Due to the unsafe nature of C, IoT apps are vulnerable to buffer overflow attacks, too

C unsafety: Outcomes



- Morris worm
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Buffer Overflow?

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Buffer Overflow



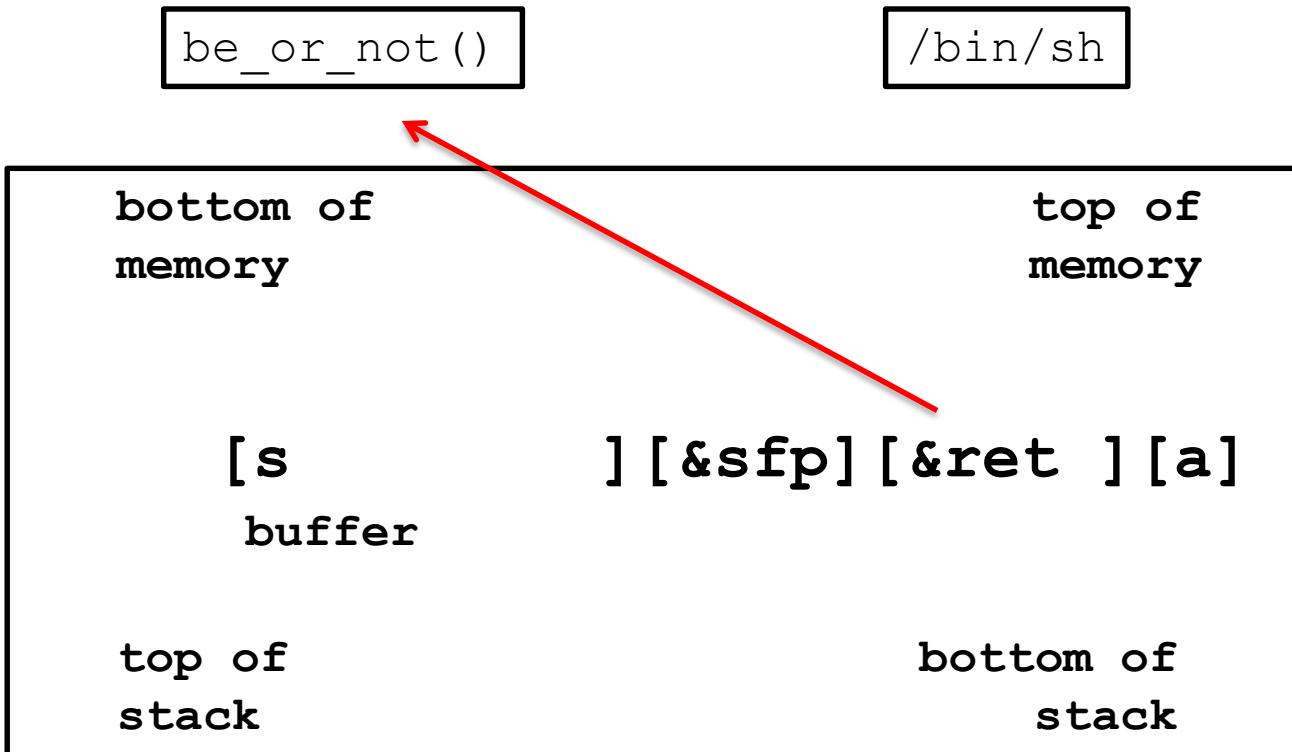
- A buffer overflow happens when the memory space that guides the execution flow is overwritten
- The idea is to manipulate arrays w/o bound checks

```
#include <stdio.h>

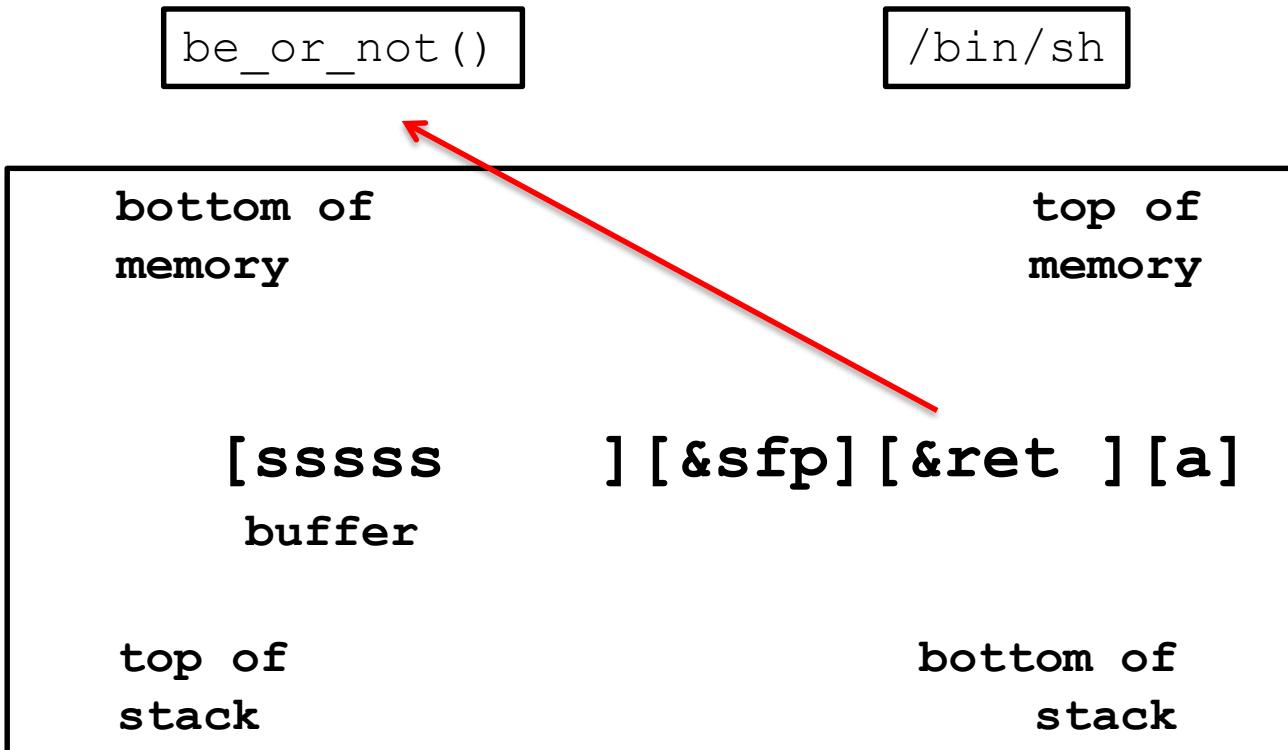
int main(int argc, char **argv) {
    char buf[8]; // creates 8-byte block memory
    gets(buf); // reads unlimited number of bytes

    return 0;
}
```

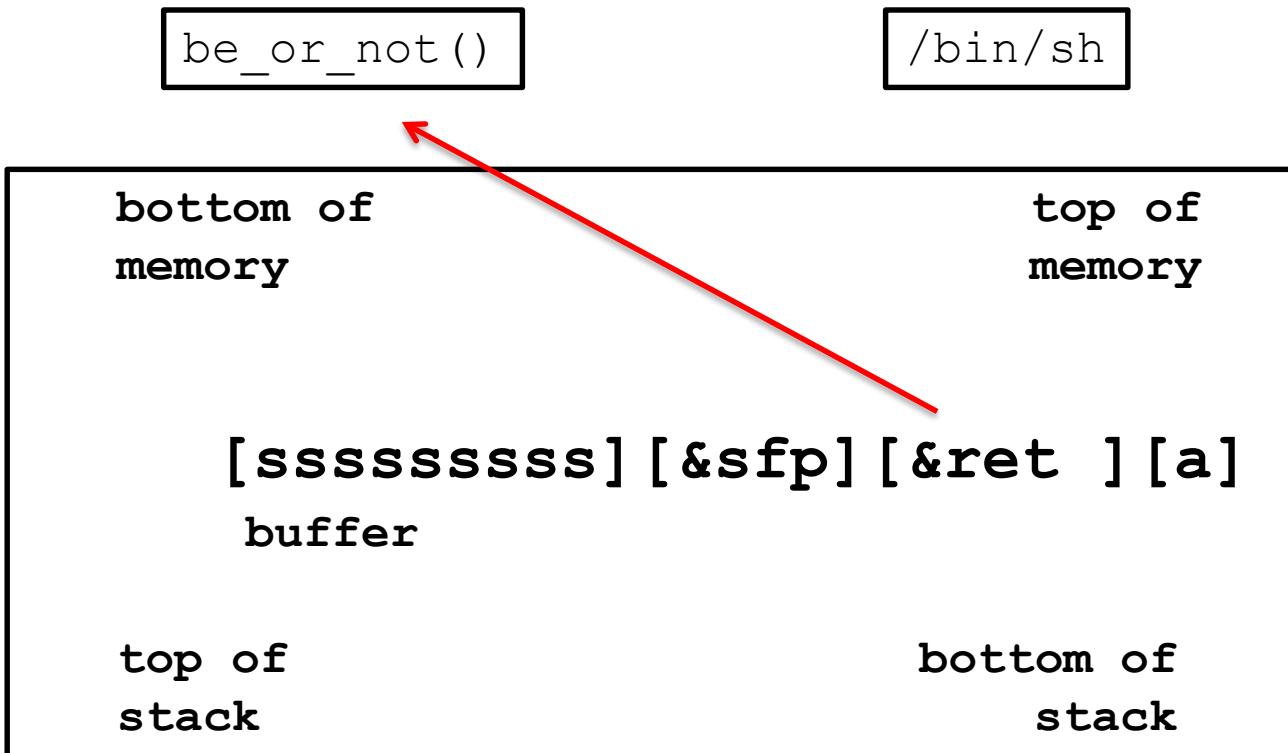
BOF (Cont.)



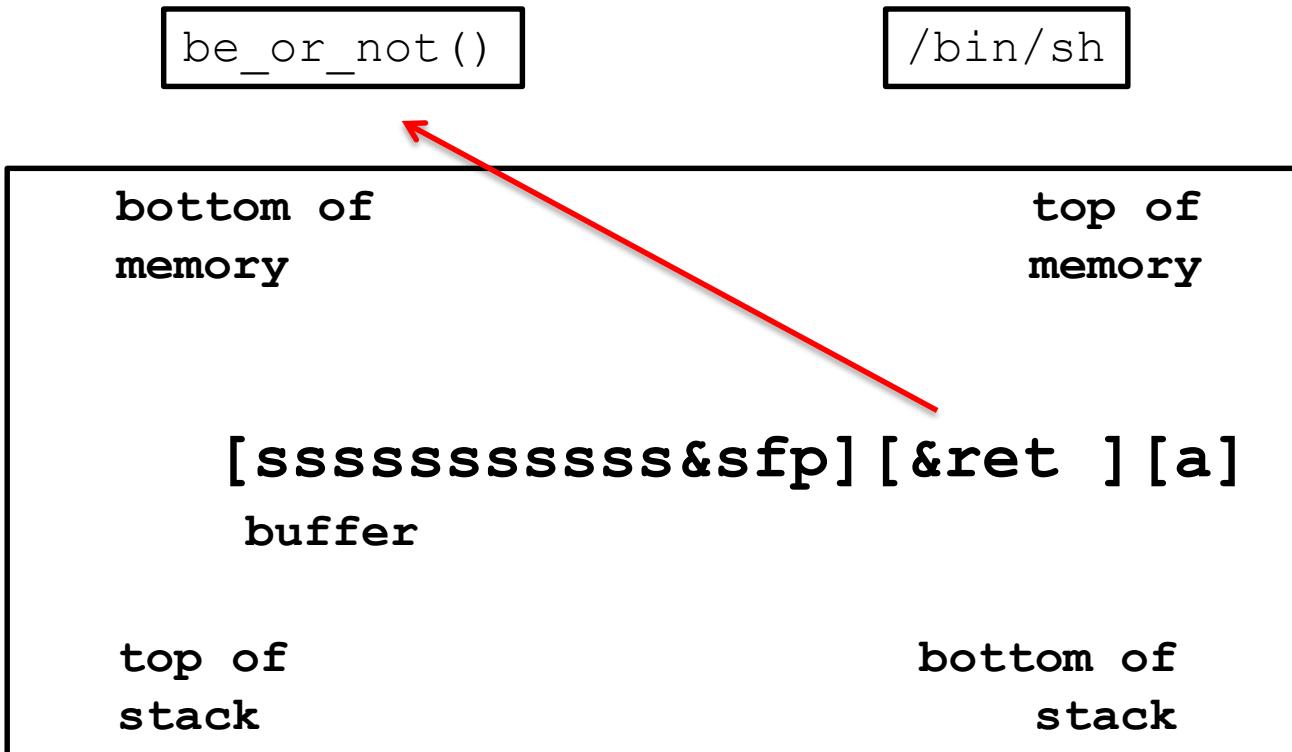
BOF (Cont.)



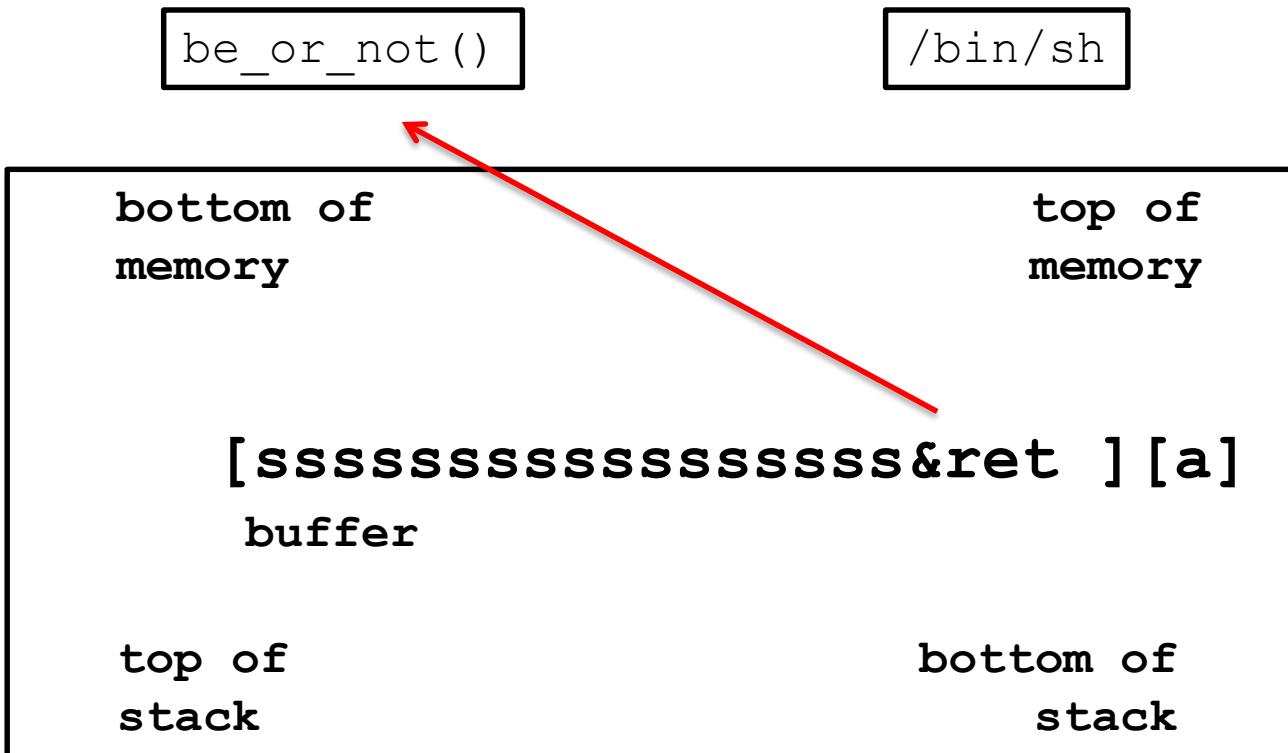
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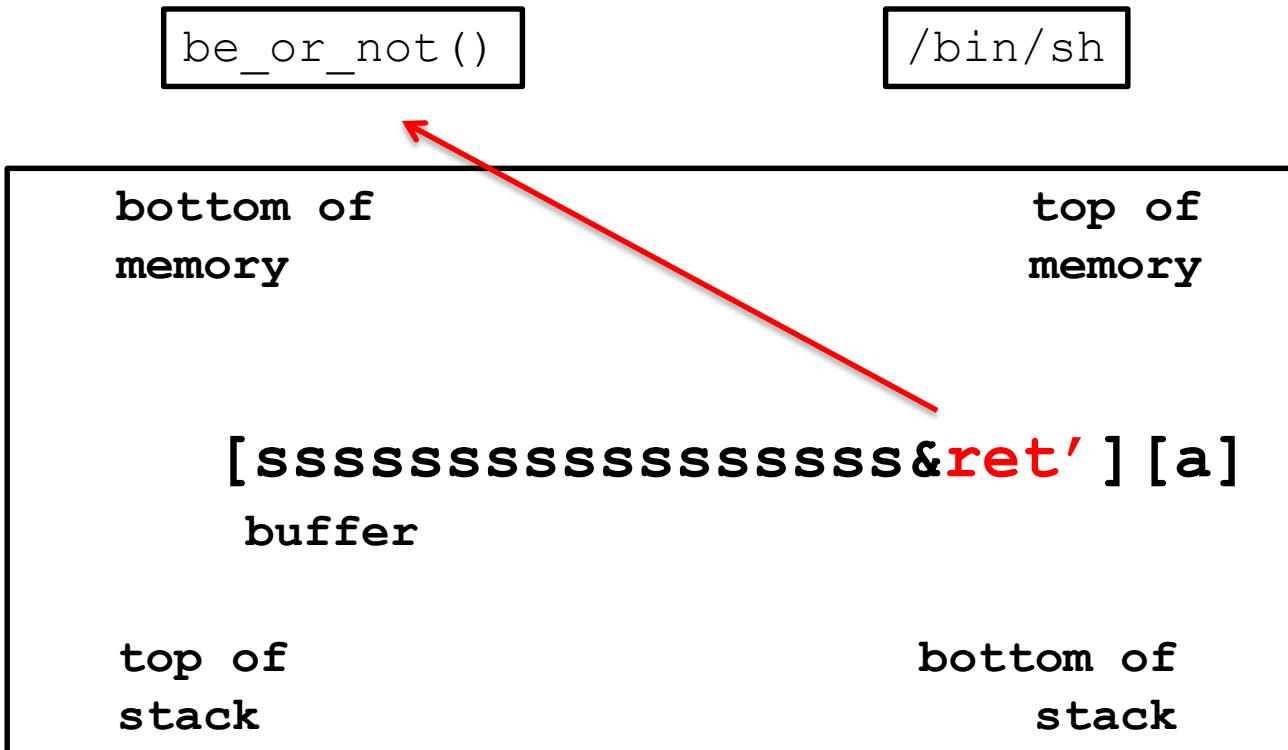
BOF (Cont.)



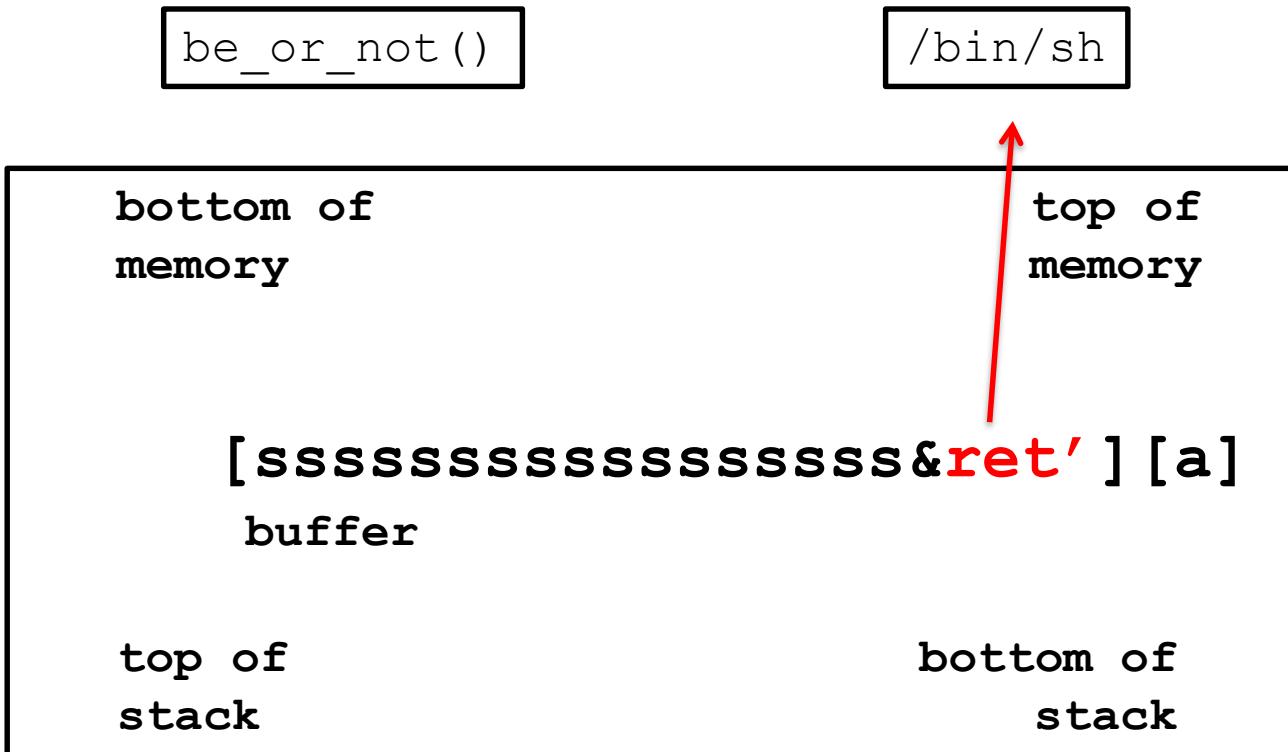
BOF (Cont.)



BOF (Cont.)



BOF (Cont.)



Ok, I got it! IoT apps are written in C and then they're particularly vulnerable to BOFs.

There are a bunch of BOF prevention mechanisms out there, though.

Can't we just pick out one and apply in IoT?

No! Because they are inadequate *as-is* to IoT.

BOF Prevention: existing proposals

- There are many proposals for BOF prevention in the context of Internet
 - E.g. SAFECode, SoftBounds, AddressSanitizer, etc.
- They are effective in that they protect memory accesses (load/store) via Array-Bound Checks

BOF Prevention: existing proposals

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Problem

- They tend to slow down the programs too much
- E.g. AddressSanitizer (Serebryany et al. 2012) incurs on average 73% of overhead in a conventional machine

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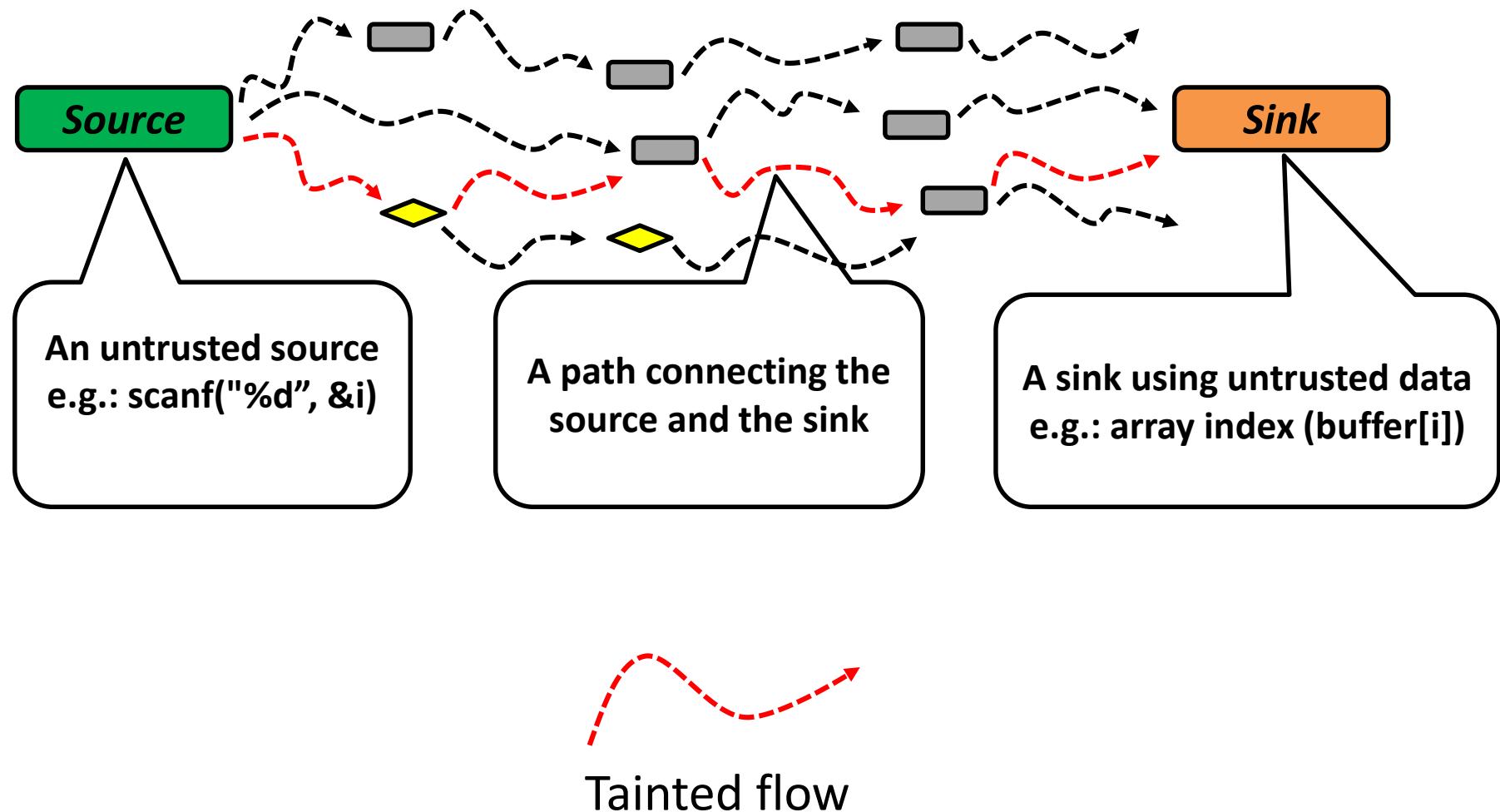
Constrained devices like *things* cannot afford this overhead

Q: How do existing proposals for preventing
BOF work?

How to protect code against BOFs

- Many of the existing proposals to secure code against BOFs have three phases
 1. They first find buffers reachable from untrusted sources, at compiling time

Stage 1: buffers reachable from untrusted sources



How to protect code against BOFs

- Many of the existing proposals to secure code against BOFs have three phases
 1. They first find buffers reachable from untrusted sources, at compiling time
 2. They thus guard buffers by inserting Array Bounds Checks (ABCs) prior to buffers use

Stage 2: ABC insertion

Vulnerable code

```
int main(int argc, char
**argv) {
    int buffer[BUFSIZE];
    int a, i, j;
    ...
    for(i; i < j; i++) {
        ...
        buffer[i] = a;
        ...
    }
    ...
}
```

ABC-protected code

```
int main(int argc, char
**argv) {
    int buffer[BUFSIZE];
    int a, i, j;
    ...
    for(i; i < j; i++) {
        ...
        if((i >= 0) && (i < BUFSIZE))
            buffer[i] = a;
        ...
    }
    ...
}
```



How to protect code against BOFs

- Many of the existing proposals to secure code against BOFs have three phases
 1. They first find buffers reachable from untrusted sources, at compiling time
 2. They thus guard buffers by inserting Array Bounds Checks (ABCs) prior to buffers use
 3. If an ABC is not satisfied at execution time, they then abort programs

Stage 3: Illegal memory access is aborted

```
void foo(const char *arg) {  
    char buffer[100];  
    if (strlen(arg) >= sizeof(buffer))  
        abort();  
    strcpy(buffer, arg);  
}
```



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Goal

- Our goal is to come up with a BOF prevention mechanism tailor-made for IoT
- Solutions must therefore be
 1. Secure against BOFs
 2. Light enough to be run in battery-powered devices

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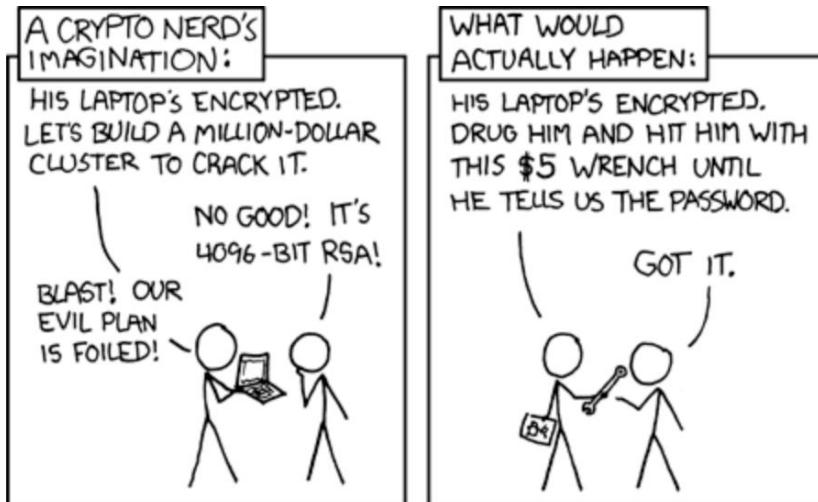
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Assumptions/Attack Model

- Nodes run authentic programs
 - E.g. they could employ Trusted Platform Module (TPM)
- The communication channel is secure
 - Crypto solutions like DTLS (Kothmayr et al.), TinyPBC (Oliveira et al.), or SPINS (Perrig et al.) could be adopted



Assumptions/Attack Model (Cont.)

- Attackers have control over the input data that the nodes receive from its environment
 - This includes data captured by the sensors or input from the user interfaces
 - But excludes data coming from network interfaces as we assume a secure communication channel.



How to lose weight?

SIoT challenge #1

Idea

- Recall existing proposals find buffers reachable from (untrusted) sources
- They analyze programs of a distributed system as disjoint/independent programs
 - E.g., they end up analyzing a client and its respective server programs individually
- Therefore the list of untrusted sources include not only conventional (e.g. `get`) and network (e.g. `recv`) sources

Idea (Cont.)

- The higher the number of untrusted sources, the higher the number of reachable arrays
- And the higher the number of reachable arrays, the higher the number of ABCs and thus the overhead

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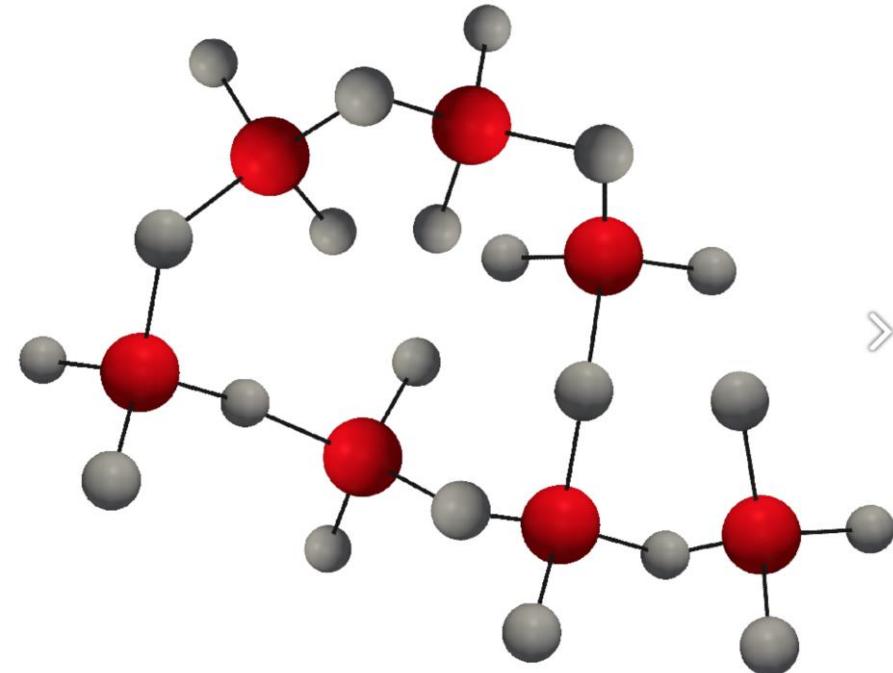
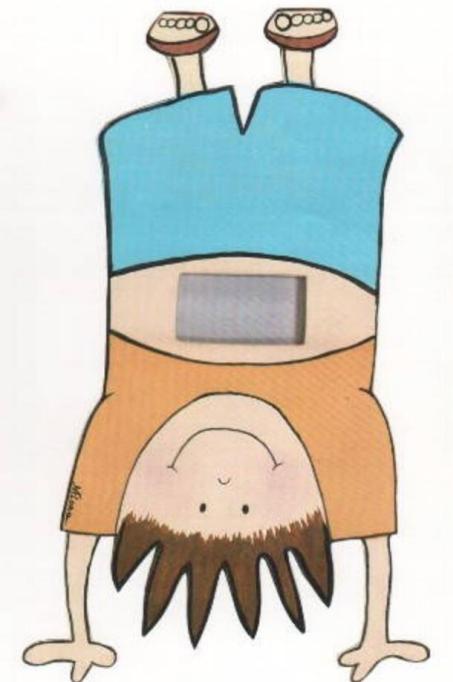
So, what if we decrease the number of untrusted sources?



How can we turn untrusted sources into something else, though?

SIoT key contribution #1

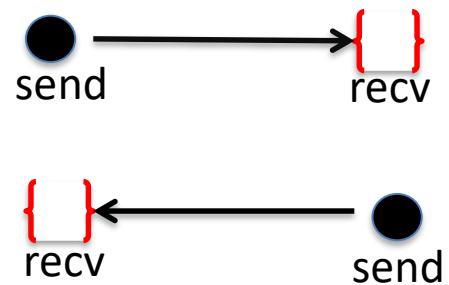
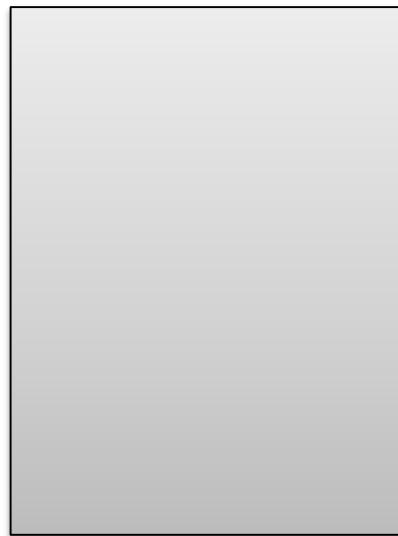
- Look at a distributed system programs from another perspective



Programs A and B: sources

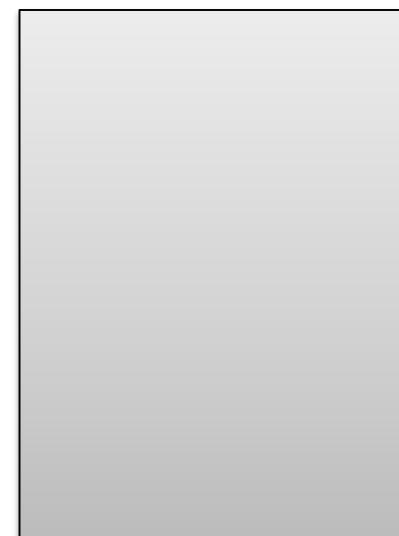
Program A

{ }
scanf { }
 argv



Program B

{ }
scanf { }
 argv



Distributed System AB: sources

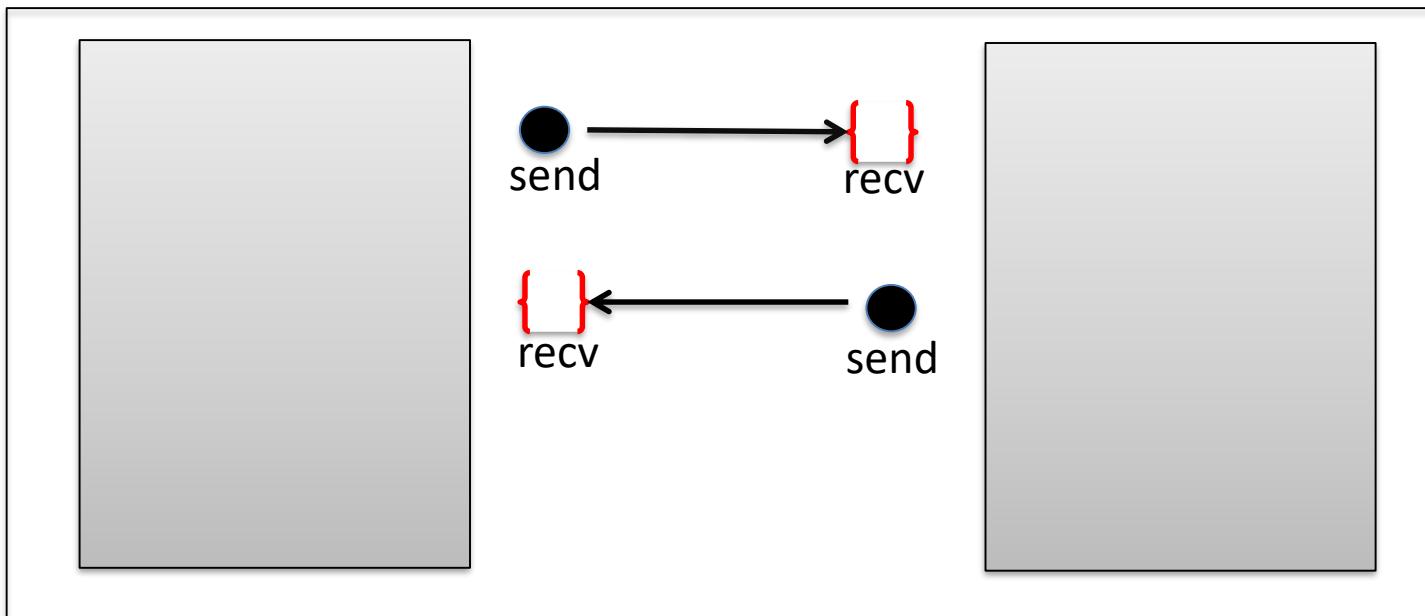
Single System AB

Program A

{ }
scanf { }
 argv

Program B

{ }
scanf { }
 argv



Distributed System AB: sources

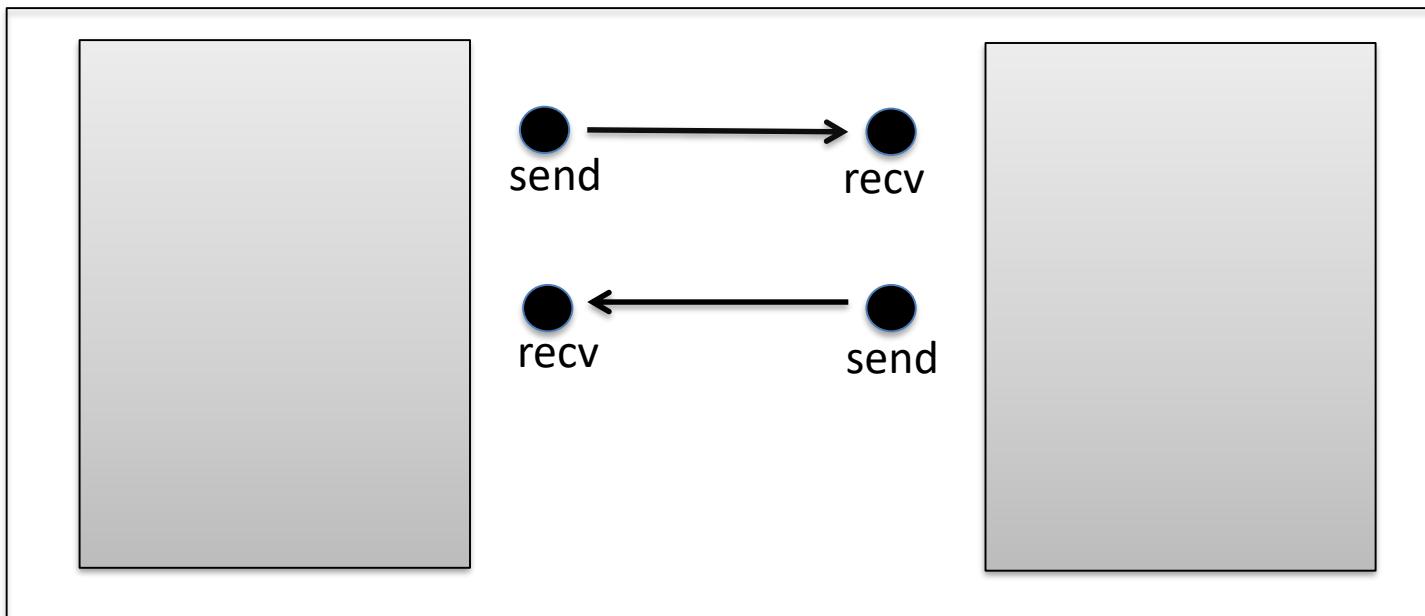
Single System AB

Program A

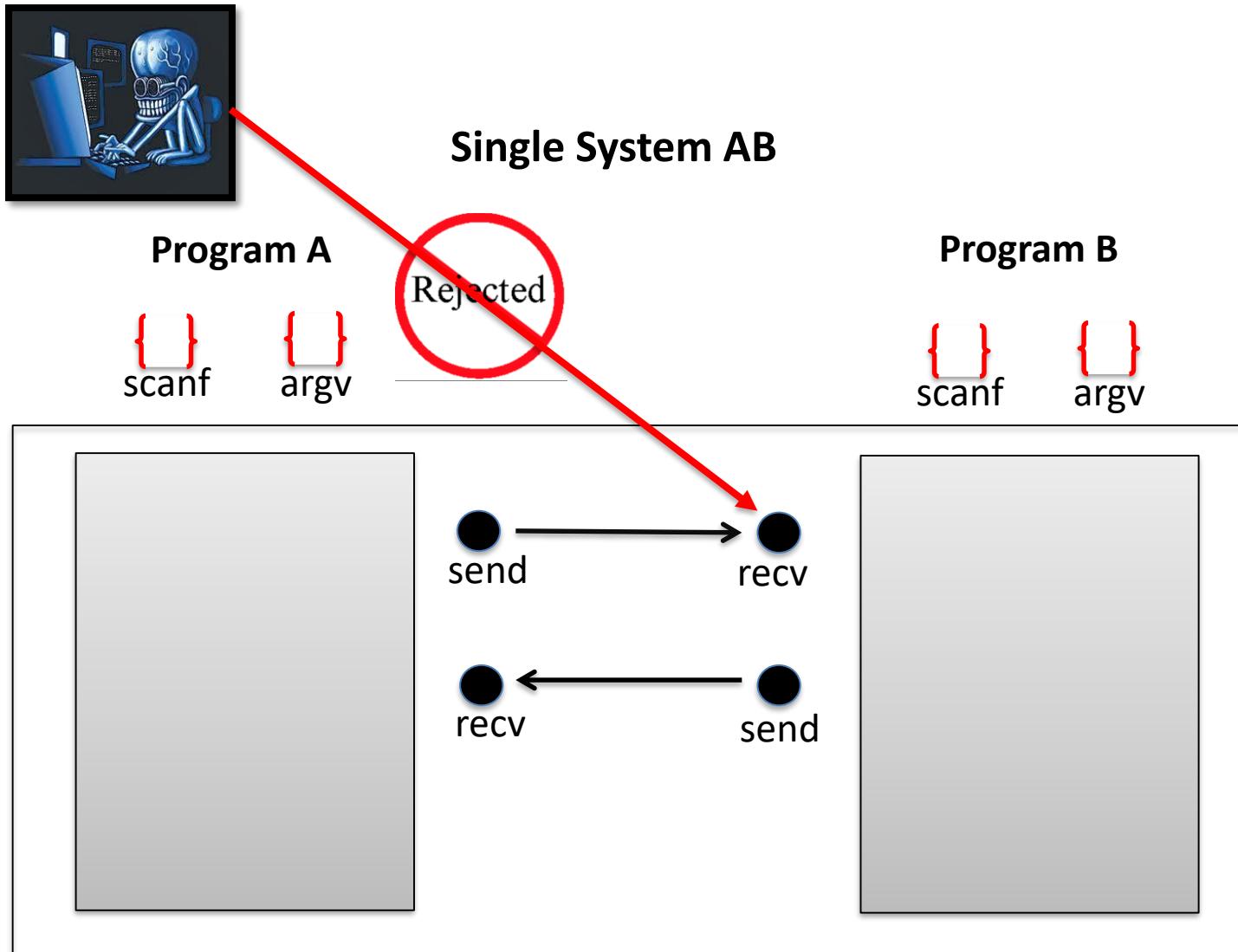
{ }
scanf { }
 argv

Program B

{ }
scanf { }
 argv



Distributed System AB: sources



Distributed System AB: sources



Single System AB

Program A

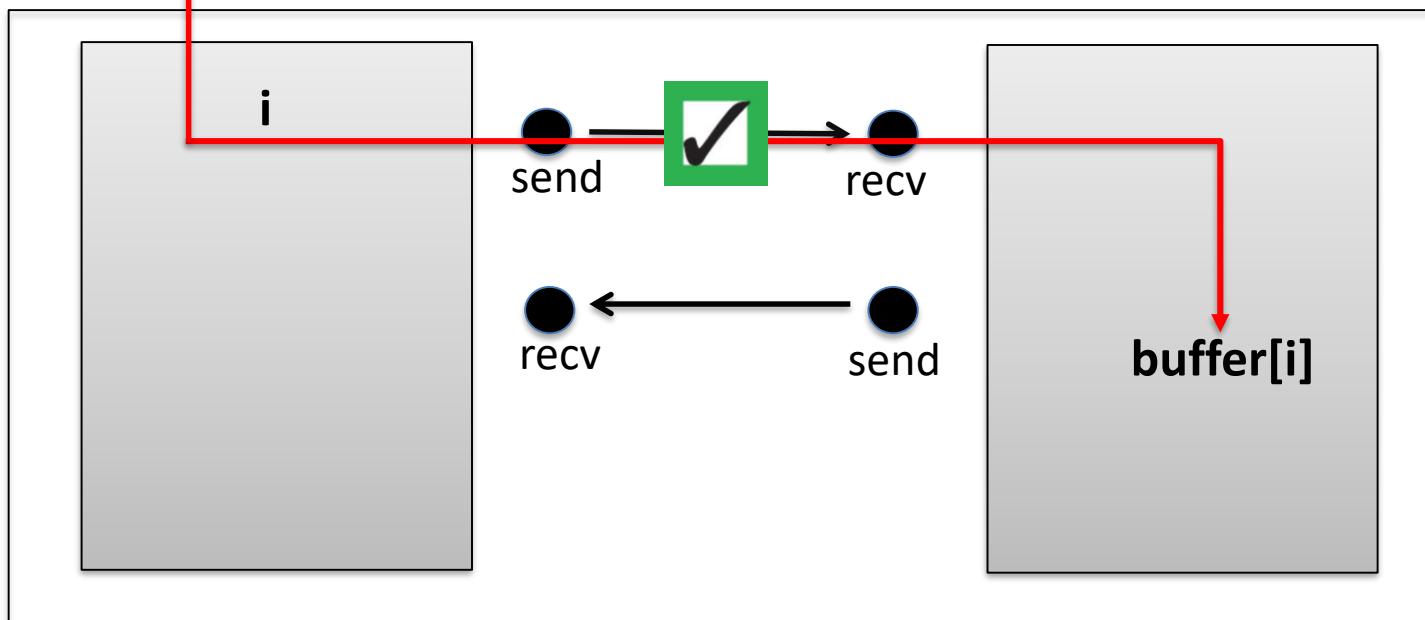
{ }
scanf

{ }
argv

Program B

{ }
scanf

{ }
argv



Distributed System AB

Program A

```
1 send(1);
2 ack = recv();
3 if (ack == 1) {
4     s = getc();
5     while (s != '\0') {
6         send(s)
7         ack = recv();
8         if (ack != 1) {
9             break;
10        } else {
11            s = getc();
12        }
13    }
14    send(s);
15 }
```

Program B

```
(b) 1 msg = recv();
2 if (msg == 1) {
3     send(1);
4     do {
5         msg = recv();
6         putc(msg);
7         if (msg != '\0')
8             send(1);
9         else
10            break;
11     } while (1);
12 } else {
13     send(0);
14 }
```

No longer considered a vulnerability

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SIoT challenge #2

- Face the lack of data-structures to analyze distributed systems
- Control Flow Graphs (CFGs) are the core data-structure in program analysis
- CFGs are not expressive enough to represent programs that communicate over a network, though
 - E.g., they do not handle message exchange between nodes

SIoT key contribution #2

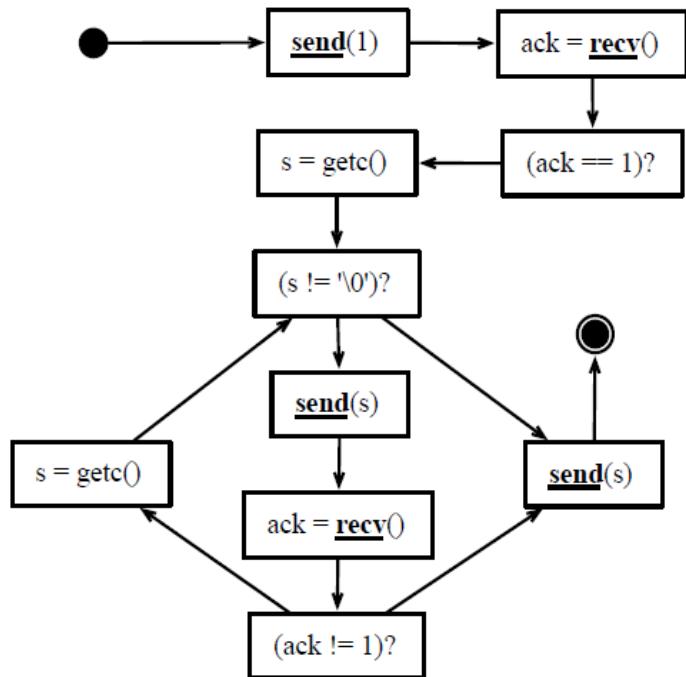
- Distributed Control Flow Graph (DCFG)
- DCFGs are data structures able to bind together the CFGs of all individual programs that constitute a system

CFG

(a)

```

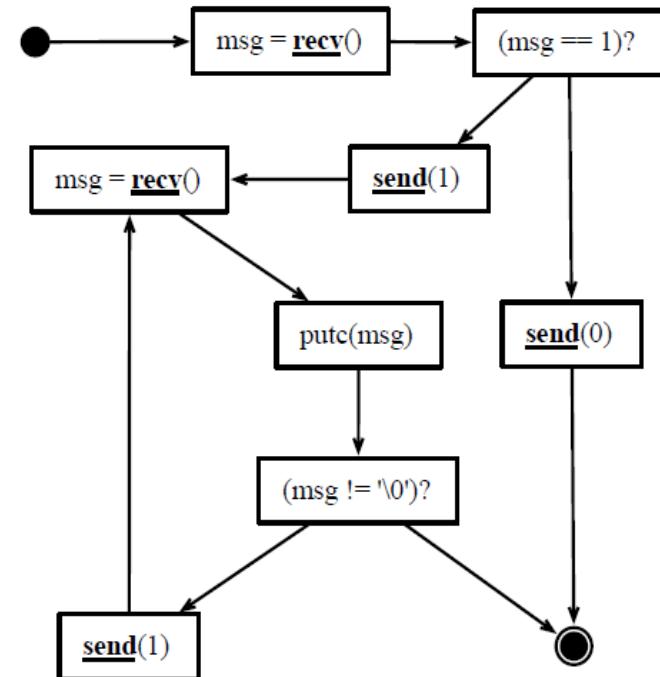
1 send(1);
2 ack = recv()
3 if (ack == 1) {
4     s = getc();
5     while (s != '\0') {
6         send(s)
7         ack = recv();
8         if (ack != 1) {
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10        } else {
11            s = getc();
12        }
13    }
14    send(s);
15 }
```



(b)

```

1 msg = recv();
2 if (msg == 1) {
3     send(1);
4     do {
5         msg = recv();
6         putc(msg);
7         if (msg != '\0')
8             send(1);
9         else
10            break;
11     } while (1);
12 } else {
13     send(0);
14 }
```

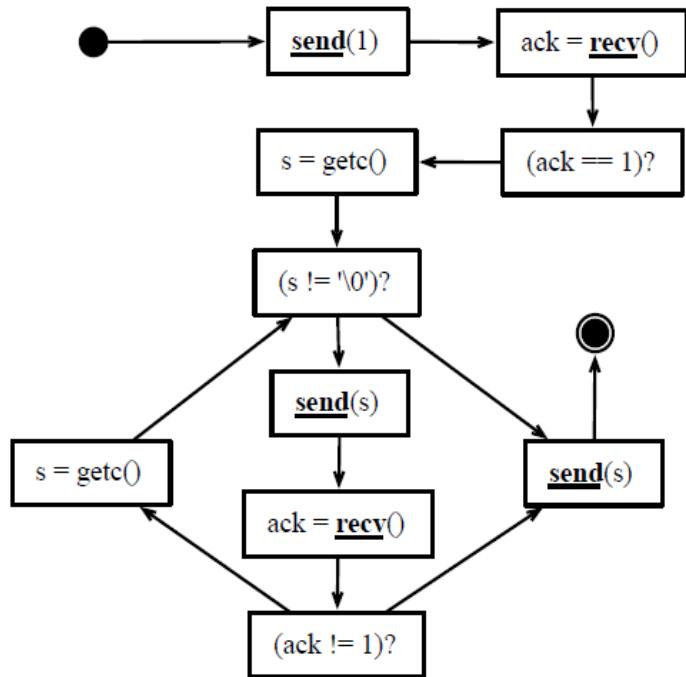


DCFG

(a)

```

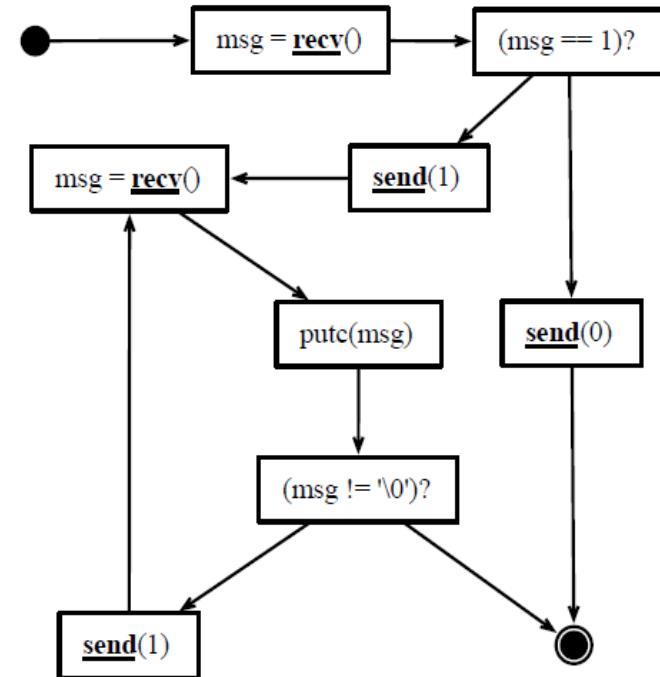
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4     s = getc();
5     while (s != '\0') {
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7         ack = recv();
8         if (ack != 1) {
9             break;
10        } else {
11            s = getc();
12        }
13    }
14    send(s);
15 }
```



(b)

```

1 msg = recv();
2 if (msg == 1) {
3     send(1);
4     do {
5         msg = recv();
6         putc(msg);
7         if (msg != '\0')
8             send(1);
9         else
10            break;
11     } while (1);
12 } else {
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```

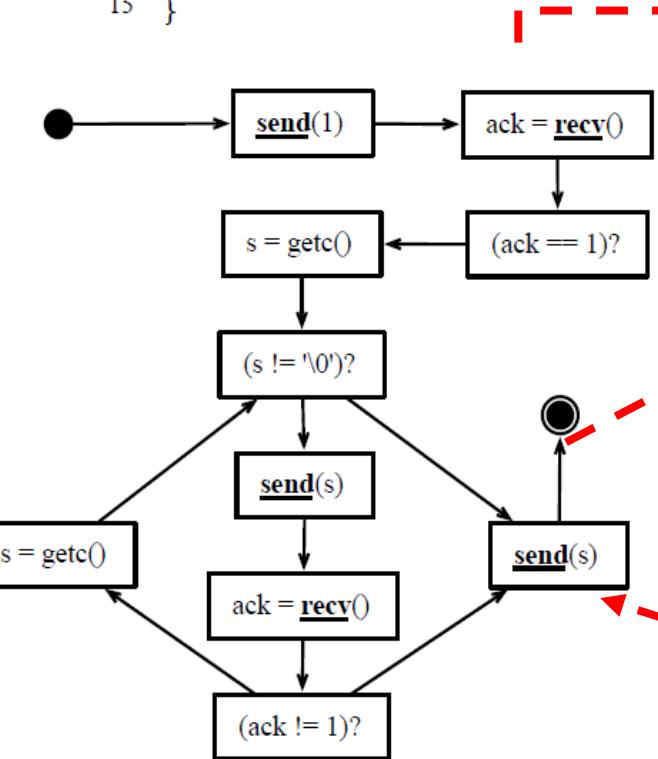


DCFG

(a)

```

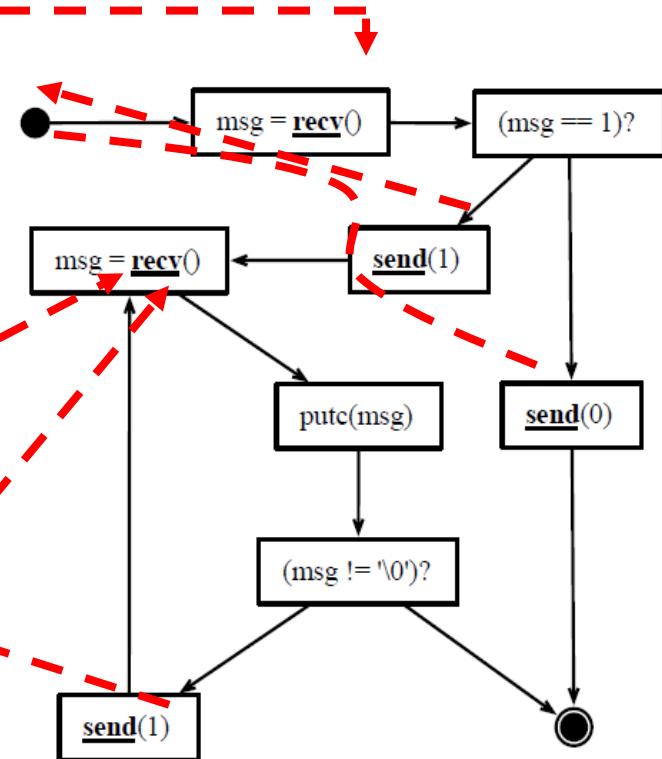
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```



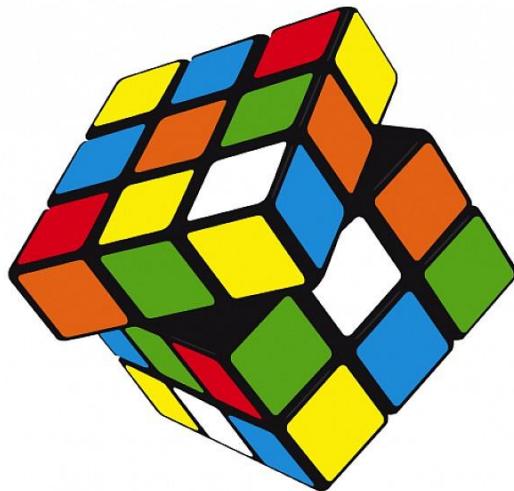
(b)

```

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9         else
10            break;
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12 } else {
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14 }
```



It's not that easy, though



SIoT challenge #3

- To build a DCFG, we have to link the `sends` of a program A with the `recvs` of a program B and vice-versa

```
// node #1
n = 3
while (a^n + b^n != c^n) {
    a = update(a);
    b = update(b);
    c = update(c);
}
x = read()
```

?

```
// node #2
write(y);
```

How to find out which sends link to a recv?

SIoT key contribution #3

- Elevator, an algorithm to selectively link sends/recvs
 1. Elevator assigns levels to sends and recvs
 2. Program A's sends and Program B's recvs in the same level are thus linked together

Elevator: Illustration

- Consider the Echo Client and Server programs

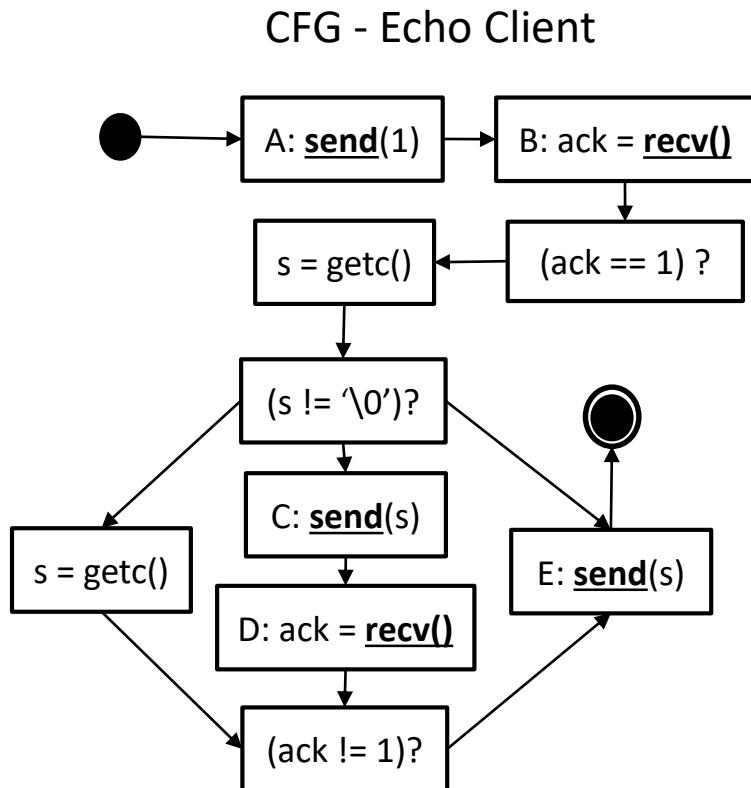
(a) Echo Client

```
1 send(1);
2 ack = recv();
3 if (ack == 1) {
4     s = getc();
5     while (s != '\0') {
6         send(s)
7         ack = recv();
8         if (ack != 1) {
9             break;
10        } else {
11            s = getc();
12        }
13    }
14    send(s);
15 }
```

(b) Echo Server

```
1 msg = recv();
2 if (msg == 1) {
3     send(1);
4     do {
5         msg = recv();
6         putc(msg);
7         if (msg != '\0')
8             send(1);
9         else
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14 }
```

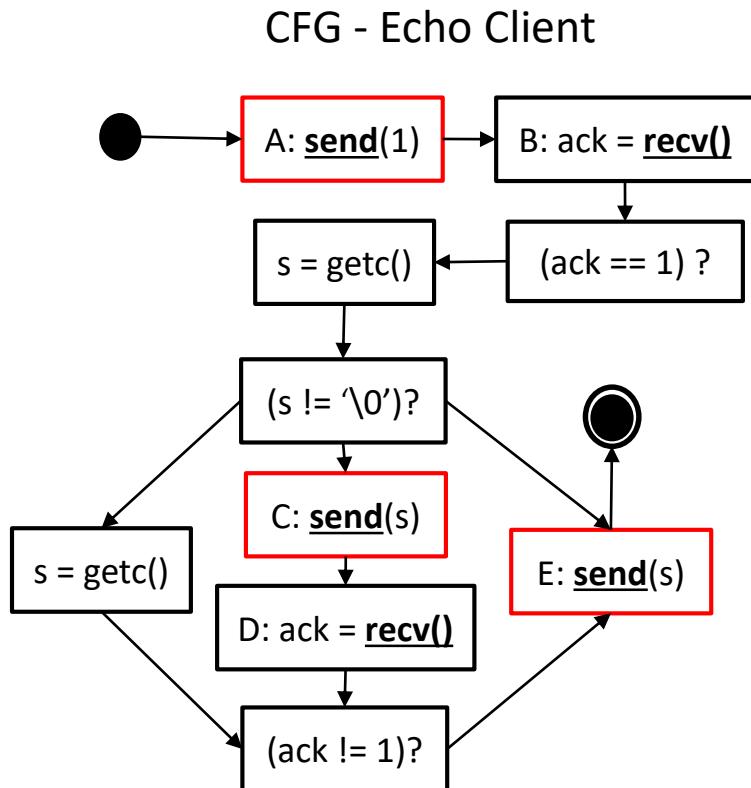
Echo Client CFG



(a) Echo Client

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7         ack = recv();
8         if (ack != 1) {
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13    }
14 }
15 }
```

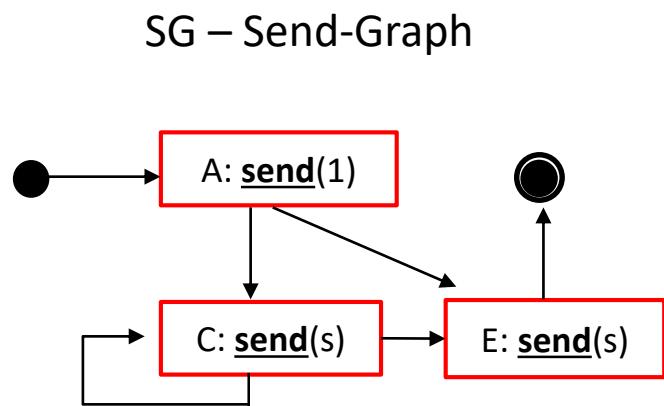
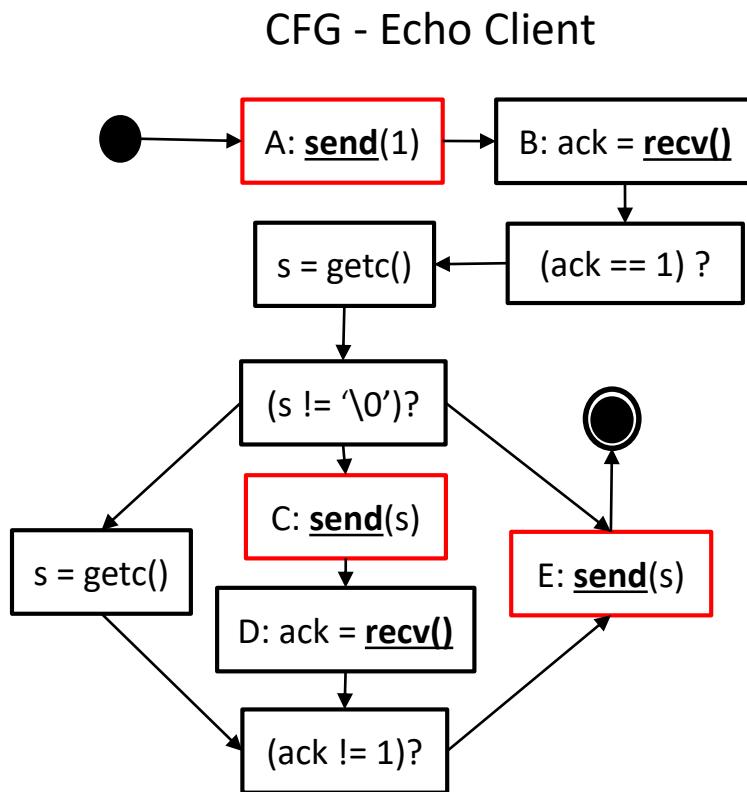
Extract Echo Client's Send-Graph



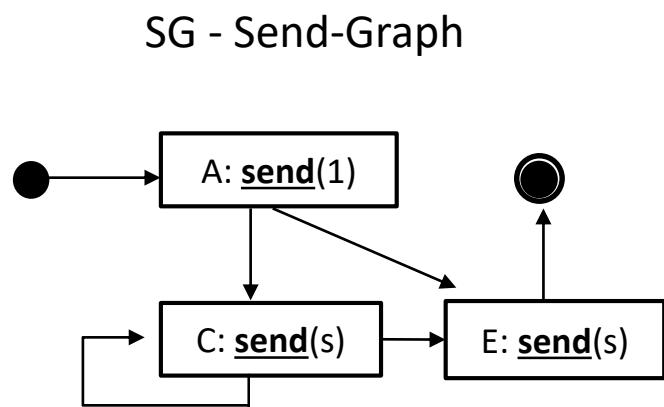
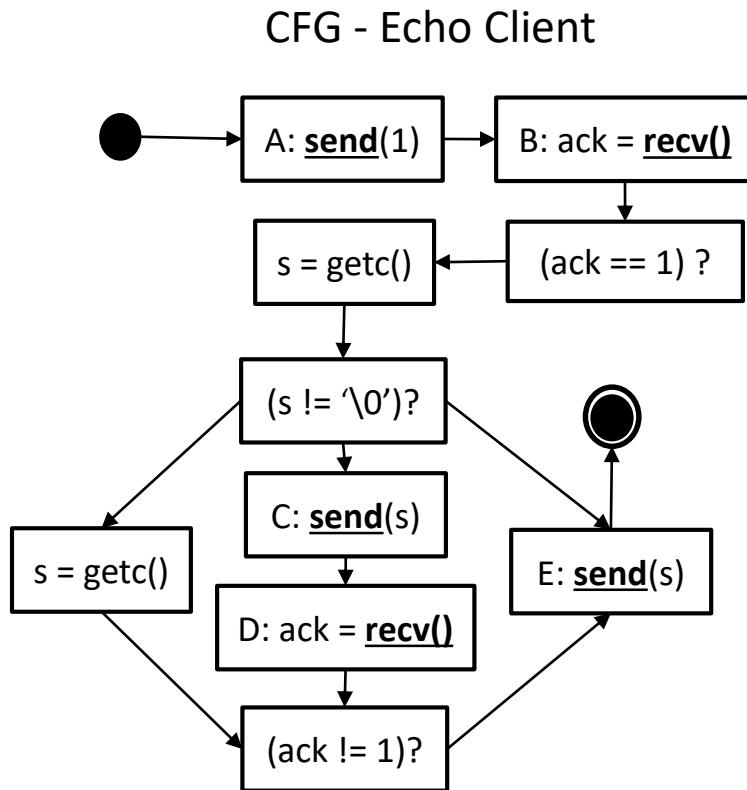
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14 }
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```

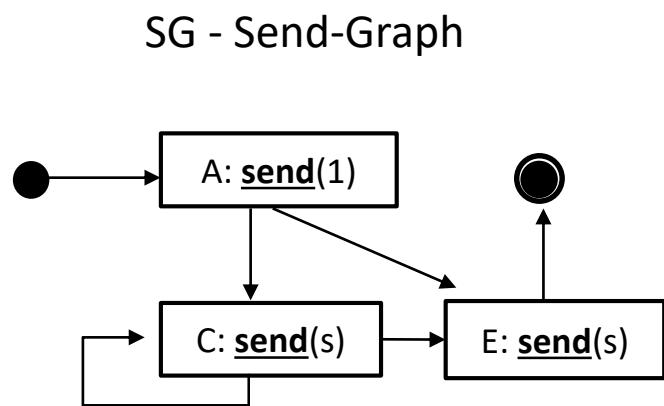
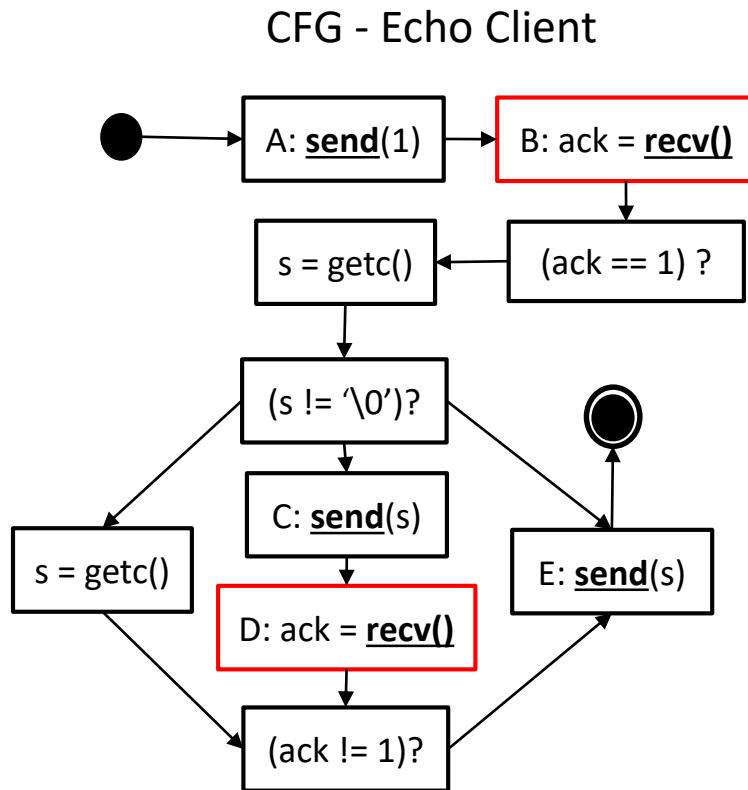
Extract Echo Client's Send-Graph



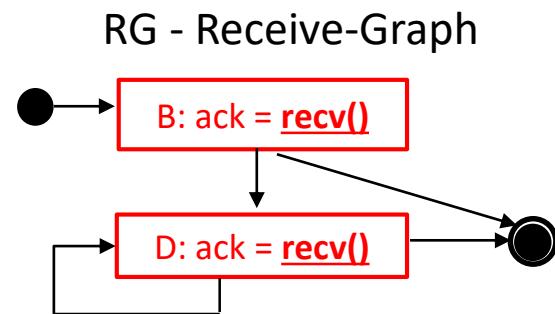
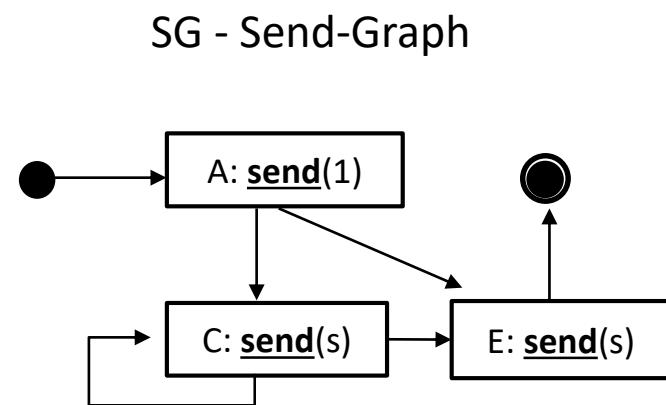
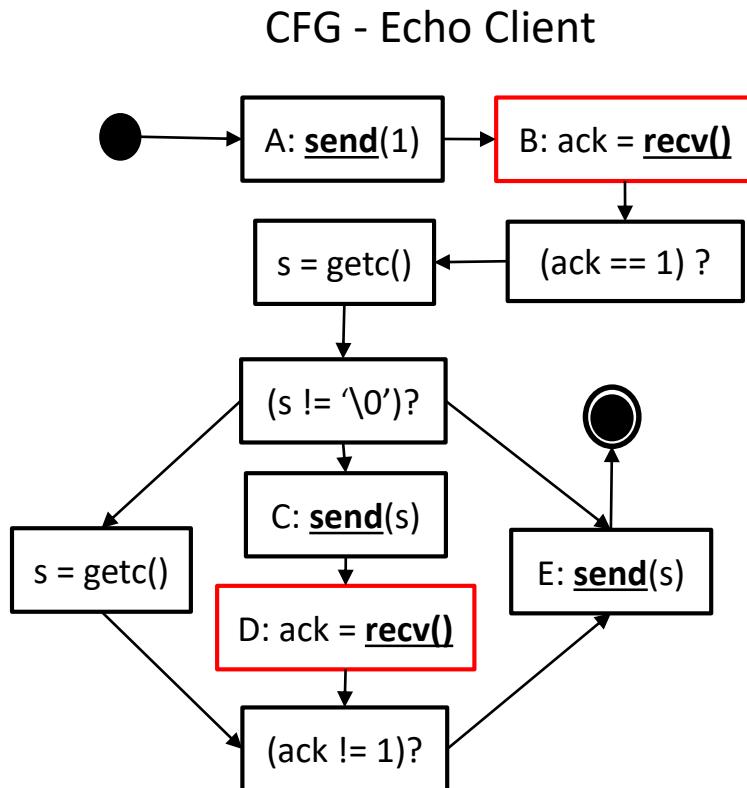
Extract Echo Client's Receive-Graph



Extract Echo Client's Receive-Graph

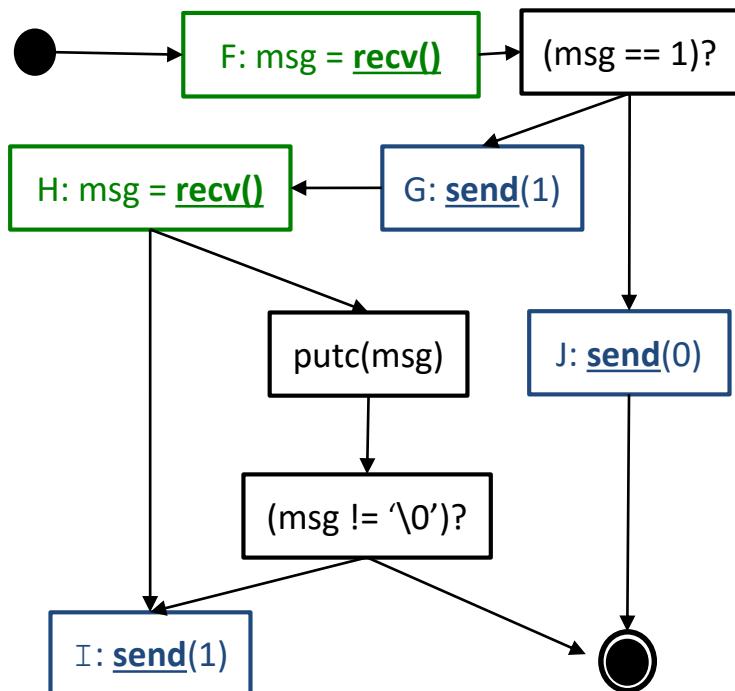


Extract Echo Client's Receive-Graph

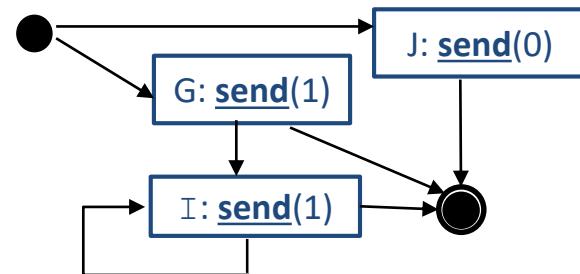


Ditto for Echo Server

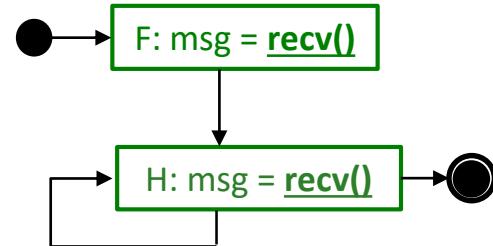
CFG - Echo Server



SG - Send-Graph

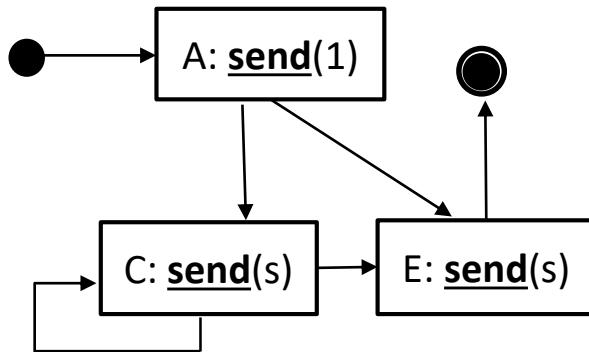


RG - Receive-Graph



Level Assignment

Echo Client: Send-Graph

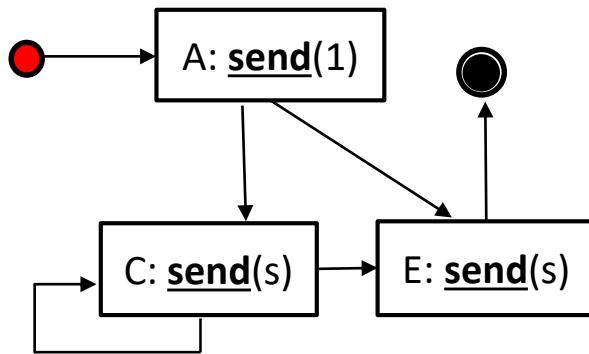


```
Elevator (Graph G) /* toy version*/  
start.level := 0  
While { sets are different }  
  For each vertex v in G  
    If v is reachable from u  
      then v.level := (u.level+1)  
    end  
  end  
end  
end
```

$$\begin{aligned} level(mg, 0) &= \{ start \} \\ level(mg, n) &= \{ v \mid \overrightarrow{uv} \in mg \wedge u \in level(mg, n-1) \} \end{aligned}$$

Level Assignment

SG – Echo Client



Level of Senders:

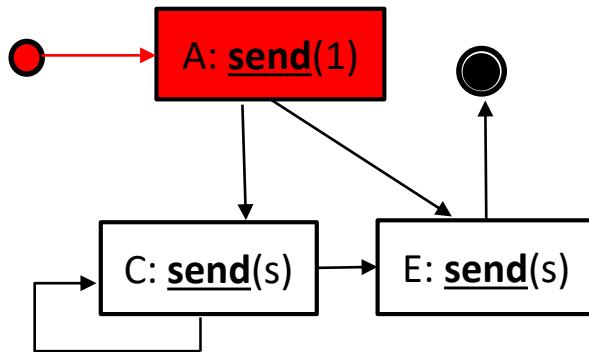
level set

0 { start }

```
Elevator (Graph G) /* toy version*/
start.level := 0
While { sets are different }
  For each vertex v in G
    If v is reachable from u
      then v.level := (u.level+1)
    end
  end
end
end
```

Level Assignment

Echo Client: Send-Graph



Level of Senders:

level set

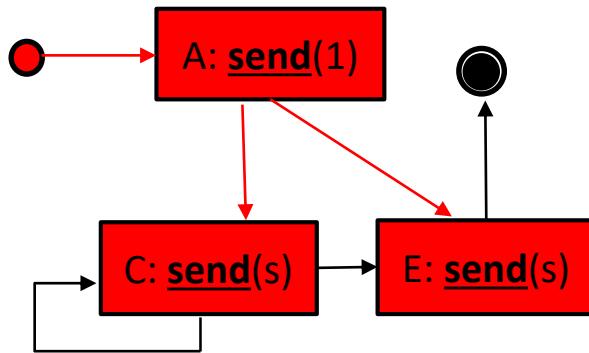
0 { start }

1 { A }

```
Elevator (Graph G) /* toy version*/
start.level := 0
While { sets are different }
  For each vertex v in G
    If v is reachable from u
      then v.level := (u.level+1)
    end
  end
end
end
```

Level Assignment

Echo Client: Send-Graph



Level of Senders:

level set

0 { start }

1 { A }

2 { C, E }

Elevator (Graph G) /* toy version */

start.level := 0

While { sets are different }

For each vertex v in G

If v is reachable from u

 then v.level := (u.level+1)

 end

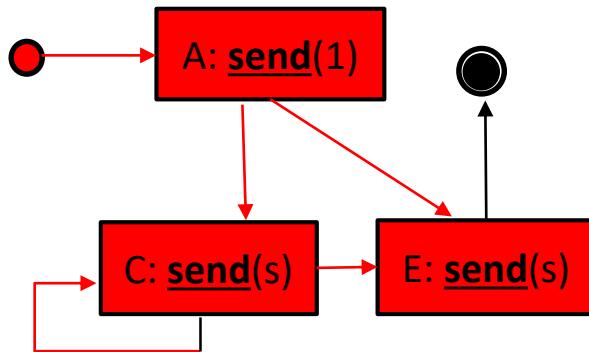
 end

 end

end

Level Assignment

Echo Client: Send-Graph



Level of Senders:

level *set*

0 { start }

1 { A }

2 { C, E }

3 { C, E }

Elevator (Graph G) /* toy version */

start.level := 0

While { sets are different }

For each vertex v in G

If v is reachable from u

 then v.level := (u.level+1)

 end

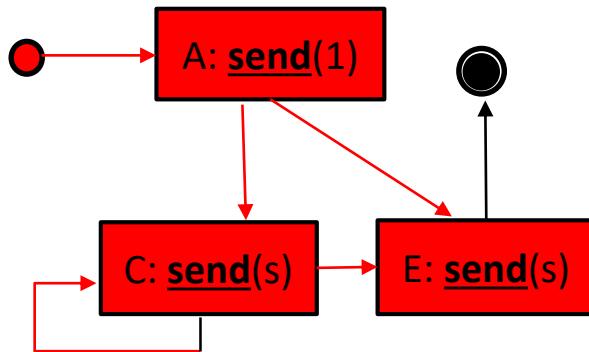
 end

 end

end

Level Assignment

Echo Client: Send-Graph



Level of Senders:

level set

0 { start }

1 { A }

2 { C, E }

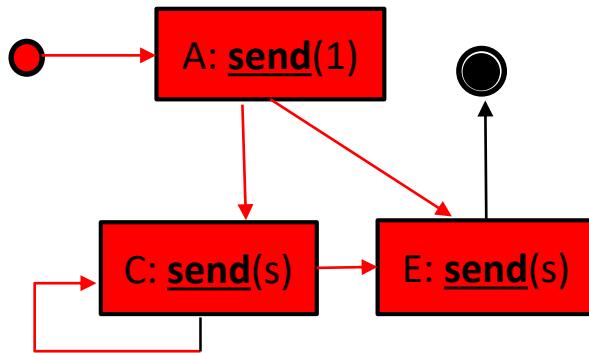
3 { C, E }

```
Elevator (Graph G) /* toy version*/
start.level := 0
While { sets are different }
  For each vertex v in G
    If v is reachable from u
      then v.level := (u.level+1)
    end
  end
end
end
```

the algorithm halts whenever sets stop changing

Level Assignment

Echo Client: Send-Graph



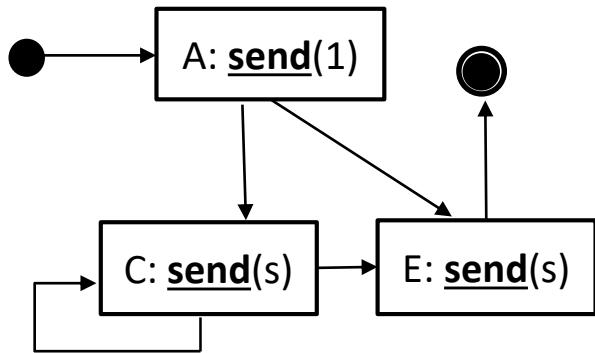
Level of Senders:

<i>level</i>	<i>set</i>
0	{ start }
1	{ A }
2	{ C, E }
3	{ C, E }

```
Elevator (Graph G) /* toy version*/
start.level := 0
While { sets are different }
  For each vertex v in G
    If v is reachable from u
      then v.level := (u.level+1)
    end
  end
end
end
```

Level Assignment: Ditto for Recv-Graph

Echo Client: Send-Graph

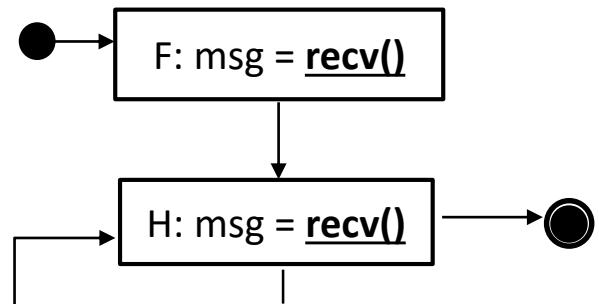


Level of Senders:

level *set*

0	{ start }
1	{ A }
2	{ C, E }
3	{ C, E }

Echo Server: Recv-Graph



Level of Receivers:

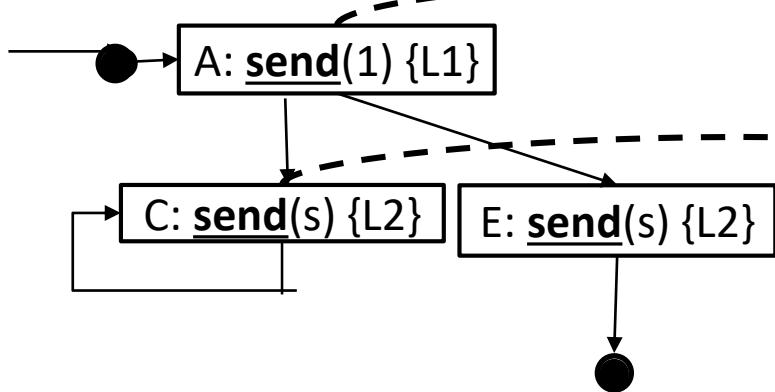
level *set*

0	{ root }
1	{ F }
2	{ H }
3	{ H }

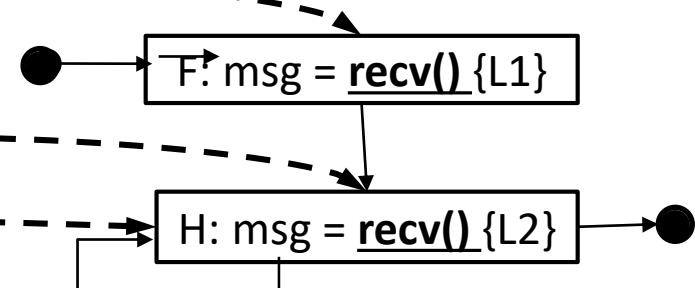
DCFG construction final step

- Link Client's sends with Server's recv's if they are belong to the same level, and vice-versa

Echo Client: Send-Graph



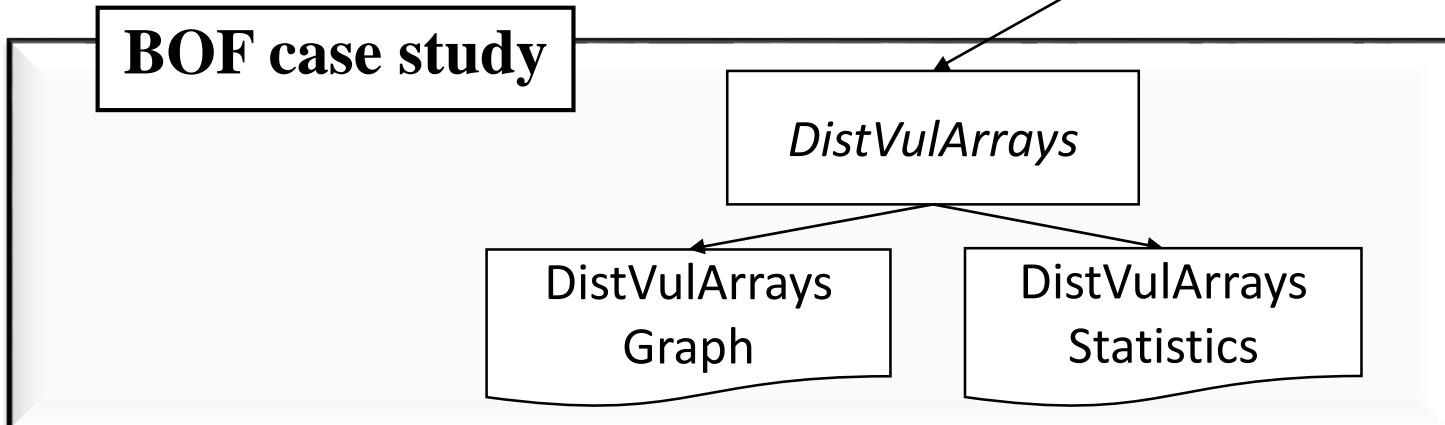
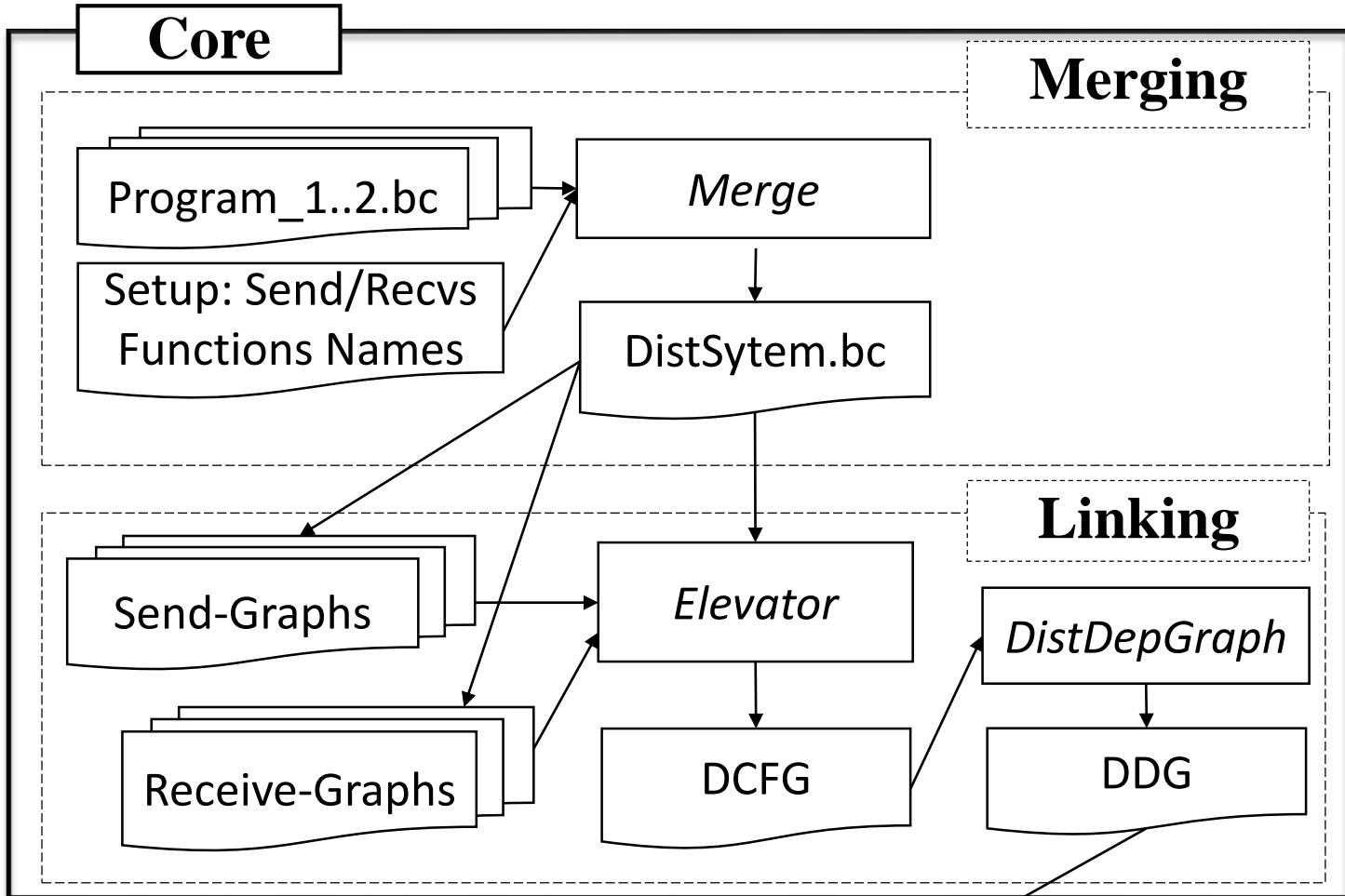
Echo Server: Recv-Graph



Agenda

- Introduction
- Goal
- Solution
 - Conception
 - Refinement
 - Development
- Results
- Conclusion

SiLoT Coding



SiLoT is publicly available

 **ecosoc**
Software security with low energy consumption

[Project Home](#) [Wiki](#) [Issues](#) [Source](#) [Administer](#) [Export to GitHub](#)

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SiLoT
SiLoT is a framework to analyze networked systems.

Updated Feb 11, 2015 by [teixeirac](#)

SiLoT

SiLoT is a framework to analyze networked systems. SiLoT's key insight is to look at a distributed system as a single body, and not as separate programs that exchange messages. By doing so, we can crosscheck information inferred from different nodes. This crosschecking increases the precision of traditional static analyses. To construct this global view of a distributed system we introduce a novel algorithm that discovers inter-program links efficiently. Such links lets us build a holistic view of the entire network, a knowledge that we can thus forward to a traditional tool. SiLoT was implemented on top of [LLVM](#).

Access the SiLoT [code](#), see the [README](#) to getting start and enjoy it!

<https://code.google.com/p/ecosoc/wiki/SiLoT>

Agenda

- Introduction
- Goal
- Solution
- **Results**
- Conclusion

Evaluation

- We have compared SloT against the state-of-the-art approach
 - Tainted flow analysis followed by ABCs insertion
 - We called this approach *Baseline*
 - Our hypothesis was that SloT would insert less ABCs than Baseline and thus end up being more efficient
- We have used real IoT code in our evaluation
 - I.e., ContikiOS applications



SloT Static Analysis

- It takes on average 66s and consumed 170 MB of RAM
 - In a Intel Core i7 2.2GHz laptop
 - Memory obtained via Valgrind
 - Time taken through Unix time
- It's done offline and does not represent a burden to nodes

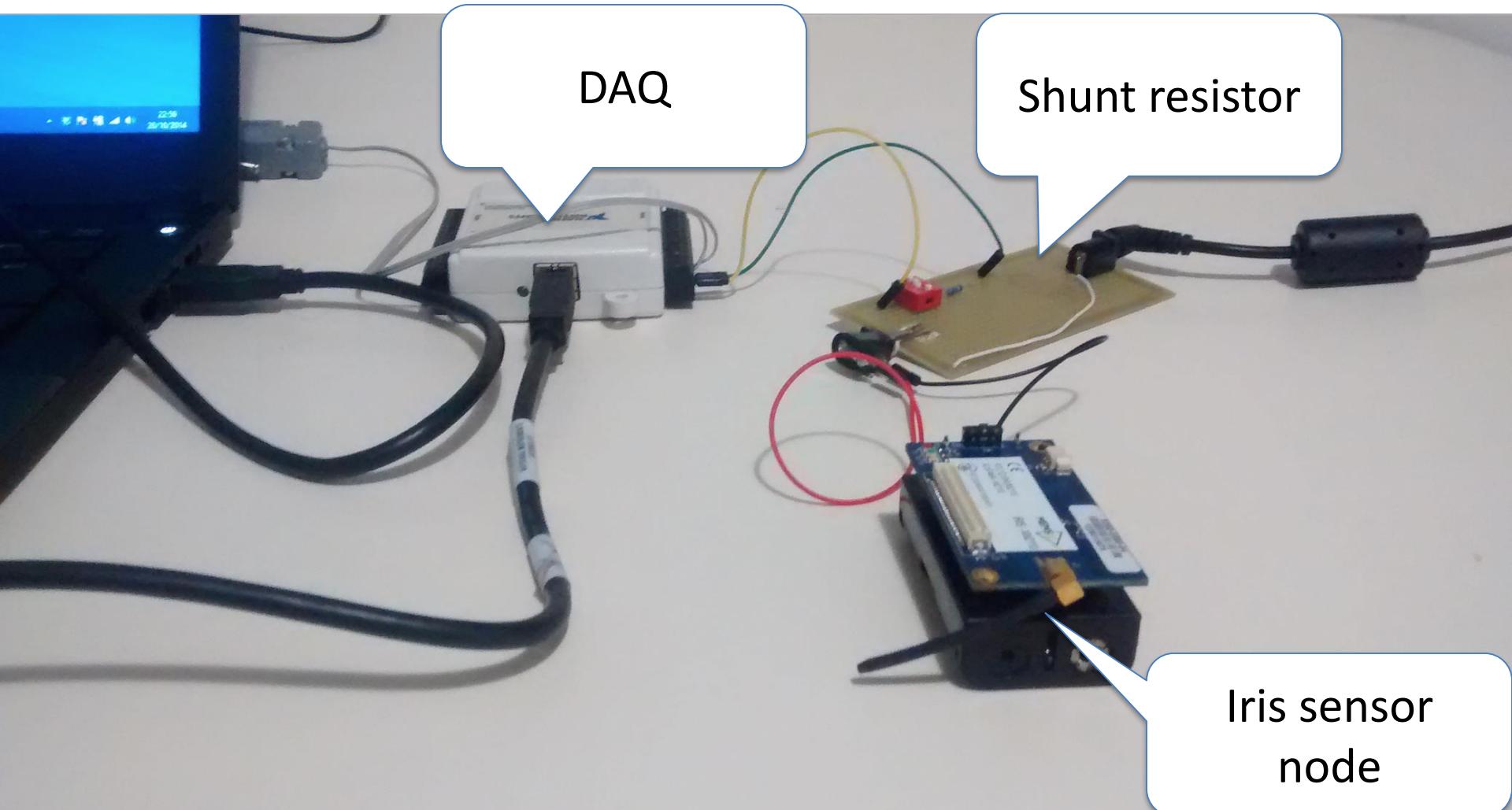
Application	Instructions	Time (s)	Memory (MB)
netdb client/server	57,877	66.24	210.03
ping / new-ipv6	47,422	63.58	167.36
ipv6-rpl-collect udp-sender/sink	48,800	80.08	173.37
ipv6-rpl-udp client/server	48,226	66.31	169.90
udp-ipv6 client/server	48,800	80.08	167.39
coap-client / rest-server	51,258	54.36	179.68

ABCs Insertion

- SIoT reduces the number of ABCs insertion by around 10x compared to Baseline in our benchmark

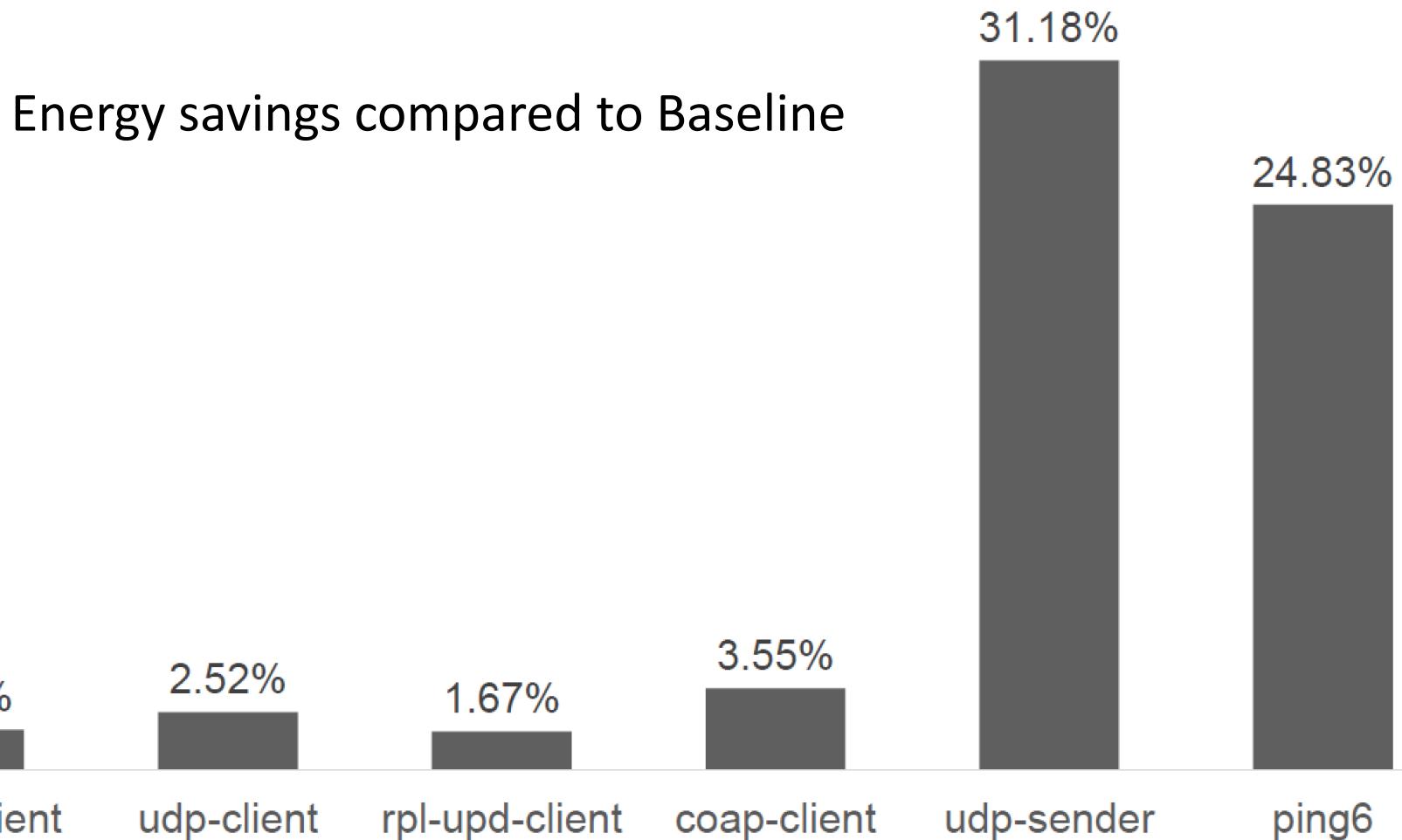
Applications	Memory Accesses	ABCs inserted		% ABCs Reduction SIoT vs Baseline
		Baseline	SIoT	
netdb client/server	22,819	172	16	90.70%
ping6 / new-ipv6	16,871	166	14	91.57%
ipv6-rpl-collect udp-sender / sink	17,301	168	14	91.67%
ipv6-rpl-udp client/server	17,162	170	14	91.76%
udp-ipv6 client/server	16,945	212	14	93.40%
coap-client / rest-server	18,693	214	14	93.46%

Experiment Setup



Iris sensor
node

SiOT Dynamic Analysis



Agenda

- Introduction
- Goal
- Solution
- Results
- Conclusion

Conclusions

SIoT

1. Sees and analyze individual programs of a distributed system as a single system
2. Protects IoT code around 20% more energy-efficiently than state-of-the-art approach
3. Is publicly available

Besides, we came up with

1. Distributed Control Flow Graphs – DCFGs
2. Elevator, an alg. that is able to link sends/recvs

Thanks

www.ecosoc.dcc.ufmg.br

leonardo.barbosa@dcc.ufmg.br

Algorithm 1: Elevator

Input: CFGs $\{\mathcal{C}_1, \mathcal{C}_2\}$, Send-Graphs $\{\mathcal{S}_1, \mathcal{S}_2\}$ and Receive-Graphs $\{\mathcal{R}_1, \mathcal{R}_2\}$.

Output: a DCFG \mathcal{D}

▷ Set the SEND and RECV levels

foreach $G_i \in \{\mathcal{S}_1, \mathcal{S}_2\} \cup \{\mathcal{R}_1, \mathcal{R}_2\}$ **do**

$n \leftarrow 0$

$L_{G_i,n} \leftarrow \{root\}$

 ▷ While the new generated set $L_{G_i,n}$ is unique

while $L_{G_i,n} \neq \emptyset$ **and** $L_{G_i,n} \neq L_{G_i,0..n-1}$ **do**

foreach vertex v in $L_{G_i,n}$ **do**

$S_{succs} \leftarrow$ successors of v

$L_{G_i,n+1} \leftarrow L_{G_i,n+1} \cup S_{succs}$

$n \leftarrow n + 1$

 ▷ Link SENDs and RECVs of the same level

$\mathcal{D} \leftarrow \mathcal{C}_1 \cup \mathcal{C}_2$

for $k \leftarrow 1$ **to** n **do**

foreach $v_s \in L_{\mathcal{S}_1,k}$ **and** $v_r \in L_{\mathcal{R}_2,k}$ **do**

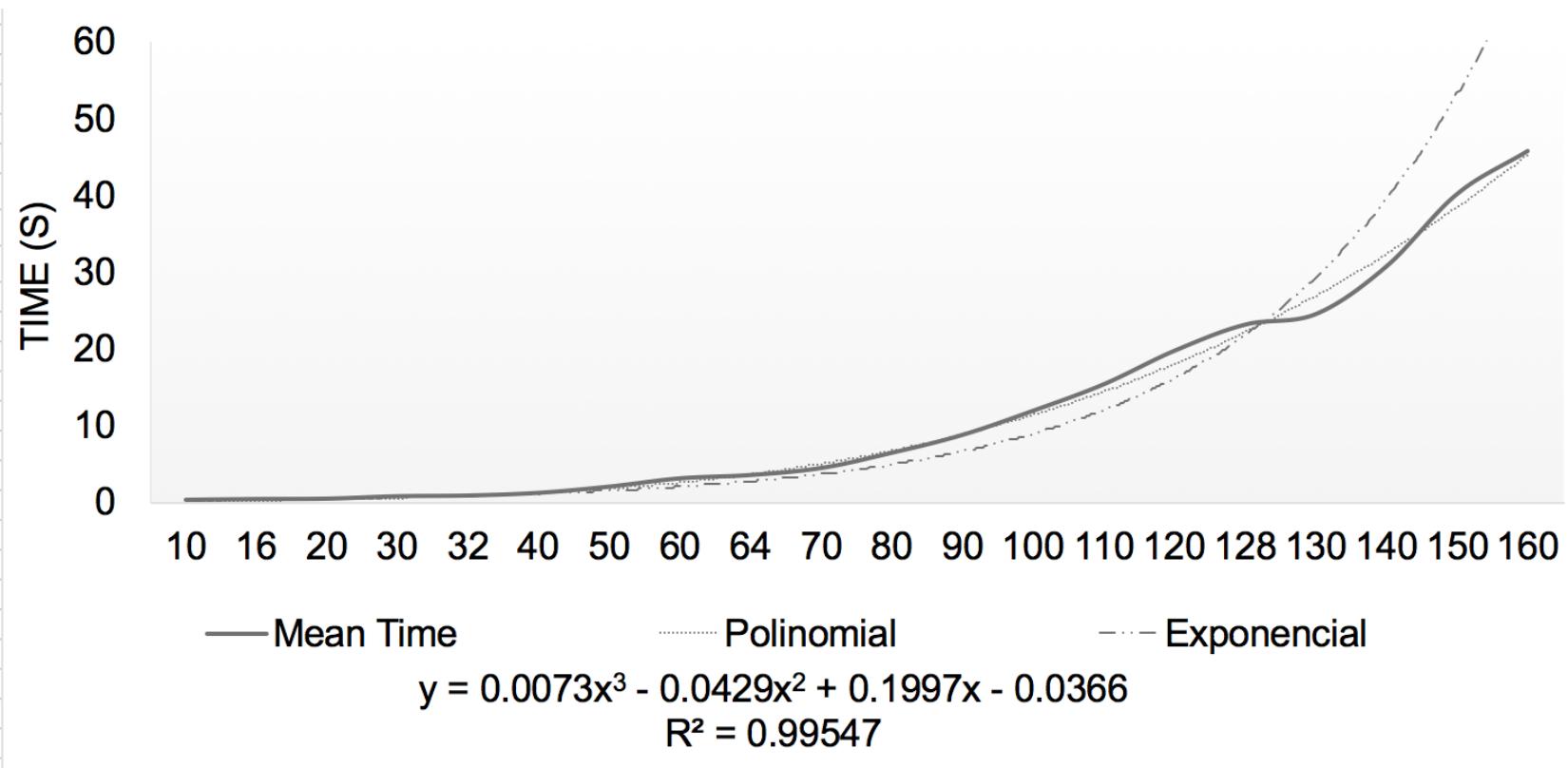
 add an edge from v_s to v_r in \mathcal{D}

foreach $v_r \in L_{\mathcal{R}_1,k}$ **and** $v_s \in L_{\mathcal{S}_2,k}$ **do**

 add an edge from v_s to v_r in \mathcal{D}

Elevator Asymptotic Complexity

- Runtime as a function of the number of CGFs vertices
- In practice, $O(n^3)$ where n is the number of vertices



Related Work

- There are works that already focused on IoT software correctness and security
 - Cooprider et al. Safe TinyOS (Sensys'07)
 - Li and Regehr. Kleenet. (IPSN'10)
 - Sasnauskas et al. T-Check. (IPSN'10)
- These works don't look at IoT as a single system and we believe ours is complementary to their strategies
 - I.e., SloT can potentially improve their numbers

ABC Cost

ABCs' Computational Cost

buffer[i] = a;



```
mrmovl -12(%ebp), %eax      Load 'i'  
mrmovl -4(%ebp), %edx  
rrmovl %eax, %edi  
sall $2, %edi  
addl %ebp, %edi  
rmmovl %edx, -2060(%edi)
```

ABCs' Computational Cost

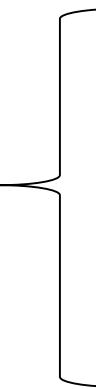
buffer[i] = a;



```
mrmovl -12(%ebp), %eax      Load 'i'  
mrmovl -4(%ebp), %edx       Load 'a'  
rrmovl %eax, %edi  
sall $2, %edi  
addl %ebp, %edi  
rmmovl %edx, -2060(%edi)
```

ABCs' Computational Cost

buffer[i] = a;



```
mrmovl -12(%ebp), %eax      Load 'i'  
mrmovl -4(%ebp), %edx       Load 'a'  
rrmovl %eax, %edi  
sall $2, %edi  
addl %ebp, %edi  
rmmovl %edx, -2060(%edi)
```

Adjust base register

ABCs' Computational Cost

buffer[i] = a;



```
mrmovl -12(%ebp), %eax      Load 'i'  
mrmovl -4(%ebp), %edx       Load 'a'  
rrmovl %eax, %edi  
sall $2, %edi                Adjust base register  
addl %ebp, %edi  
rmmovl %edx, -2060(%edi)    Move
```

ABCs' Computational Cost

```
if( (i>= 0) {  
    mrmovl -12(%ebp), %edi      Load 'i'  
    irmovl $0, %ebx  
    subl %ebx, %edi  
    js L3  
}  
(i < BUFFERSIZE) {  
    mrmovl -12(%ebp),%edi      Load 'i'  
    irmovl $511, %ebx  
    subl %ebx, %edi  
    jg L3  
}  
buffer[i] = a; {  
    mrmovl -12(%ebp), %eax      Load 'i'  
    mrmovl -4(%ebp), %edx      Load 'a'  
    rrmovl %eax, %edi  
    sall $2, %edi  
    addl %ebp, %edi  
    rmmovl %edx, -2060(%edi)  Move  
}
```

ABCs' Computational Cost

if((i>= 0)	mrmovl -12(%ebp), %edi irmovl \$0, %ebx subl %ebx, %edi js L3	Load 'i' Load lower index
(i < BUFFERSIZE))	mrmovl -12(%ebp),%edi irmovl \$511, %ebx subl %ebx, %edi jg L3	Load 'i' Load upper index
buffer[i] = a;	mrmovl -12(%ebp), %eax mrmovl -4(%ebp), %edx rrmovl %eax, %edi sall \$2, %edi addl %ebp, %edi rmmovl %edx, -2060(%edi)	Load 'i' Load 'a' Adjust base register Move

ABCs' Computational Cost

if((i>= 0)	mrmovl -12(%ebp), %edi irmovl \$0, %ebx subl %ebx, %edi js L3	Load 'i' Load lower index Compare
(i < BUFFERSIZE))	mrmovl -12(%ebp),%edi irmovl \$511, %ebx subl %ebx, %edi jg L3	Load 'i' Load upper index Compare
buffer[i] = a;	mrmovl -12(%ebp), %eax mrmovl -4(%ebp), %edx rrmovl %eax, %edi sall \$2, %edi addl %ebp, %edi rmmovl %edx, -2060(%edi)	Load 'i' Load 'a' Adjust base register Move

Full BOF example

Vulnerable Code

```
#include <stdio.h>
void foo(FILE *badfile) {
    char buffer[12];
    ...
    fread(buffer,sizeof(char),517,badfile);
    ...
    return 1;
}

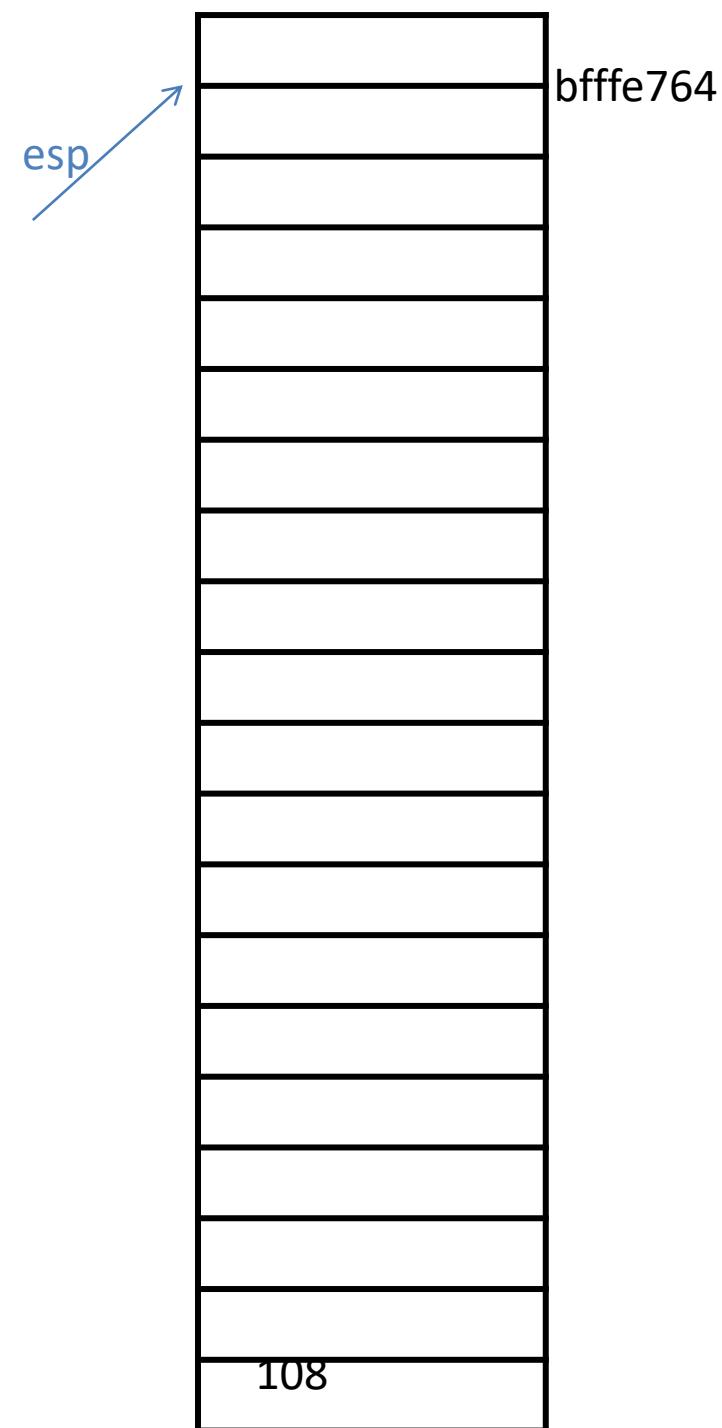
int main() {
    FILE *badfile;
    badfile = fopen("file","r");
    foo(badfile);
    fclose(badfile);
    return 1;
}
```

foo:

```
pushl    %ebp
movl %esp, %ebp
subl $40, %esp
...
movl 8(%ebp), %edx
movl %edx, 12(%esp)
movl $517, 8(%esp)
movl $1, 4(%esp)
movl %eax, (%esp)
call fread
movl $1, %eax
leave
ret
```

main:

```
...
movl %eax, (%esp)
call foo
...
$1, %eax
leave
ret
```



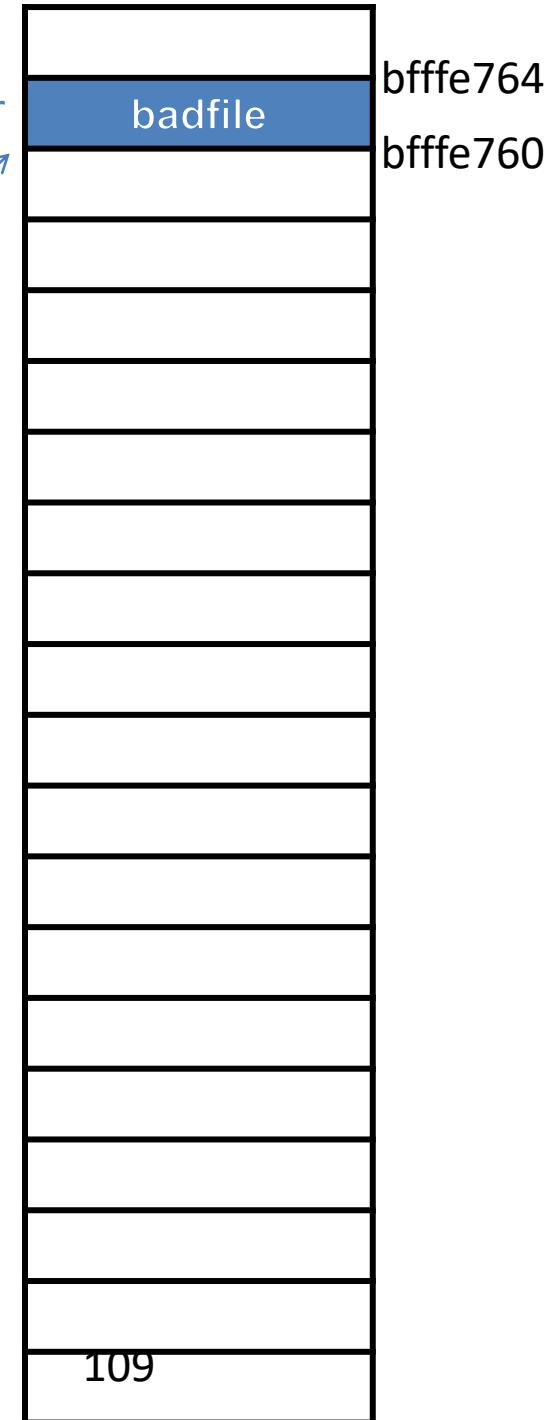
foo:

```
pushl  %ebp
movl %esp, %ebp
subl $40, %esp
...
movl 8(%ebp), %edx
movl %edx, 12(%esp)
movl $517, 8(%esp)
movl $1, 4(%esp)
movl %eax, (%esp)
call fread
movl $1, %eax
leave
ret
```

main:

```
...
movl %eax, (%esp)
call foo
...
$1, %eax
leave
ret
```

Parameter
esp

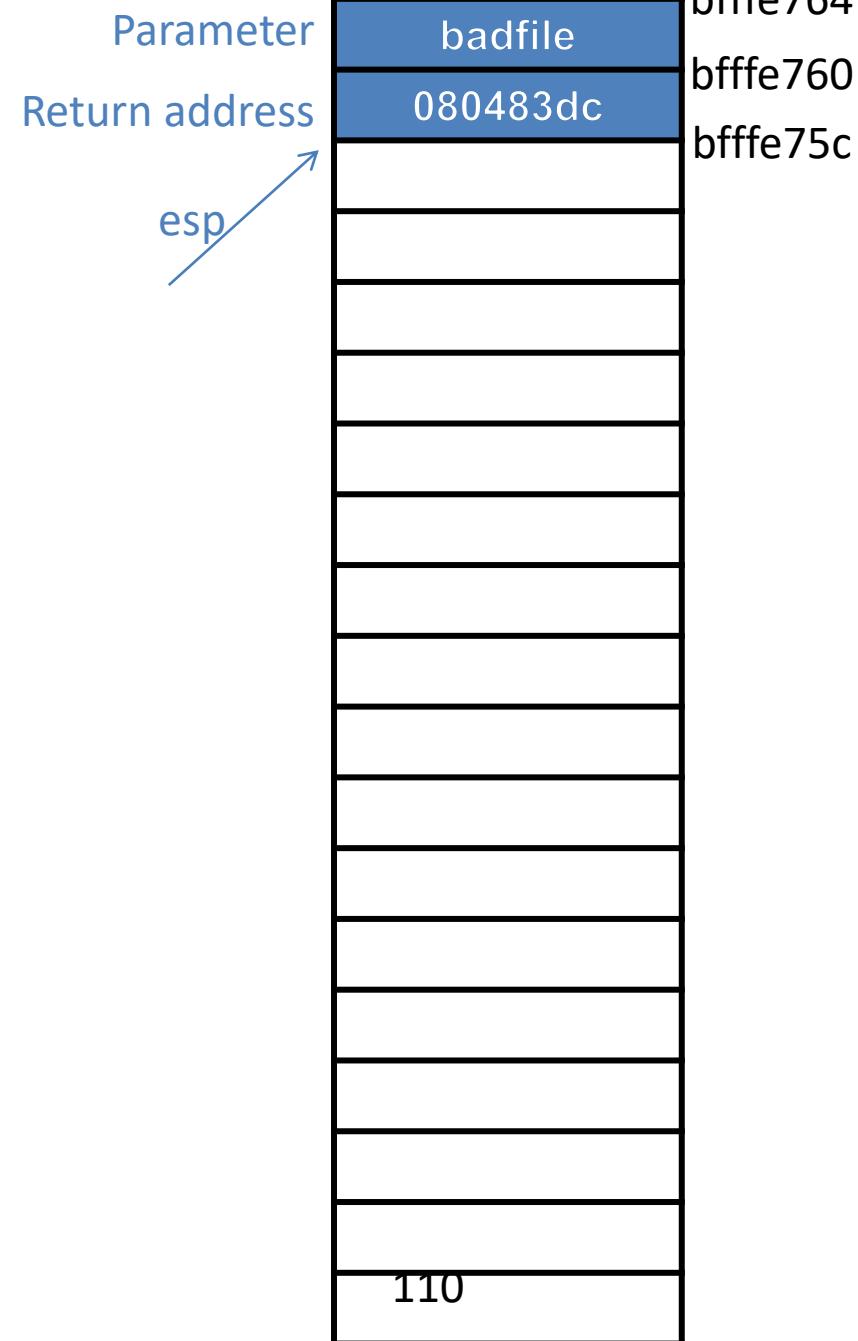


foo:

```
pushl  %ebp
movl %esp, %ebp
subl $40, %esp
...
movl 8(%ebp), %edx
movl %edx, 12(%esp)
movl $517, 8(%esp)
movl $1, 4(%esp)
movl %eax, (%esp)
call fread
movl $1, %eax
leave
ret
```

main:

```
...
movl %eax, (%esp)
call foo
...
$1, %eax
leave
ret
```

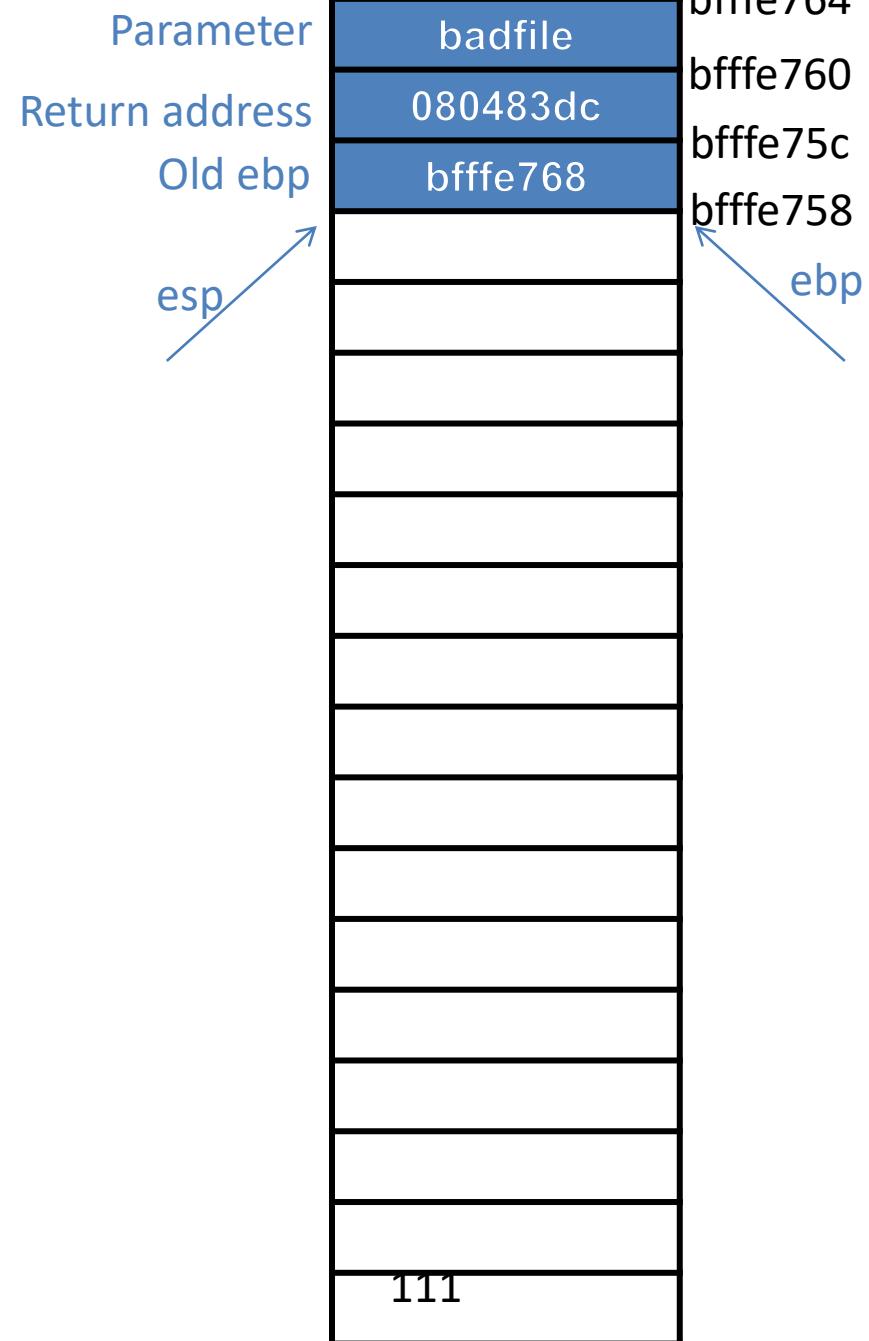


foo:

```
pushl  %ebp
movl %esp, %ebp
subl $40, %esp
...
movl 8(%ebp), %edx
movl %edx, 12(%esp)
movl $517, 8(%esp)
movl $1, 4(%esp)
movl %eax, (%esp)
call fread
movl $1, %eax
leave
ret
```

main:

```
...
movl %eax, (%esp)
call foo
...
$1, %eax
leave
ret
```

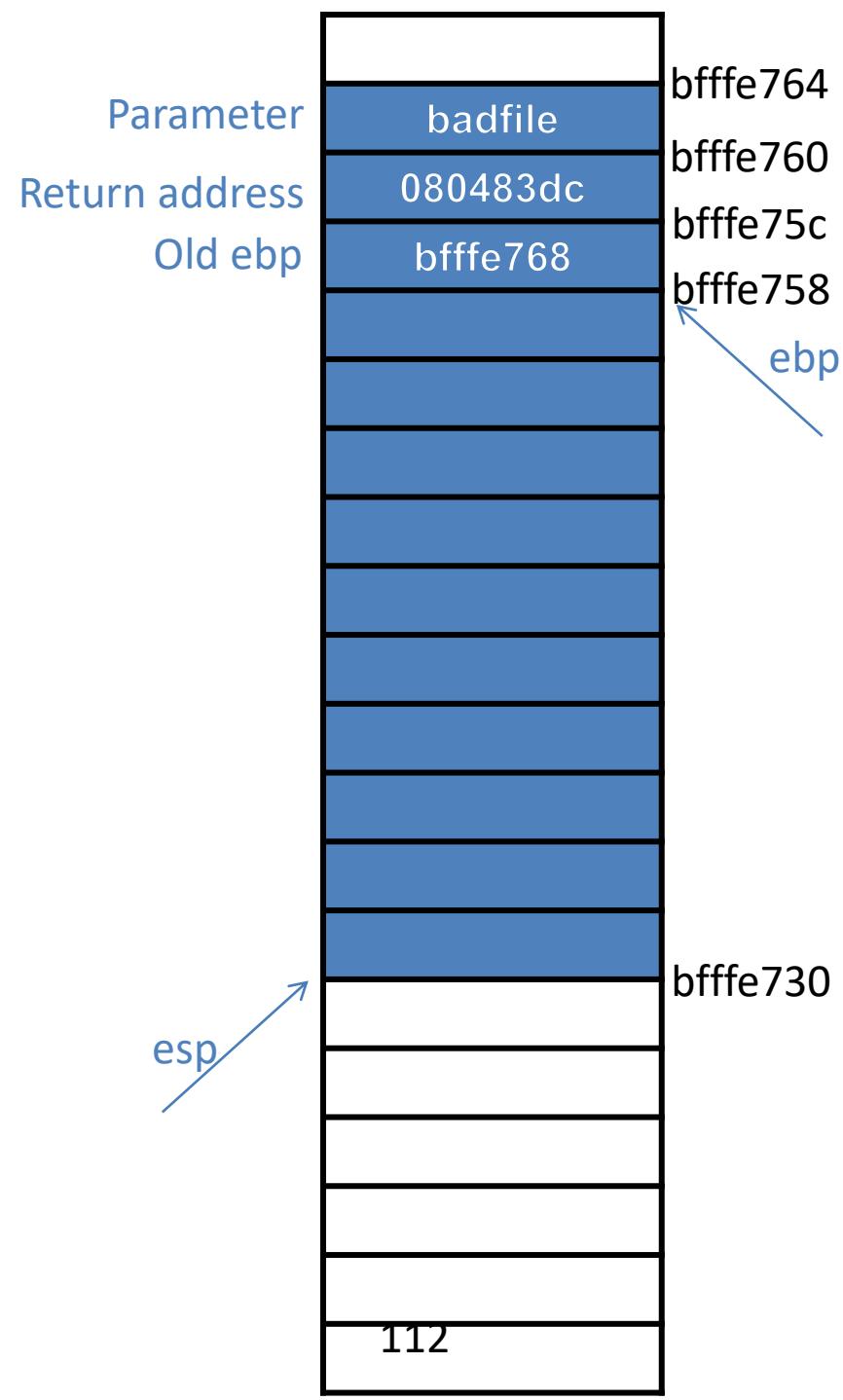


foo:

```
pushl    %ebp
movl %esp, %ebp
subl $40, %esp
...
movl 8(%ebp), %edx
movl %edx, 12(%esp)
movl $517, 8(%esp)
movl $1, 4(%esp)
movl %eax, (%esp)
call fread
movl $1, %eax
leave
ret
```

main:

```
...  
movl %eax, (%esp)  
call foo  
  
...  
$1, %eax  
leave  
ret
```



foo:

```
pushl    %ebp
movl %esp, %ebp
subl $40, %esp
...
movl 8(%ebp), %edx
movl %edx, 12(%esp)
```

movl \$517, 8(%esp)

movl \$1, 4(%esp)

movl %eax, (%esp)

call fread

movl \$1, %eax

leave

ret

main:

• • •

movl %eax, (%esp)

call foo

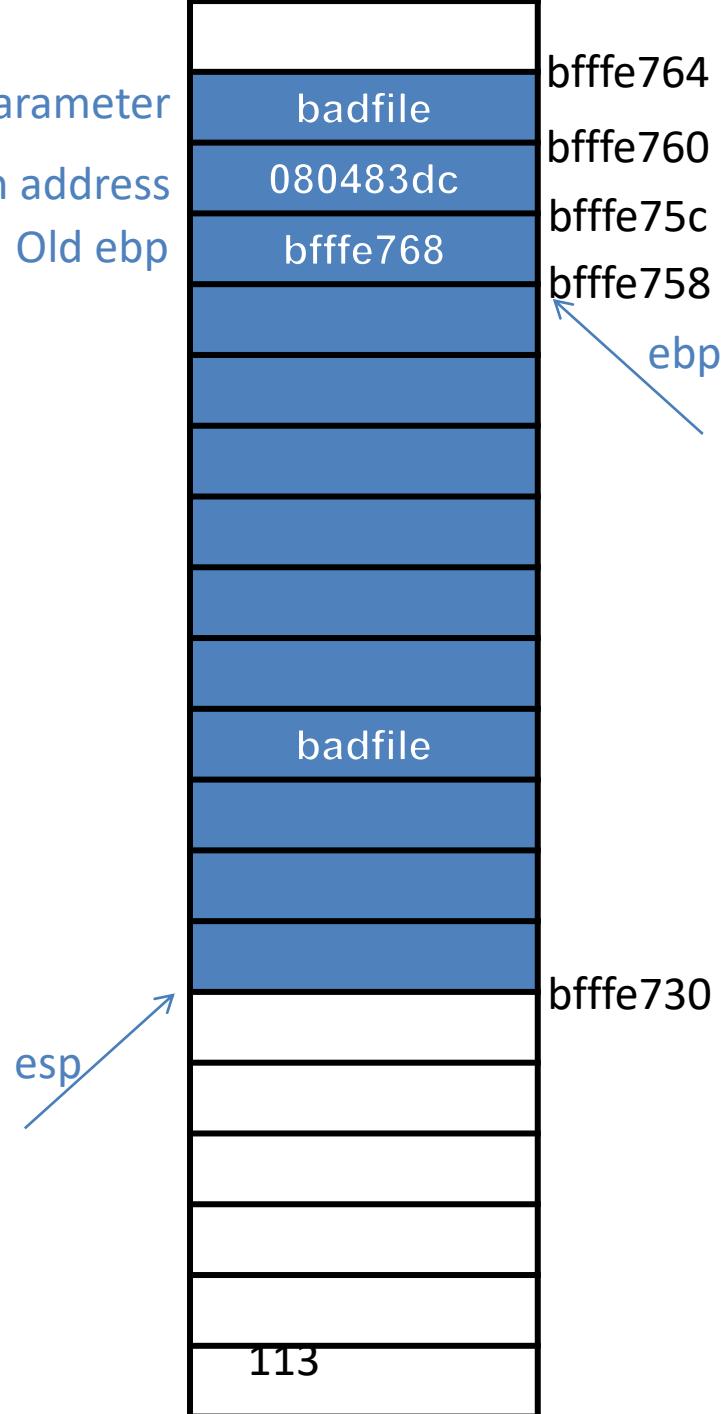
• • •

\$1, %eax

leave

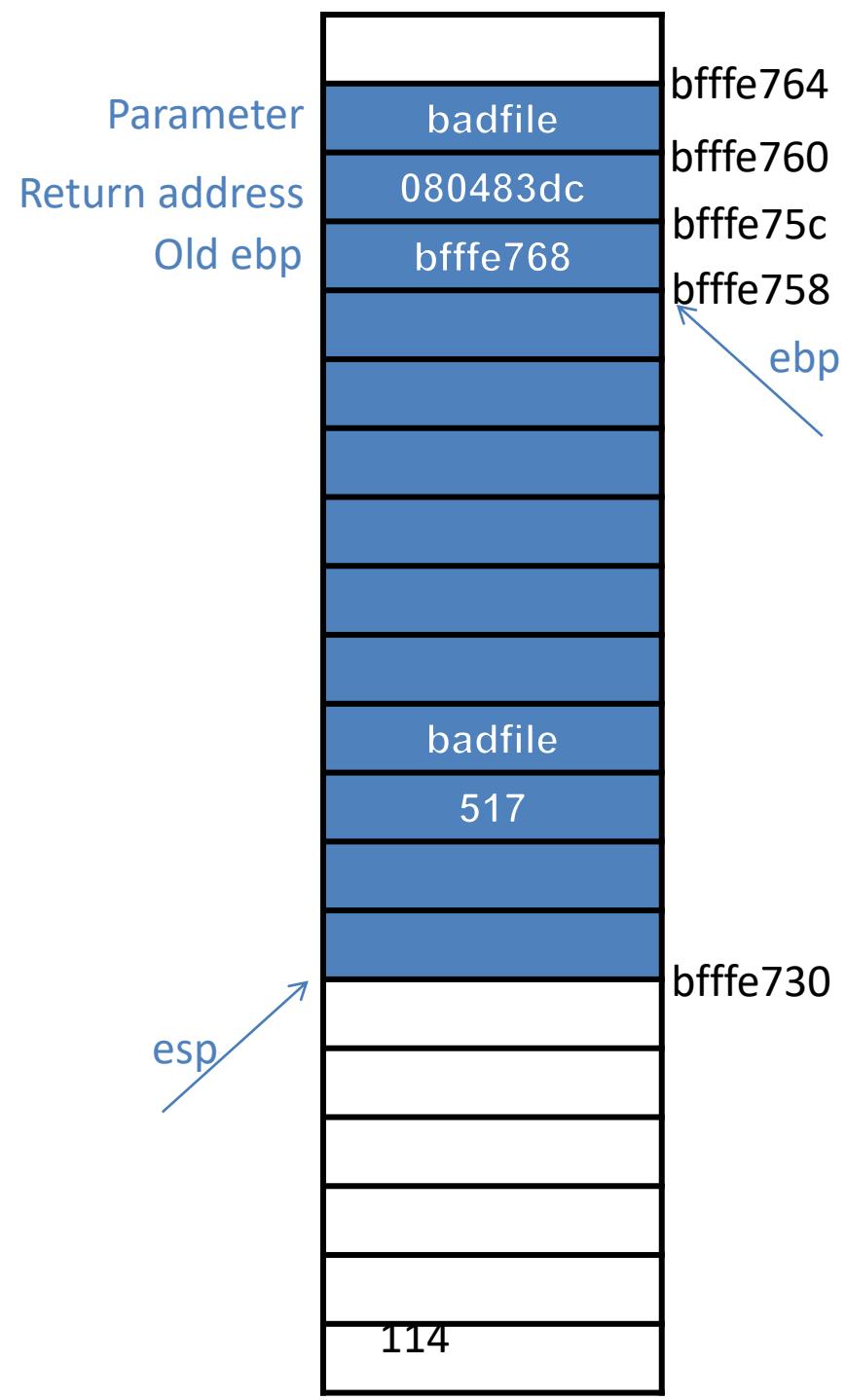
ret.

Parameter
Return address
Old ebp



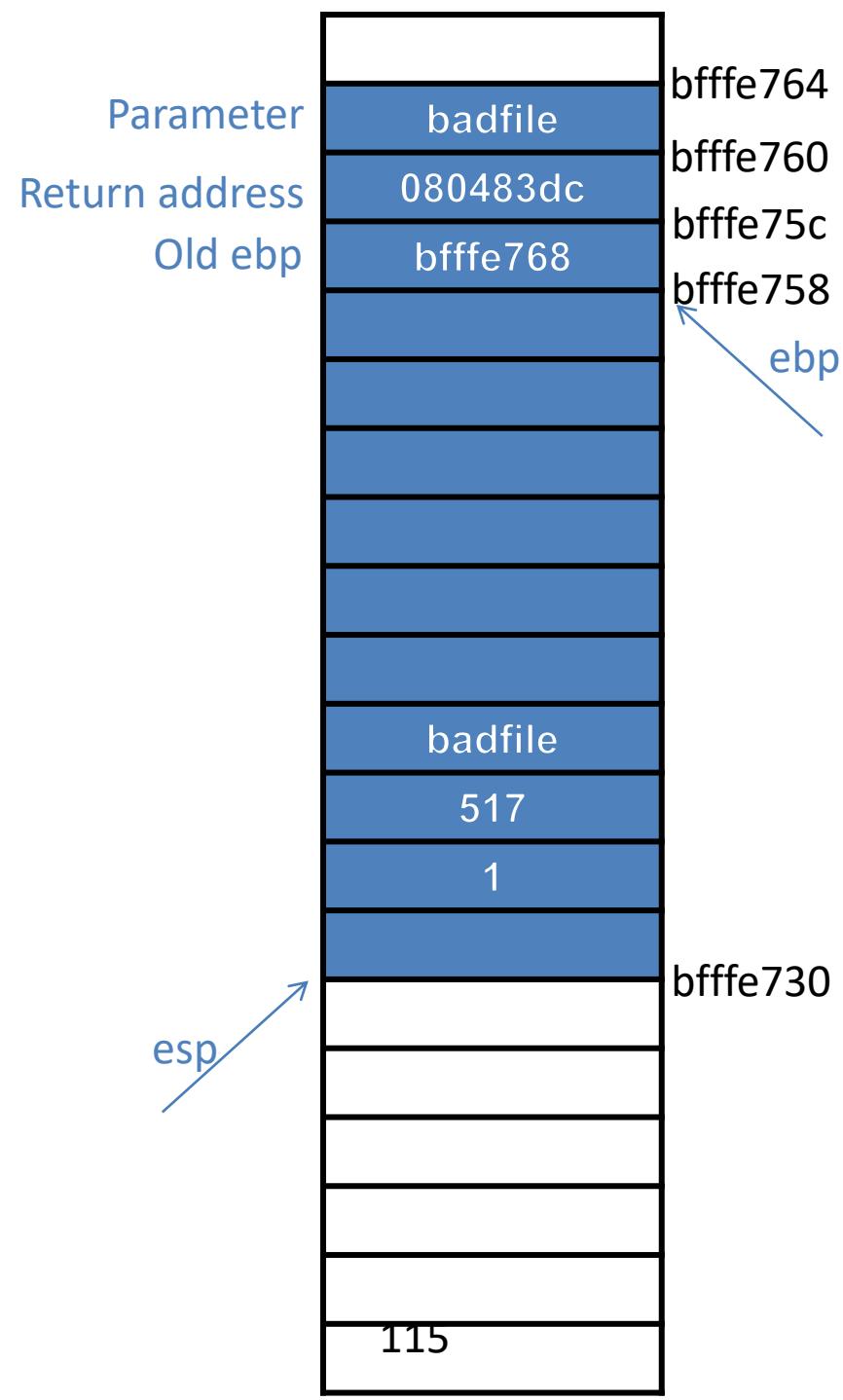
foo

```
pushl    %ebp
movl %esp, %ebp
subl $40, %esp
...
movl 8(%ebp), %edx
movl %edx, 12(%esp)
movl $517, 8(%esp)
movl $1, 4(%esp)
movl %eax, (%esp)
call fread
movl $1, %eax
leave
ret
l:
...
movl %eax, (%esp)
call foo
...
$1, %eax
leave
ret
```



foo:

```
pushl    %ebp
movl %esp, %ebp
subl $40, %esp
...
movl 8(%ebp), %edx
movl %edx, 12(%esp)
movl $517, 8(%esp)
movl $1, 4(%esp)
movl %eax, (%esp)
call fread
movl $1, %eax
leave
ret
1:
...
movl %eax, (%esp)
call foo
...
$1, %eax
leave
ret
```

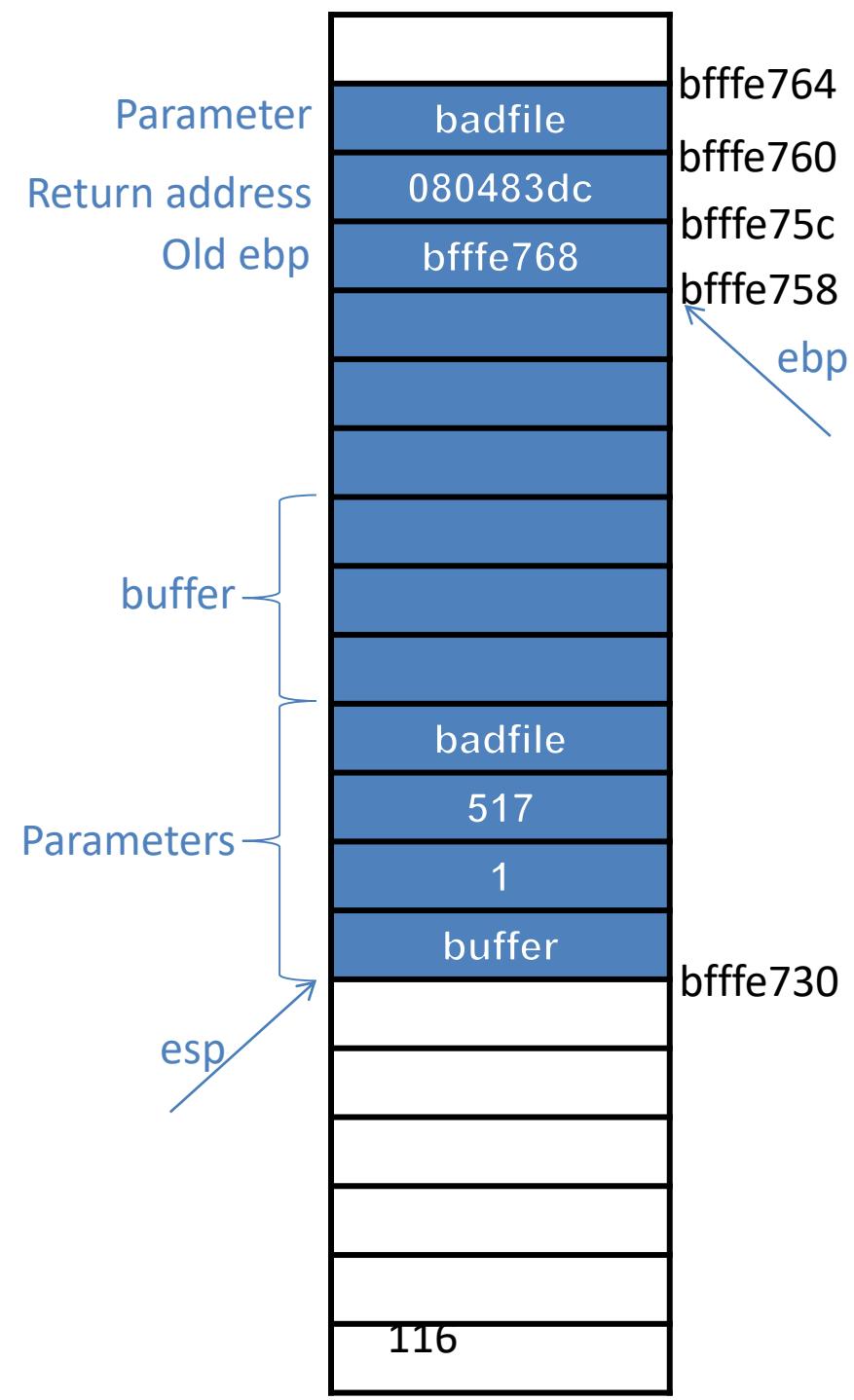


```

foo:
    pushl    %ebp
    movl %esp, %ebp
    subl $40, %esp
    ...
    movl 8(%ebp), %edx
    movl %edx, 12(%esp)
    movl $517, 8(%esp)
    movl $1, 4(%esp)
    movl %eax, (%esp)
    call fread
    movl $1, %eax
    leave
    ret

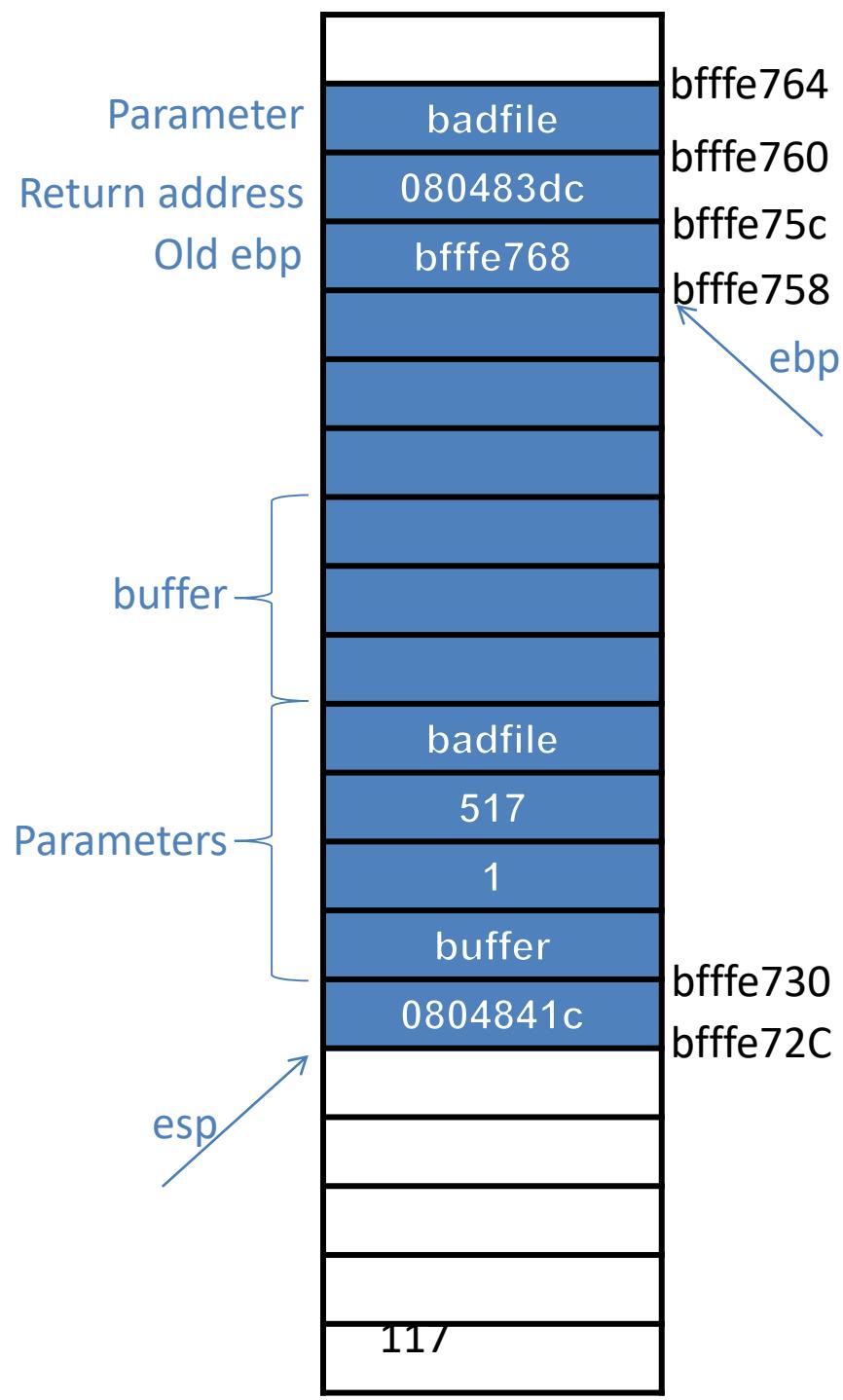
main:
    ...
    movl %eax, (%esp)
    call foo
    ...
    $1, %eax
    leave
    ret

```



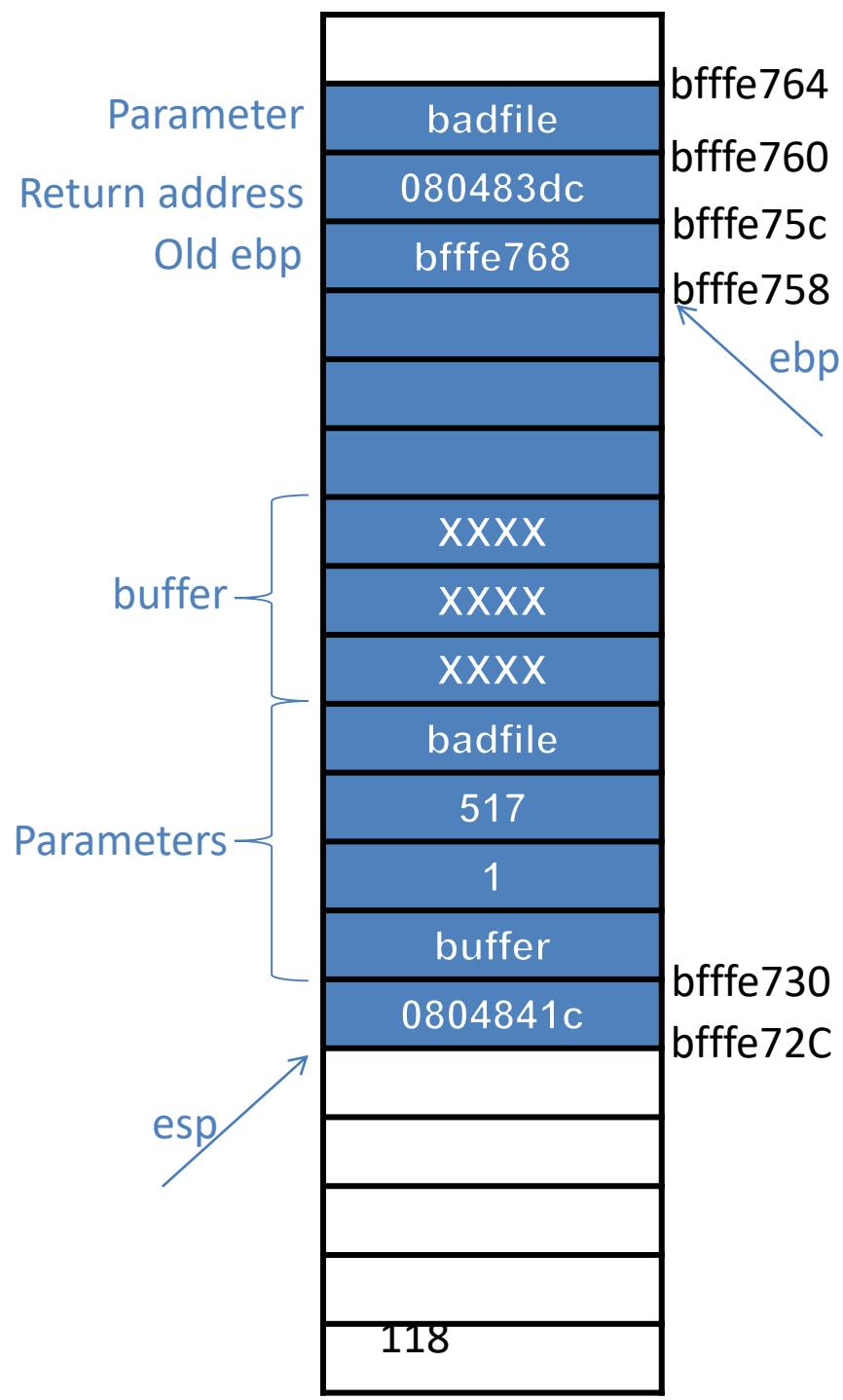
foo:

```
pushl    %ebp
movl %esp, %ebp
subl $40, %esp
...
movl 8(%ebp), %edx
movl %edx, 12(%esp)
movl $517, 8(%esp)
movl $1, 4(%esp)
movl %eax, (%esp)
call fread
movl $1, %eax
leave
ret
l:
...
movl %eax, (%esp)
call foo
...
$1, %eax
leave
ret
```



foo:

```
pushl    %ebp
movl %esp, %ebp
subl $40, %esp
...
movl 8(%ebp), %edx
movl %edx, 12(%esp)
movl $517, 8(%esp)
movl $1, 4(%esp)
movl %eax, (%esp)
call fread
movl $1, %eax
leave
ret
l:
...
movl %eax, (%esp)
call foo
...
$1, %eax
leave
ret
```



foo:

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pushl  %ebp
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movl $1, 4(%esp)
movl %eax, (%esp)
call fread
movl $1, %eax
leave
ret
```

main:

```
...
movl %eax, (%esp)
call foo
...
$1, %eax
leave
ret
```

